

5.1 LINEAR INDEPENDENCE OF VECTOR-VALUED FUNCTIONS

RECALL for $y'' + p(t)y' + q(t)y = 0$ the general solution has the form $y(t) = Ay_1(t) + By_2(t)$, where y_1 and y_2 are LI solutions (not multiples of each other)

For example, $y'' + 2y' + y = 0$ has general solution $y(t) = Ae^{-t} + Bte^{-t}$.

REMARK the function $2t$ is a multiple of the function t , but the function t^2 is not. In other words, $\{t, 2t\}$ is LD and $\{t, t^2\}$ is LI.

TODAY general solutions of SYSTEMS of linear equations

EXAMPLE $y'' + 2y' + y = 0$ can be recast as a system. Let $x_1 := y$, $x_2 := y'$

$$\begin{cases} x_1' = x_2 \\ x_2' = -2x_2 - x_1 \end{cases} \quad \text{general solution: } \begin{aligned} x_1(t) &= (A + Bt)e^{-t} \\ x_2(t) &= (-A + B - Bt)e^{-t} \end{aligned}$$

In matrix form: let $\mathbb{x}(t) := \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$, then $\mathbb{x}'(t) = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix} \mathbb{x}(t)$.

$$\text{General solution: } \mathbb{x}(t) = A \begin{bmatrix} e^{-t} \\ -e^{-t} \end{bmatrix} + B \begin{bmatrix} te^{-t} \\ (1-t)e^{-t} \end{bmatrix}.$$

Compare $y(t) = Ae^{-t} + Bte^{-t}$

2nd order equation, two LI solutions

$$\mathbf{x}(t) = A \begin{bmatrix} e^t \\ -e^{-t} \end{bmatrix} + B \begin{bmatrix} te^{-t} \\ (1-t)e^{-t} \end{bmatrix}$$

1st order SYSTEM of two equations, two LI solutions

FACT Let P be an $n \times n$ matrix. Consider the system $\mathbf{x}' = P\mathbf{x}$. Its general solution has the form

$$\mathbf{x}(t) = C_1 \mathbf{x}_1(t) + \dots + C_n \mathbf{x}_n(t), \text{ where } \mathbf{x}_1(t), \dots, \mathbf{x}_n(t) \text{ are LI solutions.}$$

RECALL a set of functions y_1, \dots, y_n is **linearly independent** if none of them is a linear combination of the others. The same definition applies to vector-valued functions.

LI	LD
$\{e^t, e^{2t}, e^{3t}\}$	$\{e^t, 2e^t, e^{3t}\}$
$\{\cos x, \sin x, \sin 2x\}$	$\{\cos x, \sin x, \cos x - \sin x\}$
$\{e^t, te^t, t^2e^t\}$	$\{te^t, te^t, t^2e^t\}$
$\left\{ \begin{bmatrix} e^{2t} \\ 2e^{2t} \end{bmatrix}, \begin{bmatrix} e^{2t} \\ 3e^{2t} \end{bmatrix} \right\}$	$\left\{ \begin{bmatrix} e^{2t} \\ 2e^{2t} \end{bmatrix}, \begin{bmatrix} 2e^{2t} \\ 4e^{2t} \end{bmatrix} \right\}$

HOW DO WE TELL IF A GIVEN SET OF SOLUTIONS IS LI?

THEOREM: Consider a linear system of differential equations $x' = P(t)x$, with n equations.

Let $x_1(t), \dots, x_n(t)$ be solutions of $x' = P(t)x$. Then $x_1(t), \dots, x_n(t)$ are LI if and only

$$\begin{vmatrix} x_1(t) & x_2(t) & \cdots & x_n(t) \end{vmatrix} \neq 0. \quad (\text{Wronskian determinant } W(t))$$

$n \times n$ matrix with
columns x_1, \dots, x_n

EXAMPLES

1) $x'(t) = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix} x(t)$. Two solutions: $\begin{bmatrix} e^{-t} \\ -e^{-t} \end{bmatrix}$ and $\begin{bmatrix} te^{-t} \\ (1-t)e^{-t} \end{bmatrix}$.

$$\begin{vmatrix} e^{-t} & te^{-t} \\ -e^{-t} & (1-t)e^{-t} \end{vmatrix} = e^{-2t} \begin{vmatrix} 1 & t \\ -1 & 1-t \end{vmatrix} = e^{-2t} [1-t - (-t)] = e^{-2t} \neq 0$$

$$\begin{aligned} & \parallel \\ e^{-t} & \begin{vmatrix} 1 & te^{-t} \\ -1 & (1-t)e^{-t} \end{vmatrix} = e^{-2t} (1-t - (-t)) \\ & \parallel \\ & = e^{-2t} \end{aligned}$$

$$\begin{aligned} & \parallel \\ e^{-t} & \begin{vmatrix} 1 & t \\ -1 & 1-t \end{vmatrix} \end{aligned}$$

$$2) \quad \mathbb{x}' = \begin{bmatrix} 3 & -2 & 0 \\ -1 & 3 & -2 \\ 0 & -1 & 3 \end{bmatrix} \mathbb{x}$$

Check that these are LI solutions:

$$\mathbb{x}_1(t) = e^t \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \quad \mathbb{x}_2(t) = e^{3t} \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} \quad \mathbb{x}_3(t) = e^{5t} \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix}$$

Let P be the matrix in the equation.

Check that $\mathbb{x}_1(t)$ is a solution:

$$\mathbb{x}_1' \stackrel{?}{=} P \mathbb{x}_1$$

$$P \mathbb{x}_1(t) = \begin{bmatrix} 3 & -2 & 0 \\ -1 & 3 & -2 \\ 0 & -1 & 3 \end{bmatrix} \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} e^t$$

$$\mathbb{x}_1'(t) = e^t \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix}$$

$$= e^t \left\{ 2 \begin{bmatrix} 3 \\ -1 \\ 0 \end{bmatrix} + 2 \begin{bmatrix} -2 \\ 3 \\ -1 \end{bmatrix} + 1 \begin{bmatrix} 0 \\ -2 \\ 3 \end{bmatrix} \right\}$$

$$= e^t \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} = \mathbb{x}_1'(t)$$

Check that $\mathbb{x}_2(t)$ is a solution:

$$\mathbb{x}_2' \stackrel{?}{=} P \mathbb{x}_2$$

$$P \mathbb{x}_2(t) = \begin{bmatrix} 3 & -2 & 0 \\ -1 & 3 & -2 \\ 0 & -1 & 3 \end{bmatrix} \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} e^{3t}$$

$$\mathbb{x}_2'(t) = 3e^{3t} \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix} = e^{3t} \begin{bmatrix} -6 \\ 0 \\ 3 \end{bmatrix}$$

$$= e^{3t} \left\{ -2 \begin{bmatrix} 3 \\ -1 \\ 0 \end{bmatrix} + 1 \begin{bmatrix} 0 \\ -2 \\ 3 \end{bmatrix} \right\} = e^{3t} \begin{bmatrix} -6 \\ 0 \\ 3 \end{bmatrix}$$

Check that $x_3(t)$ is a solution:

$$x_3'(t) \stackrel{?}{=} P x_3(t)$$

$$x_3'(t) = 5 e^{5t} \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix} = e^{5t} \begin{bmatrix} 10 \\ -10 \\ 5 \end{bmatrix}$$

$$\begin{aligned} P x_3(t) &= \begin{bmatrix} 3 & -2 & 0 \\ -1 & 3 & -2 \\ 0 & -1 & 3 \end{bmatrix} \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix} e^{5t} \\ &= \left\{ 2 \begin{bmatrix} 3 \\ -1 \\ 0 \end{bmatrix} - 2 \begin{bmatrix} -2 \\ 3 \\ -1 \end{bmatrix} + 1 \begin{bmatrix} 0 \\ -2 \\ 3 \end{bmatrix} \right\} e^{5t} \\ &= \begin{bmatrix} 10 \\ -10 \\ 5 \end{bmatrix} e^{5t} \end{aligned}$$

Check that x_1, x_2, x_3 are LI:

$$0 \neq \det |x_1(t) \ x_2(t) \ x_3(t)| = e^t e^{3t} e^{5t} \begin{vmatrix} 2 & -2 & 2 \\ 2 & 0 & -2 \\ 1 & 1 & 1 \end{vmatrix}$$

$$= e^{9t} \left\{ -2 \begin{vmatrix} -2 & 2 \\ 1 & 1 \end{vmatrix} - (-2) \begin{vmatrix} 2 & -2 \\ 1 & 1 \end{vmatrix} \right\}$$

$$= e^{9t} \{ -2(-4) - (-2)4 \} = 16 e^{9t}$$

The Wronskian is never zero, so the solutions x_1, x_2, x_3 are LI.

General solution of $x' = Px$: $x(t) = A x_1(t) + B x_2(t) + C x_3(t)$.