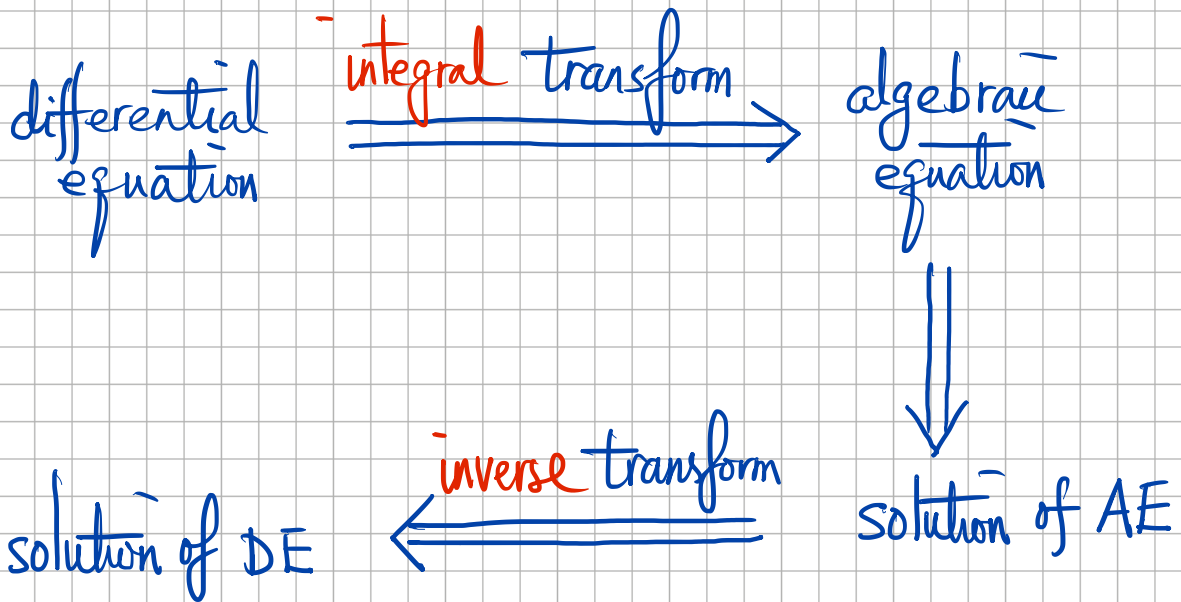


Chapter 7 Laplace Transform Methods



§7.1 Laplace Transforms and Inverse Transforms

• Laplace transform $F(s) = \mathcal{L}\{f(t)\} = \int_0^{\infty} e^{-st} f(t) dt$

• Review of Improper Integral

$$\int_a^{\infty} f(t) dt = \lim_{A \rightarrow \infty} \int_a^A f(t) dt \quad \begin{cases} \text{exists} & \text{convergence} \\ \text{DNE} & \text{divergence} \end{cases}$$

Examples

$$\begin{aligned} \text{1) } \mathcal{L}\{1\} &= \int_0^{\infty} e^{-st} \cdot 1 dt = \lim_{A \rightarrow \infty} \int_0^A e^{-st} dt = \lim_{A \rightarrow \infty} \left[\frac{1}{-s} e^{-st} \right]_0^A \\ &= \lim_{A \rightarrow \infty} \left(-\frac{1}{s} \right) \left[\underline{e^{-sA}} - 1 \right] = -\frac{1}{s} (-1) = \frac{1}{s} \end{aligned}$$

$(s > 0)$

$$(2) \mathcal{L}\{e^{at}\} = \int_0^{\infty} e^{-st} e^{at} dt = \int_0^{\infty} e^{(a-s)t} dt = \frac{1}{a-s} e^{(a-s)t} \Big|_0^{\infty}$$

$$= \frac{1}{a-s} [0 - 1] = \boxed{\frac{1}{s-a}} \quad \boxed{a-s < 0}$$

$$(3) \mathcal{L}\{t^a\} = \frac{\Gamma(a+1)}{s^{a+1}}, \quad \text{where the Gamma function } (x > 0)$$

$$\text{LHS} = \int_0^{\infty} e^{-st} t^a dt \stackrel{?}{=} \text{RHS} = \frac{1}{s^{a+1}} \int_0^{\infty} e^{-x} x^a dx$$

$$\int_0^{\infty} e^{-x} \left(\frac{x}{s}\right)^a \frac{dx}{s} \quad \begin{matrix} \boxed{x=st} \\ \boxed{dx=sdt} \end{matrix} =$$

$$\Gamma(x) = \int_0^{\infty} e^{-t} t^{x-1} dt$$

$$\Gamma(1) = 1, \quad \Gamma(x+1) = x \Gamma(x)$$

$$\Gamma(n+1) = n!$$

$$\mathcal{L}\{t^1\} = \frac{\Gamma(2)}{s^2} = \frac{1}{s^2}$$

$$\mathcal{L}\{t^n\} = \frac{n!}{s^{n+1}} \quad (s > 0)$$

• Linearity of Transforms

$$\mathcal{L}\{a f(t) + b g(t)\} = a \mathcal{L}\{f(t)\} + b \mathcal{L}\{g(t)\}$$

Examples

$$(4) \mathcal{L}\{3t^2 + 4t^{\frac{3}{2}}\} = 3 \mathcal{L}\{t^2\} + 4 \mathcal{L}\{t^{\frac{3}{2}}\}$$

$$= 3 \cdot \frac{2!}{s^3} + 4 \cdot \frac{\Gamma(\frac{3}{2}+1)}{s^{\frac{3}{2}+1}} = \frac{6}{s^3} + \frac{4 \Gamma(\frac{5}{2})}{s^{\frac{5}{2}}}$$

$$\begin{aligned}
 (5) \quad \mathcal{L}\{\cosh(kt)\} &= \mathcal{L}\left\{\frac{1}{2}(e^{kt} + e^{-kt})\right\} \\
 &= \frac{1}{2} \mathcal{L}\{e^{kt}\} + \frac{1}{2} \mathcal{L}\{e^{-kt}\} = \frac{1}{2} \frac{1}{s-k} + \frac{1}{2} \frac{1}{s-(-k)} \\
 &= \frac{1}{2} \left[\frac{1}{s-k} + \frac{1}{s+k} \right] = \frac{1}{2} \frac{(s+k) + (s-k)}{(s-k)(s+k)} = \frac{1}{2} \frac{2s}{s^2 - k^2}
 \end{aligned}$$

• Inverse Laplace Transforms

$$\mathcal{L}^{-1}\{F(s)\} = f(t) \text{ if } F(s) = \mathcal{L}\{f(t)\}$$

$f(t) = \mathcal{L}^{-1}\{F(s)\}$	$F(s) = \mathcal{L}\{f(t)\}$
$t^n \ (n \geq 0 \text{ integer})$	$\frac{n!}{s^{n+1}} \ (s > 0)$
$t^a \ (a > -1 \text{ real})$	$\frac{\Gamma(a+1)}{s^{a+1}} \ (s > 0)$
e^{at}	$\frac{1}{s-a} \ (s > a)$
$\cos(kt)$	$\frac{s}{s^2 + k^2} \ (s > 0)$
$\sin(kt)$	$\frac{k}{s^2 + k^2} \ (s > 0)$

$f(t)$	$F(s)$
$\cosh(kt)$	$\frac{s}{s^2 - k^2} \ (s > k)$
$\sinh(kt)$	$\frac{k}{s^2 - k^2} \ (s > k)$
$u(t-a)$	$\frac{1}{s} e^{-as} \ (s > 0)$

Examples

$$\mathcal{L}^{-1}\left\{\frac{1}{s^3}\right\} = \mathcal{L}^{-1}\left\{\frac{1}{2!} \cdot \frac{2!}{s^3}\right\} = \frac{1}{2} \mathcal{L}^{-1}\left\{\frac{2!}{s^3}\right\} = \frac{1}{2} t^2$$

$$\mathcal{L}^{-1}\left\{\frac{1}{s+2}\right\} = \mathcal{L}^{-1}\left\{\frac{1}{s-(-2)}\right\} = e^{-2t}$$

$$\mathcal{L}^{-1}\left\{\frac{5}{s^2+9}\right\} = \mathcal{L}^{-1}\left\{\frac{5}{s^2+3^2} \cdot \frac{3}{3}\right\} = \frac{5}{3} \sin(3t)$$

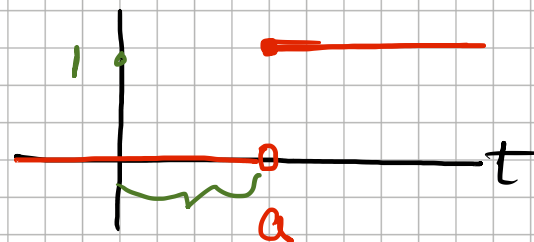
#28 $\mathcal{L}^{-1}\left\{\frac{3s+1}{s^2+4}\right\} = \mathcal{L}^{-1}\left\{\frac{3s}{s^2+2^2} + \frac{1}{s^2+2^2}\right\}$
 $= \mathcal{L}^{-1}\left\{\frac{s}{s^2+2^2}\right\} \cdot 3 + \mathcal{L}^{-1}\left\{\frac{2}{s^2+2^2} \cdot \frac{1}{2}\right\} = 3 \cdot \cos 2t + \frac{1}{2} \sin 2t$

• unit step function

$$u(t) = \begin{cases} 0 & \text{for } t < 0 \\ 1 & \text{for } t \geq 0 \end{cases}$$



$$u_a(t) = u(t-a) = \begin{cases} 0 & \text{for } t < a \\ 1 & \text{for } t \geq a \end{cases}$$



$$\mathcal{L}\{u_a(t)\} = \int_0^{\infty} e^{-st} u_a(t) dt = \int_0^a + \int_a^{\infty} e^{-st} \underline{u_a(t)} dt$$

$$= \int_a^{\infty} e^{-st} dt = \frac{1}{(-s)} e^{-st} \Big|_a^{\infty} = -\frac{1}{s} [0 - e^{-as}] \quad [s > 0]$$

$$\mathcal{L}\{f'(t)\} = \int_0^{\infty} \underbrace{e^{-st}}_u \underbrace{f'(t)}_{v'} dt \quad \begin{matrix} u' = -se^{-st} \\ v = f \end{matrix} \quad e^{-st} f(t) \Big|_0^{\infty} + s \int_0^{\infty} e^{-st} f(t) dt$$

$$\int t \sin t dt = -t \cos t + \int \cos t dt$$

$u = t, \quad v' = \sin t$
 $u' = 1, \quad v = -\cos t$

$$= -t \cos t + \sin t$$

$$\stackrel{(s > 0)}{=} [0 - f(0)] + s \int_0^{\infty} e^{-st} f(t) dt$$

$$= s \mathcal{L}\{f(t)\} - f(0)$$

$$= \mathcal{L}\{f'(t)\}$$

§7.2 Transformation of Initial Value Problems

IVP

$$\begin{cases} ax''(t) + bx'(t) + cx(t) = f(t) \\ x(0) = x_0, x'(0) = x'_0 \end{cases}$$

- L-transformation of derivatives

$$\mathcal{L}\{f^{(n)}(t)\} = s^n \mathcal{L}\{f(t)\} - s^{n-1}f(0) - s^{n-2}f'(0) - \dots - f^{(n-1)}(0)$$

IVP

$$a \mathcal{L}\{x''\} + b \mathcal{L}\{x'\} + c \mathcal{L}\{x\} = \mathcal{L}\{f\}$$

Example 1

$$\begin{cases} x'' - x' - 6x = 0 \\ x(0) = 2, x'(0) = -1 \end{cases}$$

Example 2

$$\begin{cases} x'' + 4x = \sin 3t \\ x(0) = x'(0) = 0 \end{cases}$$

• Linear System

Example 3

$$\begin{cases} 2x'' = -6x + 2y \\ y'' = 2x - 2y + 40 \sin 3t \\ x(0) = x'(0) = y(0) = y'(0) = 0 \end{cases}$$

- Transform Perspective

$$\begin{cases} m x'' + c x' + k x = f(t) \\ x(0) = x_0, \quad x'(0) = x'_0 \end{cases}$$

• additional transform techniques

Example 4 Show that $\mathcal{L}\{te^{at}\} = \frac{1}{(s-a)^2}$. (using $\mathcal{L}\{f'(t)\}$)

$$f(t) = te^{at}$$

$$\begin{aligned} f'(t) &= e^{at} + t \cdot a e^{at} \\ &= e^{at} + a(te^{at}) \\ &= e^{at} + a f(t) \end{aligned}$$

$$\mathcal{L}\{f'(t)\} = \mathcal{L}\{e^{at}\} + a \mathcal{L}\{f(t)\}$$

||

$$= \mathcal{L}\{f(t)\} - f(0)$$

$$(s-a) \mathcal{L}\{f(t)\} = \mathcal{L}\{e^{at}\} = \frac{1}{s-a}$$

$$f(0) = 0$$

Example 5 Find $\mathcal{L}\{t \sin kt\}$. (using $\mathcal{L}\{f''(t)\}$).

$$f(t) = t \sin kt$$

$$f'(t) = \sin kt + t \cdot k \cos kt$$

$$f'' = k \cos kt + k[\cos kt - k t \sin kt]$$

$$= 2k \cos kt - k^2 \underline{f(t)}$$

$$s^2 \mathcal{L}\{f(t)\} = \mathcal{L}\{f''\} = 2k \mathcal{L}\{\cos kt\} - k^2 \mathcal{L}\{f(t)\}$$

$$-s f(0) - f'(0)$$

$$\Rightarrow (s^2 + k^2) \mathcal{L}\{f(t)\} = 2k \frac{s}{s^2 + k^2}$$

- Transforms of Integrals

$$\mathcal{L}\left\{\int_0^t f(\tau) d\tau\right\} = \frac{F(s)}{s} \iff \mathcal{L}^{-1}\left\{\frac{F(s)}{s}\right\} = \int_0^t f(\tau) d\tau$$

Example 6 $\mathcal{L}^{-1}\left\{\frac{1}{s^2(s-a)}\right\} = ?$

§ 7.3 Translation and Partial Fractions

- Partial Fraction

$$R(s) = \frac{P(s)}{Q(s)}, \text{ where } P(s), Q(s) \text{ are polynomials } \deg P < \deg Q$$

$$\frac{P(s)}{(s-a)^n} = \frac{A_1}{s-a} + \frac{A_2}{(s-a)^2} + \dots + \frac{A_n}{(s-a)^n}$$

$$\frac{P(s)}{[(s-a)^2+b^2]^n} = \frac{A_1 s + B_1}{(s-a)^2+b^2} + \dots + \frac{A_n s + B_n}{[(s-a)^2+b^2]^n}$$

Translation

$$\mathcal{L}\{e^{at}f(t)\} = F(s-a) \iff \mathcal{L}^{-1}\{F(s-a)\} = e^{at}f(t)$$

Proof $F(s-a) = \int_0^{\infty} e^{-(s-a)t} f(t) dt$
 $= \int_0^{\infty} e^{-st} [e^{at} f(t)] dt$

#

$$(1) \mathcal{L}^{-1}\left\{\frac{n!}{(s-a)^{n+1}}\right\} = \underline{e^{at}} t^n$$

$$(2) \mathcal{L}^{-1}\left\{\frac{s-a}{(s-a)^2 + k^2}\right\} = e^{at} \cos kt$$

$$(3) \mathcal{L}^{-1}\left\{\frac{k}{(s-a)^2 + k^2}\right\} = e^{at} \sin kt$$

Examples

(1) Spring-mass system: $m x'' + c x' + k x = 0$ ($m = \frac{1}{2}, k = 17, c = 3$)
 $x(t) = ?$ $\begin{cases} x(0) = 3, x'(0) = 1 \end{cases}$

$$(ms^2 + cs + k) \mathcal{L}\{x(t)\} - [(ms + c) \cdot 3 + m \cdot 1] = 0$$

$$X(s) = \frac{3ms + (3c + m)}{ms^2 + cs + k}$$

$$= \frac{s^*}{s(s-4)(s+2)} + \frac{1}{s(s-4)(s+2)}$$

$$\frac{s^4+1}{s^3-2s^2-8s} = \frac{s^4+1}{s(s-4)(s+2)}$$

$$\frac{s^2+1}{s^3-2s^2-8s} = \frac{s^2+1}{s(s^2-2s-8)}$$

$$(3) \quad \mathcal{L}^{-1} \left\{ \frac{s^2+1}{s^3-2s^2-8s} \right\}$$

$$= \frac{s^2+1}{s(s-4)(s+2)} = \frac{A_1}{s} + \frac{A_2}{s-4} + \frac{A_3}{s+2}$$

$$= A_1 \mathcal{L}^{-1} \left\{ \frac{1}{s} \right\} + A_2 \mathcal{L}^{-1} \left\{ \frac{1}{s-4} \right\} + A_3 \mathcal{L}^{-1} \left\{ \frac{1}{s+2} \right\} = \frac{A_1 s(s-4) + A_2 (s-4)(s+2) + A_3 s(s+2)}{s(s-4)(s+2)}$$

$$= A_1 t + A_2 e^{4t} + A_3 e^{-2t}$$

$$s^2+1 = A_1(s-4)(s+2) + A_2 s(s+2) + A_3 s(s-4)$$

$$\underline{s=0} \quad 1 = A_1(-8) \Rightarrow A_1 = -\frac{1}{8}$$

$$\underline{s=4} \quad 9 = A_2 \cdot 4 \cdot 6 \Rightarrow A_2 = \frac{8}{3}$$

$$\underline{s=-2} \quad 5 = A_3(-2) \cdot (-6) \Rightarrow A_3 = \frac{5}{12}$$

$$(4) \quad \begin{cases} y'' + 4y' + 4y = t^2 \\ y(0) = y'(0) = 0 \end{cases}$$

$$\mathcal{L}\{t^2\} = \frac{2}{s^3}$$

$$(s^2+4s+4)Y(s) = \frac{2}{s^3} \Rightarrow Y(s) = \frac{2}{s^3(s+2)^2}$$

$$Y(s) = \frac{A_1}{s} + \frac{A_2}{s^2} + \frac{A_3}{s^3} + \frac{A_4}{s+2} + \frac{A_5}{(s+2)^2}$$

$$2 = \underbrace{A_1 s^2 (s+2)^2}_{A_1(s^4+\dots)} + \underbrace{A_2 s (s+2)^2}_{A_2(s^3+\dots)} + \underbrace{A_3 (s+2)^2}_{A_3(s^2+\dots)} + \underbrace{A_4 s^3 (s+2)}_{A_4(s^4+\dots)} + \underbrace{A_5 s^3}_{A_5(s^3+\dots)}$$

$$\underline{s=0} \quad 2 = A_3 \cdot 4 \Rightarrow A_3 = \frac{1}{2}$$

$$\underline{s=-2} \quad 2 = A_5(-8) \Rightarrow A_5 = -\frac{1}{4}$$

$$(4) \quad \begin{cases} x'' + 6x' + 34x = 30 \sin 2t \\ x(0) = 0 = x'(0) \end{cases}$$

• Resonance and Repeated Quadratic Factors

$$\mathcal{L}^{-1} \left\{ \frac{s}{(s^2 + k^2)^2} \right\} = \frac{1}{2k} t \sin kt$$

$$\mathcal{L}^{-1} \left\{ \frac{1}{(s^2 + k^2)^2} \right\} = \frac{1}{2k^3} (\sin kt - kt \cos kt)$$

Example 5

$$\begin{cases} x'' + \omega_0^2 x = F_0 \sin \omega t = f(t) \\ x(0) = 0 = x'(0) \end{cases} \quad x(t)$$

$$(s^2 + \omega_0^2) X(s) = F_0 \frac{\omega}{s^2 + \omega^2} \Rightarrow X(s) = F_0 \omega \frac{1}{(s^2 + \omega_0^2)(s^2 + \omega^2)}$$

$\omega = \omega_0$ $X(s) = F_0 \omega_0 \frac{1}{(s^2 + \omega_0^2)^2}$

$$x(t) = F_0 \omega_0 \mathcal{L}^{-1} \left\{ \frac{1}{(s^2 + \omega_0^2)^2} \right\} = \frac{F_0 \omega_0}{2\omega_0^3} [\sin \omega_0 t - \omega_0 t \cos \omega_0 t] \quad \boxed{\omega_0, \omega > 0}$$

$$\Rightarrow 1 = (A_1 s + A_2)(s^2 + \omega^2) + (B_1 s + B_2)(s^2 + \omega_0^2)$$

$s = \omega i$ $1 = (B_1 \omega i + B_2)(-\omega^2 + \omega_0^2)$ $B_1 = 0, \quad B_2 = \frac{1}{\omega_0^2 - \omega^2}$

$s = \omega_0 i$ $1 = (A_1 \omega_0 i + A_2)(\omega^2 - \omega_0^2)$ $A_1 = 0, \quad A_2 = \frac{1}{\omega^2 - \omega_0^2}$

$$\frac{1}{(s^2 + \omega_0^2)(s^2 + \omega^2)} = \left[\frac{1}{s^2 + \omega_0^2} - \frac{1}{s^2 + \omega^2} \right] \left(\frac{1}{\omega^2 - \omega_0^2} \right)$$

$$x(t) = \mathcal{L}^{-1} \{ X(s) \} = F_0 \omega \frac{1}{\omega^2 - \omega_0^2} \left[\mathcal{L}^{-1} \left\{ \frac{1}{s^2 + \omega_0^2} \right\} - \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + \omega^2} \right\} \right]$$

$$= \frac{F_0 \omega}{\omega^2 - \omega_0^2} \left[\frac{1}{\omega_0} \sin(\omega_0 t) - \frac{1}{\omega} \sin(\omega t) \right]$$

$\omega \neq \omega_0$

Example 6

$$\begin{cases} y^{(4)} + 2y'' + y = 4te^t \\ y(0) = y'(0) = y''(0) = y^{(3)}(0) = 0 \end{cases}$$

§7.4 Derivative, Integral, and Product of Inverse Transform

• Convolution

$$(f * g)(t) = \int_0^t f(\tau) g(t-\tau) d\tau$$

Examples

$$\cos A \sin B = \frac{1}{2} [\sin(A+B) - \sin(A-B)]$$

(1) $f(t) = \cos t$

$$g(t) = \sin t$$

#2 $f(t) = t$

$$g(t) = e^{at}$$

$$\mathcal{L}\{f * g\} = F(s)G(s) \iff \mathcal{L}^{-1}\{F(s)G(s)\} = (f * g)(t)$$

Examples

$$(2) \mathcal{L}^{-1}\left\{\frac{2}{(s-1)(s^2+4)}\right\}$$

$$\int_0^t e^{-\tau} \sin 2\tau \, d\tau = \left[\frac{e^{-\tau}}{5} (-\sin 2\tau - 2\cos 2\tau) \right]_0^t$$

$$\mathcal{L}\{-t f(t)\} = F'(s) \iff \mathcal{L}^{-1}\{(-1)F'(s)\} = t f(t)$$

$$\mathcal{L}\{t^n f(t)\} = (-1)^n F^{(n)}(s) \iff \mathcal{L}^{-1}\{(-1)^n F^{(n)}(s)\} = t^n f(t)$$

Examples

$$(3) \mathcal{L}\{t^2 \sin kt\} =$$

$$\left(\tan^{-1} s \right)' = \frac{1}{1+s^2}$$

$$-t \mathcal{L}^{-1}\{F(s)\} = -t f(t) = \mathcal{L}^{-1}\{F'(s)\}$$

$$\mathcal{L}^{-1}\{F(s)\} = -\frac{1}{t} \mathcal{L}^{-1}\{F'(s)\}$$

$$(4) \mathcal{L}^{-1}\left\{\tan^{-1}\left(\frac{1}{s}\right)\right\}$$

=

$$\mathcal{L}\left\{\frac{f(t)}{t}\right\} = \int_s^\infty F(\sigma) d\sigma \iff f(t) = \mathcal{L}^{-1}\{F(s)\} \\ = t \mathcal{L}^{-1}\left\{\int_s^\infty F(\sigma) d\sigma\right\}$$

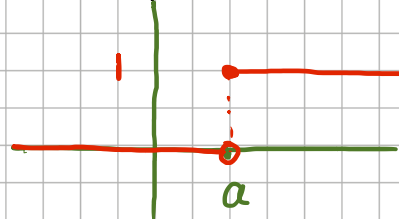
Examples

$$(6) \mathcal{L}\left\{\frac{\sinh t}{t}\right\} =$$

$$(7) \mathcal{L}^{-1} \left\{ \frac{2s}{(s^2-1)^2} \right\} =$$

§7.5 Periodic and Piecewise Continuous Input Functions

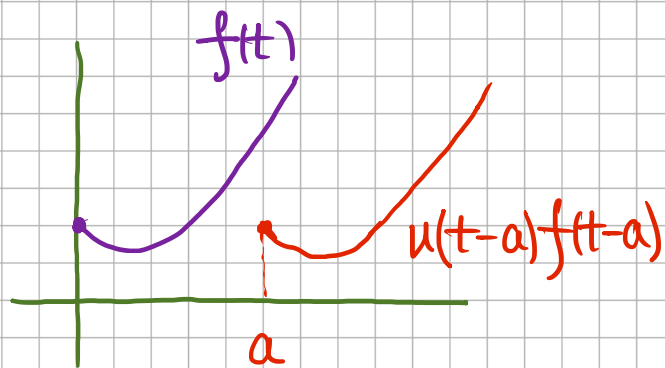
$$u_a(t) = u(t-a) = \begin{cases} 0, & t < a \\ 1, & t \geq a \end{cases}$$



$$\mathcal{L} \{ u(t-a) \} = \frac{e^{-as}}{s}$$

$$\mathcal{L} \{ u_0(t) \} = \mathcal{L} \{ u(t) \} = \frac{1}{s}$$

$$\mathcal{L} \{ u(t-a) f(t-a) \} = e^{-as} F(s)$$



$$u(t-a) f(t-a) = \mathcal{L}^{-1} \{ e^{-as} F(s) \}$$

Ex. (1)

$$\mathcal{L}^{-1} \left\{ \frac{e^{-as}}{s^3} \right\} =$$

$$(2) \quad g(t) = \begin{cases} 0, & t < 3 \\ t^2, & t \geq 3 \end{cases}$$

$$\mathcal{L}\{g(t)\} =$$

$$(3) \quad f(t) = \begin{cases} \cos 2t, & 0 \leq t < 2\pi \\ 0, & t \geq 2\pi \end{cases}$$

$$\mathcal{L}\{f(t)\} =$$

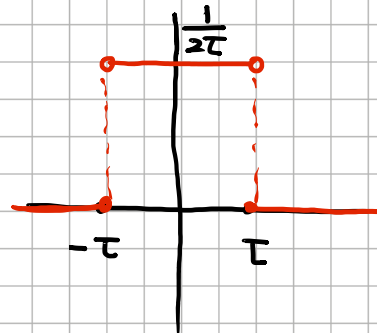
$$(4) \quad \begin{cases} x'' + 4x = f(t) & \text{in } (3) \\ x(0) = x'(0) = 0 \end{cases}$$

$$(5) \quad \begin{cases} \dot{i}(t) + 110 \bar{L}(t) + 1000 \int_0^t i(\tau) d\tau = e(t) = \begin{cases} 90, & 0 < t < 1 \\ 0, & t > 1 \end{cases} \\ i(0) = \bar{L}'(0) = 0 \end{cases}$$

§7.6 Impulse and Delta Functions

• Impulse Function

$$d_\tau(t) = \begin{cases} \frac{1}{2\tau}, & -\tau < t < \tau \\ 0, & \text{otherwise} \end{cases}$$



Properties

$$(1) \quad I(\tau) = \int_{-\infty}^{\infty} d_\tau(t) dt = 1 \quad \forall \tau \neq 0$$

$$(2) \quad \lim_{\tau \rightarrow 0^+} d_\tau(t) = 0 \quad \forall t \neq 0$$

$$(3) \quad \lim_{\tau \rightarrow 0} I(\tau) = 1$$

• Delta Function

$$\delta(t) = \lim_{\tau \rightarrow 0^+} d_{\tau}(t)$$

$$\Rightarrow (1) \delta(t) = 0 \quad \forall t \neq 0$$

$$(2) \int_{-\infty}^{\infty} \delta(t) dt = 1$$

$$(3) \int_{-\infty}^{\infty} \delta(t) f(t) dt = f(0)$$

at a

$$(1) \delta_a(t) = \delta(t-a) = 0 \quad \forall t \neq a$$

$$(2) \int_{-\infty}^{\infty} \delta(t-a) dt = 1$$

$$(3) \int_{-\infty}^{\infty} \delta(t-a) f(t) dt = f(a)$$

$$\boxed{\mathcal{L}\{\delta(t-a)\} = e^{-as}} \Rightarrow \mathcal{L}\{\delta(t)\} = 1$$

Examples

$$(1) \begin{cases} x'' + 4x = 8 \delta_{2\pi}(t) \\ x(0) = 3, x'(0) = 0 \end{cases}$$

$$(2) \begin{cases} \bar{L}'' + 110\bar{L}' + 1000\bar{L} = -90 \delta(t-1) \\ \bar{L}(0) = 0, \bar{L}'(0) = 90 \end{cases}$$

• System Analysis and Duhamel's Principle

$$\begin{cases} ax'' + bx' + cx = f(t) \\ x(0) = x'(0) = 0 \end{cases}$$

$$\Rightarrow X(s) = W(s) F(s), \text{ where } W(s) = \frac{1}{as^2 + bs + c} \Rightarrow w(t) = \mathcal{L}^{-1}\{W(s)\}$$

$$\Rightarrow x(t) = \int_0^t w(\tau) f(t-\tau) d\tau.$$

Duhamel's principle

example 4
$$\begin{cases} x'' + 6x' + 10x = f(t) \\ x(0) = x'(0) = 0 \end{cases}$$

$$w(t) = \mathcal{L}^{-1} \left\{ \frac{1}{(s+3)^2 + 1} \right\} = e^{-3t} \sin t$$

$$x(t) = \int_0^t e^{-3\tau} \sin \tau f(t-\tau) d\tau$$