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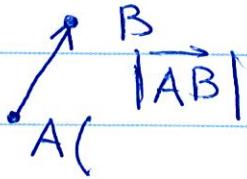
## §12.2 Vectors

magnitude : mass, length, time

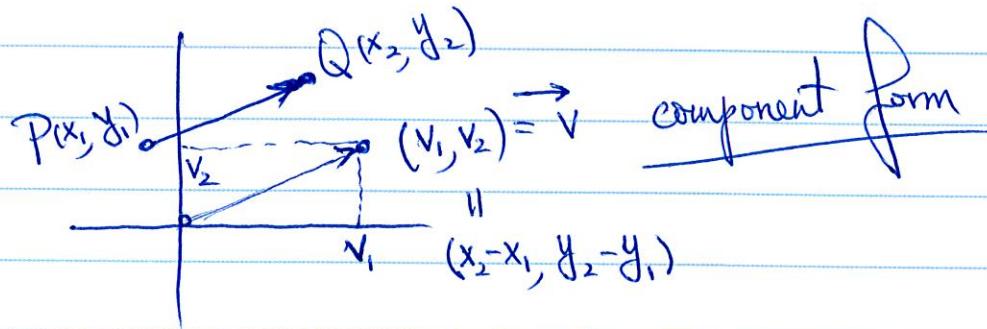
magnitude & direction : force, displacement, ... vector

component form

vector  $\Leftrightarrow$  directed line segment  $\vec{AB}$



$\vec{v}_1 = \vec{v}_2 \Leftrightarrow |\vec{v}_1| = |\vec{v}_2|$  and in the same direction



$\vec{PQ}$  has the same direction and length as  $\vec{v}$

$$\Rightarrow \begin{cases} x_2 = x_1 + v_1 \\ y_2 = y_1 + v_2 \end{cases} \Rightarrow (v_1, v_2) = (x_2 - x_1, y_2 - y_1)$$

magnitude  $|\vec{v}| = \sqrt{v_1^2 + v_2^2}$

(2)

## Vector Algebra Operations

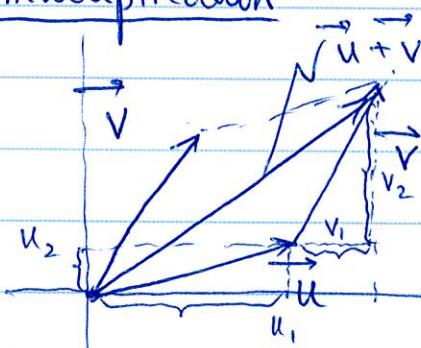
$$\vec{u} = (u_1, u_2, u_3), \vec{v} = (v_1, v_2, v_3)$$

addition

$$\vec{u} + \vec{v}$$

scalar multiplication

$$k\vec{u}$$

difference

$$\vec{u} - \vec{v} = \vec{u} + (-\vec{v})$$

$$\begin{aligned} \vec{v} &= \vec{u} - \vec{u} \\ \vec{u} &= \vec{v} + (\vec{u} - \vec{v}) \end{aligned}$$

Properties

$$\vec{u} + \vec{v} = \vec{v} + \vec{u}$$

$$(\vec{u} + \vec{v}) + \vec{w} = \vec{u} + (\vec{v} + \vec{w})$$

$$\vec{u} + \vec{0} = \vec{u}$$

$$\vec{u} + (-\vec{u}) = \vec{0}$$

$$0 \cdot \vec{u} = \vec{0}$$

$$|\vec{u}| = \vec{u}$$

$$a(b\vec{u}) = (ab)\vec{u}$$

$$a(\vec{u} + \vec{v}) = a\vec{u} + a\vec{v}$$

$$(a+b)\vec{u} = a\vec{u} + b\vec{u}$$

Unit Vector

$$\vec{i} = (1, 0, 0), \quad \vec{j} = (0, 1, 0), \quad \vec{k} = (0, 0, 1)$$

$$\vec{v} = (v_1, v_2, v_3) = v_1 \vec{i} + v_2 \vec{j} + v_3 \vec{k}$$

the direction of  $\vec{v} \neq \vec{0}$ 

$$\frac{\vec{v}}{|\vec{v}|} \text{ unit vector}$$

3

$$\vec{v} \neq \vec{0}$$

direction  $\frac{\vec{V}}{|V|}$

$$\underline{\text{direction}} \quad |\vec{v}| \quad \left( \begin{matrix} \vec{v} \\ |\vec{v}| \end{matrix} \right)$$

## Midpt of a Line Segment

The diagram illustrates the vector addition of  $\vec{OP_1}$  and  $\vec{P_1M}$  to find  $\vec{OM}$ . A point M is located such that the vector  $\vec{OM}$  is the sum of  $\vec{OP_1}$  and  $\vec{P_1M}$ . The coordinates of M are given as  $M\left(\frac{x_1+x_2}{2}, \frac{y_1+y_2}{2}, \frac{z_1+z_2}{2}\right)$ .

$$\frac{1}{2} \left( \overrightarrow{P_1 P_2} \right) = \frac{1}{2} \left[ \overrightarrow{OP_2} - \overrightarrow{OP_1} \right]$$

$$\overrightarrow{OM} = \overrightarrow{OP_1} + \overrightarrow{P_1M}$$

## Applications

### Ex. 8

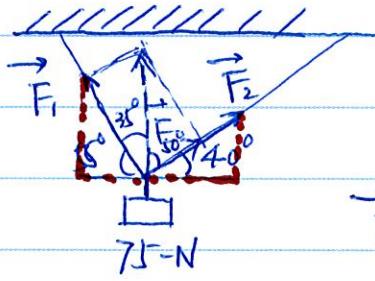
A vector diagram illustrating the relative velocity of an airplane. A horizontal dashed line represents the ground. A solid horizontal arrow labeled  $\vec{u}$  points to the right, labeled "velocity of air plane". A second solid horizontal arrow labeled  $\vec{v}$  points to the right, labeled "velocity of tailwind". A third solid horizontal arrow labeled  $\vec{u} + \vec{v}$  points to the right, labeled "velocity w.r.t. G". A vertical arrow labeled  $v_1$  points upwards. A hypotenuse labeled  $|\vec{v}| = 70$  degrees to the horizontal connects the origin to a point on the dashed line. The angle between  $v_1$  and the horizontal is also labeled 22°.

$$\vec{u} = (500, 0)$$

$$\text{Given } \vec{v} = (70 \cos 60^\circ, 70 \sin 60^\circ)$$

w.r.t. the ground

### Ex. 9



$$\text{Given } \vec{F} = \vec{F}_1 + \vec{F}_2 = (0, 75)$$

Find  $\vec{F}_1 = ?$ ,  $\vec{F}_2 = ?$

$$\vec{F}_1 = \left( -|\vec{F}_1| \cos 55^\circ, |\vec{F}_1| \sin 55^\circ \right), \vec{F}_2 = \left( |\vec{F}_2| \cos 40^\circ, |\vec{F}_2| \sin 40^\circ \right)$$

$$(0, 75) = \vec{F}_1 + \vec{F}_2 \Rightarrow |\vec{F}_1| \approx 57.67 N, |\vec{F}_2| \approx 43.18 N$$

(4)

### §12.3 The Dot Product

dot product  $\vec{u} = (u_1, u_2, u_3), \vec{v} = (v_1, v_2, v_3)$

$$\begin{aligned}\vec{u} \cdot \vec{v} &= u_1 v_1 + u_2 v_2 + u_3 v_3 \\ &= |\vec{u}| |\vec{v}| \cos \theta\end{aligned}$$

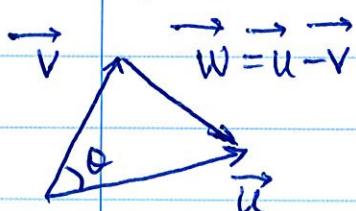
DefinitionThrm 1

Law of Cosine

$$|\vec{w}|^2 = |\vec{u}|^2 + |\vec{v}|^2 - 2 |\vec{u}| |\vec{v}| \cos \theta$$

|| ~ quadratic form

$$|\vec{u} - \vec{v}|^2 = |\vec{u}|^2 + |\vec{v}|^2 - 2 \boxed{\vec{u} \cdot \vec{v}}$$

Proof of Thrm 1Ex. 1 & 2 & 3

Orthogonal Vectors  $\vec{u} \perp \vec{v} \iff \vec{u} \cdot \vec{v} = 0$

Ex. 4

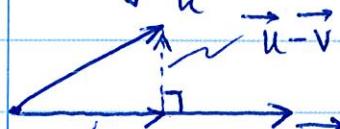
Properties

$$\begin{aligned}\vec{u} \cdot \vec{v} &= \vec{v} \cdot \vec{u} & (\vec{c}\vec{u}) \cdot \vec{v} &= \vec{u} \cdot (\vec{c}\vec{v}) = c(\vec{u} \cdot \vec{v}) \\ \vec{u} \cdot (\vec{v} + \vec{w}) &= \vec{u} \cdot \vec{v} + \vec{u} \cdot \vec{w}, & \vec{u} \cdot \vec{u} &= |\vec{u}|^2 \\ \vec{0} \cdot \vec{u} &= \vec{0}\end{aligned}$$

$$|\vec{u} \pm \vec{v}|^2 = |\vec{u}|^2 + |\vec{v}|^2 \pm 2 \vec{u} \cdot \vec{v}$$

5

Projection of  $\vec{u}$  onto  $\vec{v}$



$$\text{Proj}_{\vec{v}} \vec{u} = \alpha \vec{v}$$

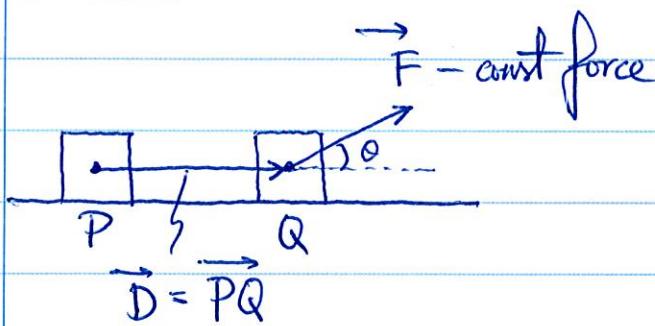
$$\vec{u} - \vec{v} \perp \vec{v} \quad \vec{u} = \vec{v} + \text{Proj}_{\vec{v}} \vec{u}$$

$$\text{Proj}_{\vec{v}} \vec{u} = \left( \vec{u} \cdot \frac{\vec{v}}{|\vec{v}|} \right) \frac{\vec{v}}{|\vec{v}|}$$

$$\begin{aligned} 0 &= (\vec{u} - \vec{v}) \cdot \alpha \vec{v} \\ \alpha &= (\vec{u} \cdot \vec{v}) / |\vec{v}|^2 \end{aligned}$$

Ex. 5 & 6

Work



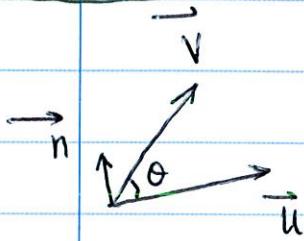
$\vec{F}$  - const force  
The work done by a const force  $\vec{F}$  acting through a displacement  $\vec{D}$

$$W = \vec{F} \cdot \vec{D}$$

Ex. 7

(6)

## §12.4 The Cross Product



Def

$$\vec{u} \times \vec{v} = \left( |\vec{u}| |\vec{v}| \sin \theta \right) \vec{n}$$

$\vec{n}$  - unit vector  $\perp \vec{u}$  and  $\vec{v}$

### Properties

$$(1) \vec{u} \parallel \vec{v} \Rightarrow \vec{u} \times \vec{v} = \vec{0}$$

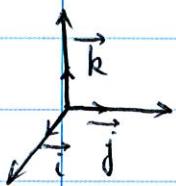
$$(2) (r\vec{u}) \times (s\vec{v}) = (rs) (\vec{u} \times \vec{v}), \quad (3) \vec{u} \times (\vec{v} + \vec{w}) = \vec{u} \times \vec{v} + \vec{u} \times \vec{w}$$

$$(4) \vec{v} \times \vec{u} = -(\vec{u} \times \vec{v}),$$

$$(4) (\vec{v} + \vec{w}) \times \vec{u} = \vec{v} \times \vec{u} + \vec{w} \times \vec{u}$$

$$(5) \vec{0} \times \vec{u} = \vec{0},$$

$$(6) \vec{u} \times (\vec{v} \times \vec{w}) = (\vec{u} \cdot \vec{w}) \vec{v} - (\vec{u} \cdot \vec{v}) \vec{w}$$

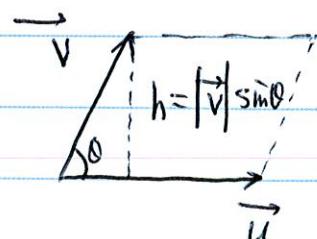
Ex.

$$\vec{i} \times \vec{j} = \vec{k} = -(\vec{j} \times \vec{i})$$

$$\vec{j} \times \vec{k} = \vec{i} = -(\vec{k} \times \vec{j})$$

$$\vec{k} \times \vec{i} = \vec{j} = -(\vec{i} \times \vec{k})$$

$$(7) \begin{aligned} |\vec{u} \times \vec{v}| &= \text{area of a parallelogram} \\ &= \left( |\vec{v}| \sin \theta \right) |\vec{u}| \end{aligned}$$



(7)

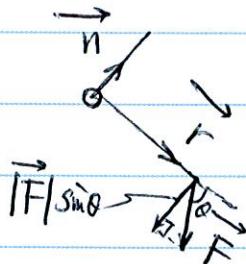
## Determinant Formula for $\vec{u} \times \vec{v}$

$$\vec{u} = u_1 \vec{i} + u_2 \vec{j} + u_3 \vec{k}, \quad \vec{v} = v_1 \vec{i} + v_2 \vec{j} + v_3 \vec{k}$$

$$\begin{aligned}\vec{u} \times \vec{v} &= (\vec{u}_1 \vec{i} + \vec{u}_2 \vec{j} + \vec{u}_3 \vec{k}) \times (\vec{v}_1 \vec{i} + \vec{v}_2 \vec{j} + \vec{v}_3 \vec{k}) \\ &= (u_2 v_3 - u_3 v_2) \vec{i} - (u_1 v_3 - u_3 v_1) \vec{j} + (u_1 v_2 - u_2 v_1) \vec{k} \\ &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix}\end{aligned}$$

Ex. 1, 2, 3, 4

Torque



$$\text{Torque vector} = (|\vec{r}| |\vec{F}| \sin \theta) \hat{n} = \vec{r} \times \vec{F}$$

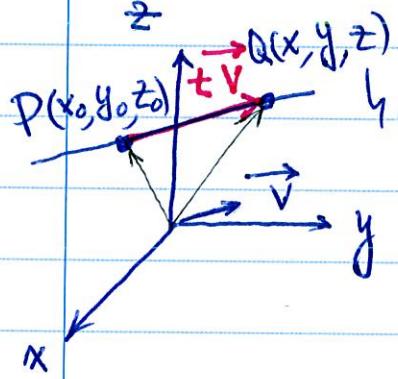
Triple Scalar

$$\vec{u} \cdot \vec{v} \cdot \vec{w} = \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

(8)

## §12.5 Lines and Planes in Space

### Equation for a Line



Given

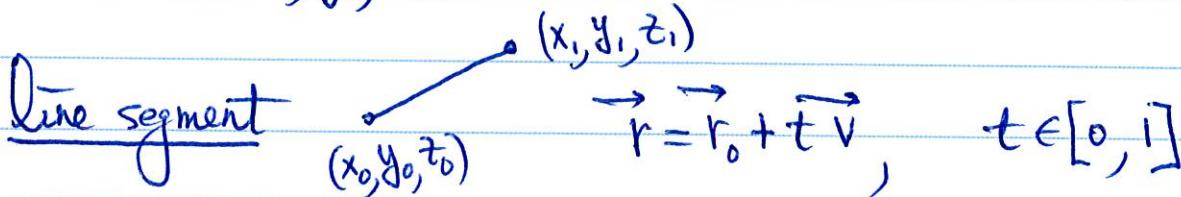
 $(x_0, y_0, z_0)$  on Lvector  $\vec{v} \parallel L \sim$  line

arbitrary pt on L Find equation of L

$$L: (x, y, z) = (x_0, y_0, z_0) + t\vec{v}$$

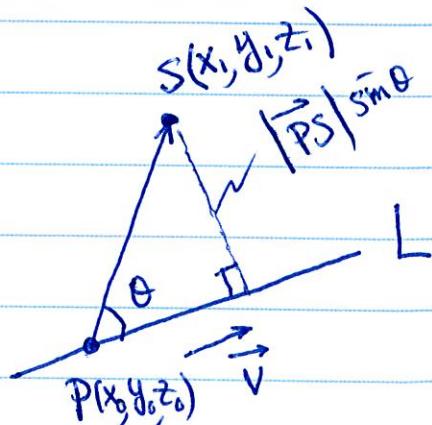
$$\begin{cases} x = x_0 + t v_1 \\ y = y_0 + t v_2 \\ z = z_0 + t v_3 \end{cases} \quad \text{parametric equation}$$

- Given  $(x_0, y_0, z_0)$  2 pts on L  $\Rightarrow \vec{v} = (x_1 - x_0, y_1 - y_0, z_1 - z_0)$

Ex. 1, 2, 3, 4

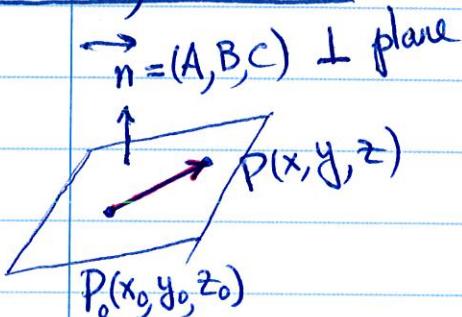
### Distance from a pt to a line

$$d = \frac{|\vec{PS} \times \vec{v}|}{|\vec{v}|} = |\vec{PS}| \sin \theta$$

Ex. 5

(9)

## Equation for a Plane



Given pt  $P_0 = (x_0, y_0, z_0)$

vector  $\vec{n} \perp$  plane

$$0 = \vec{n} \cdot \vec{P_0 P}$$

$$= A(x - x_0) + B(y - y_0) + C(z - z_0)$$

$$\Leftrightarrow Ax + By + Cz = D$$

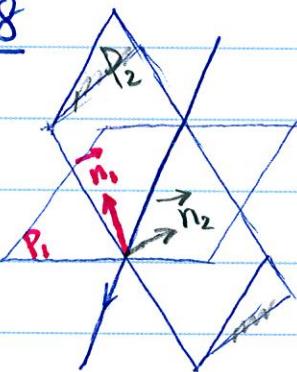
Ex. 6, 7

## Lines of Intersection

$$\text{plane } P_1 \parallel \text{plane } P_2 \Leftrightarrow \vec{n}_1 \parallel \vec{n}_2 \Leftrightarrow \vec{n}_1 = k\vec{n}_2$$

$k \in \mathbb{R}$

Ex. 8



Find a vector  $\parallel$  the line of intersection of 2 planes

$$\begin{aligned} & \vec{n}_1 \times \vec{n}_2 \\ &= (14, 2, 15) \end{aligned}$$

$$P_1: 3x - 6y - 2z = 15$$

$$P_2: 2x + y - 2z = 5$$

Ex. 9 Find the parametric eq. of the line of intersection of 2 planes.

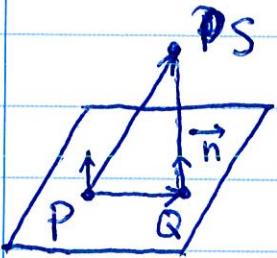
vector  $\vec{n}_1 \times \vec{n}_2 = (14, 2, 15)$

pt.  $z = 0 \Rightarrow \begin{cases} 3x - 6y = 15 \\ 2x + y = 5 \end{cases} \Rightarrow (3, -1, 0)$

$$\Rightarrow (x, y, z) = (3, -1, 0) + t(14, 2, 15)$$

(10)

## Distance from a pt to a plane



$$\begin{aligned}
 d &= |\vec{QS}| = \left| \text{Proj}_{\vec{n}} \vec{PS} \right| \\
 &= \left| \left( \vec{PS} \cdot \frac{\vec{n}}{|\vec{n}|} \right) \frac{\vec{n}}{|\vec{n}|} \right| = \text{abs} \left( \frac{\vec{PS} \cdot \vec{n}}{|\vec{n}|} \right) \\
 d &= \text{abs} \left( \frac{\vec{PS} \cdot \vec{n}}{|\vec{n}|} \right)
 \end{aligned}$$

Ex. 11

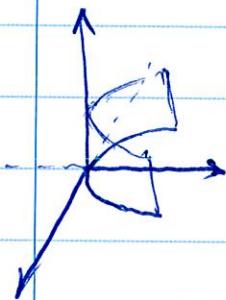
Angle between Planes = angle between their normals.

Ex. 12

## §12.6 Cylinders and Quadric Surfaces

### Cylinders

2d curve  $f(x, y) = c$  defines a 3d cylinder parallel to z-axis.



### Quadric Surface

$$Ax^2 + By^2 + Cz^2 + Dx + Ey + Fz = G$$

Focus on  $Ax^2 + By^2 + Cz^2 + Dz = E$ .

### basic quadric surfaces

ellipsoid  $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$

hyperbolic paraboloid  $\frac{y^2}{b^2} - \frac{x^2}{a^2} = \frac{z^2}{c^2}$  with  $c > 0$

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TABLE 12.1 Graphs of Quadric Surfaces

