

### 3.6 FORCED OSCILLATIONS AND RESONANCE

On Section 3.4, we analyzed the eq.

$$mx'' + cx' + Kx = 0$$

and found the following types of solutions:

1)  $c=0$  (undamped)  $x(t) = C \cdot \cos(\omega_0 t - \alpha)$ , where  $\omega_0 = \sqrt{\frac{K}{m}}$

2)  $c^2 > 4mk$  (overdamped)  $x(t) = Ae^{-r_1 t} + Be^{-r_2 t}$

3)  $c^2 = 4mk$  (critical damping)  $x(t) = (A+Bt)e^{-pt}$  where  $p = c/2m$

4)  $c^2 < 4mk$  (underdamped)  $x(t) = C \cdot \cos(\omega_1 t - \alpha) \cdot e^{-pt}$  where  $\omega_1 = \sqrt{\omega_0^2 - p^2}$

Today:  $mx'' + cx' + Kx = F_0 \cos \omega t$

GOAL: analyse the possible types of solutions as we change  $\omega$ .

**CASE 1:** undamped,  $\omega \neq \omega_0$

$$m x'' + kx = F_0 \cos \omega t$$

Can use undetermined coefficients to get

$$x(t) = A \cos \omega_0 t + B \sin \omega_0 t + \frac{F_0/m}{\omega_0^2 - \omega^2} \cos \omega t$$

$$= C \cdot \cos(\omega_0 t - \alpha) + \frac{F_0/m}{\omega_0^2 - \omega^2} \cos \omega t$$

What does it look like? Periodic, with higher frequency oscillations within each period.

**Special case: BEATS**

Happen when  $x(0) = x'(0) = 0$

$$x(t) = \frac{F_0}{m(\omega_0^2 - \omega^2)} (\cos \omega t - \cos \omega_0 t)$$

Trick: let's use  $\cos(a-b) - \cos(a+b) = 2 \sin a \sin b$ , choosing  $a$  and  $b$  so that  
 $a-b = \omega$ ,  $a+b = \omega_0$

$$\text{Then } x(t) = \frac{F_0}{m(\omega_0^2 - \omega^2)} \sin \frac{\omega_0 - \omega}{2} \sin \frac{\omega_0 + \omega}{2} \quad (\text{look at some graphs!})$$

**CASE 2:** undamped,  $\omega = \omega_0$  (RESONANCE)

$$mx'' + kx = F_0 \cos \omega_0 t$$

Use undetermined coefficients, guess  $x(t) = t(A \cos \omega_0 t + B \sin \omega_0 t)$

$$x(t) = A \cos \omega_0 t + B \sin \omega_0 t + \frac{F_0}{2m\omega_0} t \sin \omega_0 t$$

**CASE 3:** damped

$$mx'' + cx' + kx = F_0 \cos \omega t$$

$x(t) = x_h(t) + x_p(t)$ , where  $x_h$  is a solution to  $mx'' + cx' + kx = 0$  (transient solution)

$x_p$  is a particular solution (steady solution)

Whatever  $x_h$  may be, it's always the case that  $\lim_{t \rightarrow \infty} x_h(t) = 0$ .

$x_p$  has the form  $x_p(t) = C \cdot \cos(\omega t - \alpha)$ .