

Chapter 3 Finite Element Spaces of $H^1(\Omega)$

- Definition $\mathcal{T} = \{K_i\}$ is a subdivision of the domain Ω

\iff (1) K_i are open sets

(2) $K_i \cap K_j = \emptyset$ if $i \neq j$

(3) $\bigcup_i \bar{K}_i = \bar{\Omega}$.

- global smoothness

Theorem Let Ω be a bounded domain in \mathbb{R}^d , and $v \in C^\infty(\mathcal{T})$.

$\Rightarrow "v \in H^k(\Omega) \iff v \in C^{k-1}(\Omega)"$, where $k \geq 1$.

Proof ($k=1$) For a given $v \in C^\infty(\mathcal{T})$, $\forall g \in C_0^\infty(\Omega)$

$$\begin{aligned}\int_{\Omega} \frac{\partial v}{\partial x_i} g \, dx &= \sum_K \int_K \frac{\partial v}{\partial x_i} g \, dx \\ &= - \int_{\Omega} v \frac{\partial g}{\partial x_i} \, dx + \sum_K \int_{\partial K} g v n_i \, ds\end{aligned}$$

$$v \in H^1(\Omega) \iff 0 = \sum_K \int_{\partial K} g v n_i \, ds = \sum_F \int_F g [v]_F n_i \, ds$$

$$\iff [v]_F = 0 \quad \forall \text{ interior } F \iff v \in C^0(\bar{\Omega})$$

Definition (Triangulation)

$$\Omega \subset \mathbb{R}^2$$

$\mathcal{T} = \{K\}$ is a triangulation of a polygonal domain

\iff (1) \mathcal{T} is a subdivision of Ω ,

(2) $\forall K \in \mathcal{T}$, K is either triangle or rectangle,

(3) no vertex of any $K \in \mathcal{T}$ lies in the interior of an edge of $K' \in \mathcal{T}$.

§3.1 The Finite Element

Definition (finite element)

K — element domain

ϕ — shape functions

N — nodal variables

(K, ϕ, N) is a finite element

\iff (1) $K \subset \mathbb{R}^n$ is a bounded closed set with nonempty interior

(2) ϕ is a finite-dimensional space of functions on K

(3) $N = \{N_1, \dots, N_k\}$ is a basis for ϕ .

Definition (nodal basis)

$\{\varphi_1, \dots, \varphi_k\}$ is the nodal basis of ϕ

\iff (1) $\{\varphi_1, \dots, \varphi_k\}$ is a basis of ϕ

(2) $\{\varphi_1, \dots, \varphi_k\}$ is dual to N , i.e., $N_i(\varphi_j) = \delta_{ij}$

Example (1d Lagrange element)

$$K = [a, b], \quad \mathcal{P} = P_k(K), \quad \mathcal{N}_k = \{N_0, N_1, \dots, N_k\}$$

$$N_i(v) = v\left(a + i \frac{b-a}{k}\right) \text{ for } i=0, 1, \dots, k$$

$k=1$ $N_0(v) = v(a), \quad N_1(v) = v(b)$

$k=2$ $N_0(v) = v(a), \quad N_1(v) = v\left(\frac{a+b}{2}\right), \quad N_2(v) = v(b)$

Lemma (3.1.4)

Let \mathcal{P} be a d -dimensional vector space and let $\{N_1, \dots, N_d\}$ be a subset of the dual space \mathcal{P}' .

$$\text{"}\{N_1, \dots, N_d\}\text{ is a basis for }\mathcal{P}'\text{"} \iff \text{"Given } v \in \mathcal{P} \text{ with } N_i v = 0 \text{ for } i=1, \dots, d \Rightarrow v = 0\text{"}$$

$$\forall L \in \mathcal{P}', \exists \alpha_i \text{ s.t. } L = \sum_{i=1}^d \alpha_i N_i$$

Proof Let $\{\varphi_1, \dots, \varphi_d\}$ be a basis of \mathcal{P} .

$$\text{"}\Rightarrow\text{" } v \in \mathcal{P} \Rightarrow v = \sum_{j=1}^d \beta_j \varphi_j \xrightarrow{N_i v = 0} 0 = N_i(v) = \sum_{j=1}^d \beta_j N_i(\varphi_j)$$

$$\Rightarrow C \vec{\beta} = \vec{0}, \text{ where } C = (N_i(\varphi_j))_{d \times d}$$

$$\Rightarrow \vec{\beta} = \vec{0} \iff C \text{ is invertible}$$

$$\begin{aligned}
 & \Leftarrow \text{ Let } \vec{y}_j = L(\varphi_j) = \sum_{i=1}^d \alpha_i N_i(\varphi_j) \quad \text{for } j=1, \dots, d \\
 & \Leftrightarrow \vec{y} = B \vec{\alpha}, \text{ where } B = (N_i(\varphi_j))_{d \times d} = C^t \\
 & \Rightarrow " \exists \vec{\alpha} \Leftrightarrow B \text{ is invertible}"
 \end{aligned}$$

Definition (3.1.8)

N determines \mathcal{P} \Leftrightarrow " $\psi \in \mathcal{P}$ with $N(\psi) = 0 \forall N \in \mathcal{P}'$ "
 $\Rightarrow \psi = 0$

Lemma (3.1.10)

Let P be a polynomial of degree $k \geq 1$ that vanishes on a hyperplane L .
 $\Rightarrow P = L Q$, where Q is a polynomial of degree $(k-1)$.

Proof hyperplane $L : \{ \vec{x} \in \mathbb{R}^n \mid L(\vec{x}) = 0 \}$

§3.2 Triangular Finite Elements

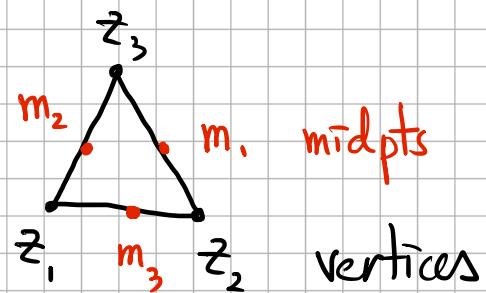
K is a triangle, $\mathcal{P}_k = \{ \text{poly. in 2 variables of degree} \leq k \}$

$$\dim \mathcal{P}_k = \frac{1}{2} (k+1)(k+2)$$

The Lagrange Element

$$k=1 \quad \mathcal{P}_1 = \text{span} \{ 1, x, y \}$$

$$\mathcal{N}_1 = \{ N_1, N_2, N_3 \}$$



- linear Lagrange element

$$N_i(v) = z_i \quad \text{for } i=1, 2, 3.$$

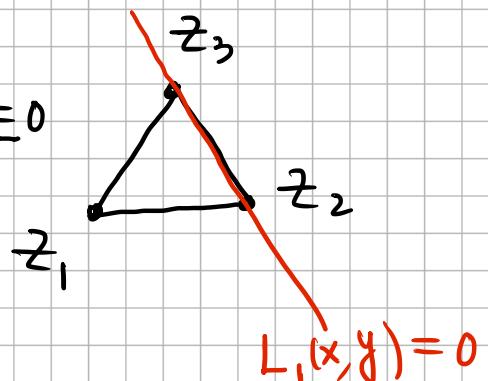
(1) \mathcal{N}_1 determines \mathcal{P}_1

Lemma $\forall v \in \mathcal{P}_1, N_i(v) = v(z_i) = 0 \implies v(x, y) \equiv 0 \text{ on } K.$

Proof $v|_{L_1} = a + b s$ is linear $\left. \begin{array}{l} \\ v(z_2) = v(z_3) = 0 \end{array} \right\} \Rightarrow v|_{L_1} = 0$

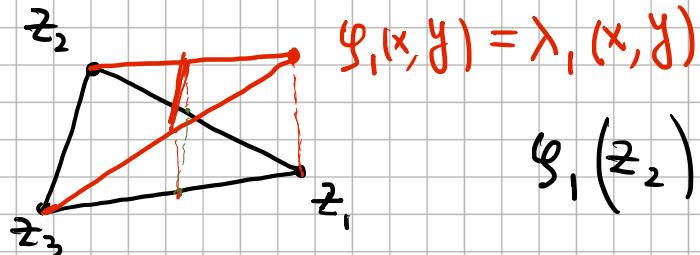
$$\implies v(x, y) = c L_1(x, y)$$

$$\implies v(z_1) = 0 \quad c = 0 \implies v \equiv 0 \text{ on } K.$$



(2) nodal basis functions $\{\varphi_i\}_{i=1}^3$

$$N_j(\varphi_i) = \varphi_i(z_j) = \delta_{ij}$$



$$\varphi_1(z_2) = \varphi_1(z_3) = 0 \implies \varphi_1|_{L_1} = 0$$

$$\Rightarrow \varphi_i = c L_i(x, y)$$

$$\varphi_i(z_i) = 1 \quad \Rightarrow \quad \varphi_i(x, y) = \frac{L_i(x, y)}{L_i(z_i)} \equiv \lambda_i(x, y)$$

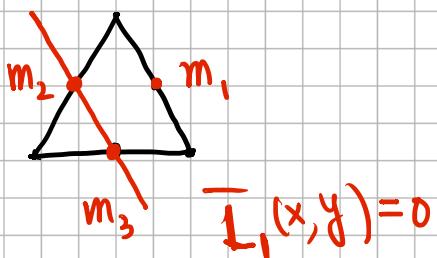
Barycentric center $\lambda_i(z_j) = \delta_{ij} \Rightarrow \lambda_i(x, y) = L_i(x, y) / L_i(z_i)$

Partition of unity $\lambda_1(x, y) + \lambda_2(x, y) + \lambda_3(x, y) = 1 \text{ on } K$.

(3) global smoothness $C^0(\bar{\Omega})$

- Crouzeix-Raviart element

$$N_i(v) = v(m_i)$$



(1) N_i determines Φ_i

(2) nodal basis function $\varphi_i(x, y) = \frac{-L_i(x, y)}{-L_i(m_i)}$

k=2 (quadratic Lagrange element)

$$\Phi_2 = \text{span} \{1, x, y, x^2, xy, y^2\}$$

$$\mathcal{N}_2 = \{N_1, N_2, \dots, N_6\}$$

$$N_i(v) = v(z_i)$$

(ii) \mathcal{N}_2 determines \mathcal{P}_2

" $\forall v \in \mathcal{P}_2, v(z_i) = 0 \implies v(x, y) \equiv 0$ on K "

Proof $v|_{L_1} = a + bs + cs^2$ $\left. v(z_2) = v(z_3) = v(z_4) = 0 \right\} \Rightarrow v|_{L_1} \equiv 0 \Rightarrow v = Q_1(x, y)L_1(x, y)$
 $Q_1 \in \mathcal{P}_1(K)$

$$v|_{L_2} \equiv 0 = L_1(x, y)Q_1(x, y) \Rightarrow Q_1(x, y)|_{L_2} \equiv 0 \text{ except possible at } z_3$$

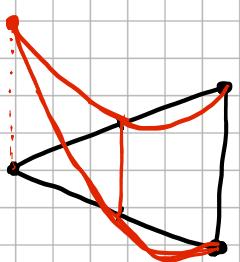
$$\Rightarrow Q_1(x, y)|_{L_2} \equiv 0 \Rightarrow Q_1(x, y) = cL_2(x, y)$$

$$\Rightarrow v = cL_1(x, y)L_2(x, y) \xrightarrow{v(z_6)=0} c=0 \Rightarrow v(x, y) \equiv 0 \text{ on } K. \quad \#$$

(2) nodal basis functions

$$\varphi_1(x, y) = c \lambda_1(x, y) (2\lambda_1(x, y) - 1)$$

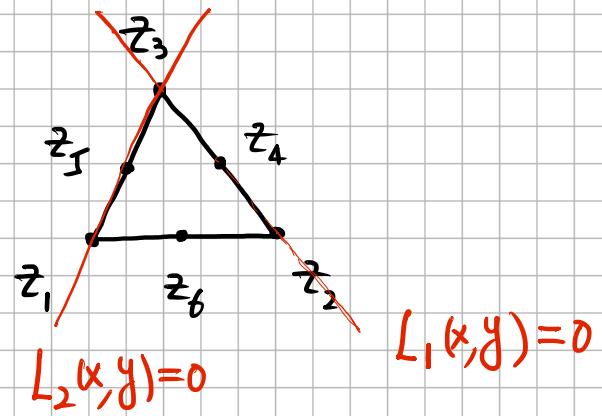
$$\varphi_1(z_1) = 1$$

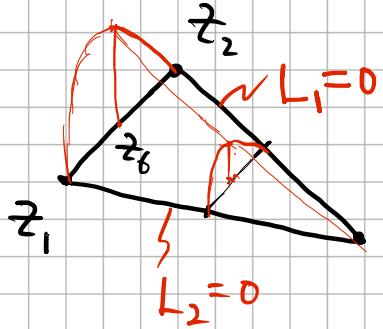


$$\lambda_1 \cdot \frac{1}{2} = 0 \quad \lambda_1 = 0$$

$$\Rightarrow \varphi_1(x, y) = \lambda_1(2\lambda_1 - 1)$$

$$\varphi_2(x, y) = \lambda_2(2\lambda_2 - 1), \quad \varphi_3(x, y) = \lambda_3(2\lambda_3 - 1)$$





$$\begin{aligned} \Phi_6 &= c, \lambda_1, \lambda_2 \\ \Phi_6(z_6) &= 1 = c \lambda_1(z_6) \lambda_2(z_6) = \frac{c}{4} \end{aligned} \quad \left\{ \Rightarrow \Phi_6(x, y) = 4 \lambda_1 \lambda_2 \right.$$

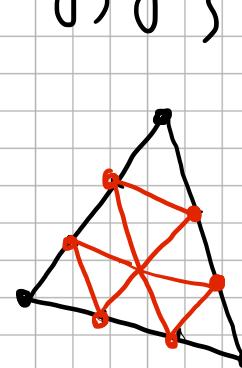
$$\Phi_5 = 4 \lambda_2 \lambda_3, \quad \Phi_6 = 4 \lambda_1 \lambda_3$$

$k=3$ (cubic Lagrange element)

$$\mathcal{P}_3 = \text{span} \{ 1, x, y, x^2, xy, y^2, x^3, x^2y, xy^2, y^3 \}$$

$$\mathcal{N}_3 = \{ N_1, \dots, N_{10} \}$$

$$N_i(v) = v(z_i)$$



3 vertices

6 edge nodes

1 interior node

N_3 determines \mathcal{P}_3

$$v(z_i) = 0 \implies v = c L_1 L_2 L_3 \stackrel{v(z_{10})=0}{\implies} v(x, y) \equiv 0 \text{ on } K.$$

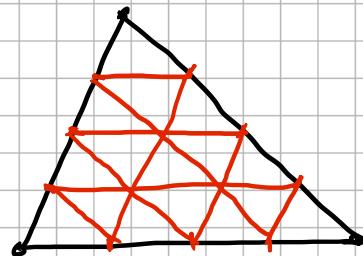
general k

$$\mathcal{P}_k = \{ \text{polynomials of degree } \leq k \}$$

$$\mathcal{N}_k = \{ N_1, \dots, N_{m(k)} \}, \quad m(k) = \dim \mathcal{P}_k = \frac{1}{2} (k+2)(k+1)$$

$$N_i(v) = v(z_i) \quad - \text{nodal values}$$

$$\frac{\dim \mathcal{P}_{k-3}}{\dim \mathcal{P}_k} = \frac{\frac{1}{2}(k-2)(k-1)}{\frac{1}{2}(k+2)(k+1)}$$



N_k determines \mathcal{P}_k

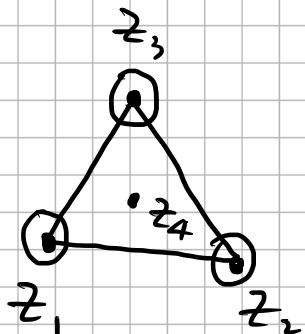
$$v = L_1 L_2 L_3 Q, \quad Q \in \mathcal{P}_{k-3}$$

$\Rightarrow Q = 0$ at all interior nodes

$\Rightarrow Q \equiv 0 \Rightarrow v \equiv 0$ on K . #

The Hermite Element

$k=3$ (cubic Hermite) $\mathcal{P} = \mathcal{P}_3$



N : • nodal value { vertices 3
 interior 1

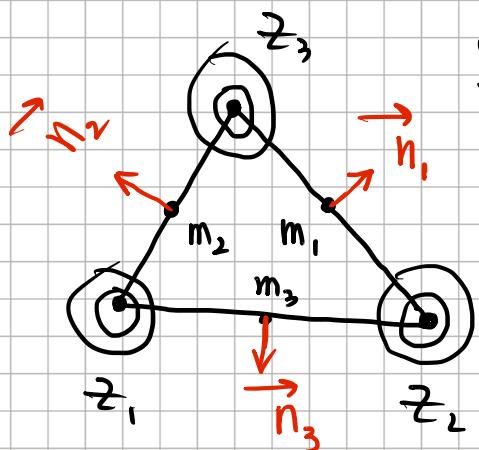
0 gradient at vertices $2 \times 3 = 6$

$\forall v \in \mathcal{P}_3, v|_{L_i} \equiv 0 \Rightarrow v = c_1 L_1 L_2 L_3 \Rightarrow c_1 = 0 \Rightarrow v \equiv 0$ on K .

$$v(z_4) = 0$$

The Argyris's Element

$C^1(\Omega)$



$$\phi = \phi_S$$

$$\dim \phi_S = 21$$

$$\mathcal{N} = \begin{array}{l} \text{• value } 3 \times 1 \\ \text{• gradient } 3 \times 2 \\ \text{• } 2^{\text{nd}} \text{ order der. } 3 \times 3 \\ \text{• normal der. } 3 \times 1 \end{array}$$

21

\mathcal{N} determines ϕ

Proof $\forall v \in \mathcal{P}_5, v|_{L_i} \equiv 0 \Rightarrow v = L_1 L_2 L_3 Q, Q \in \mathcal{P}_2$

$$0 = \partial_{L_1} (\partial_{L_2} v)(z_3) = Q(z_3) L_3(z_3) \frac{\partial L_1}{\partial L_2} \cdot \frac{\partial L_2}{\partial L_1} \Rightarrow \boxed{Q(z_3) = 0} \Rightarrow \begin{cases} Q(z_1) = 0 \\ Q(z_2) = 0 \end{cases}$$

$\left[\frac{\partial L_i(x, y)}{\partial L_i} \equiv 0 \text{ since } L_i(x, y) = \text{constant along the } L_i \right]$

$$L_1(z_3) = 0 = L_2(z_3), L_3(z_3) \neq 0, \frac{\partial L_1}{\partial L_2} \neq 0, \frac{\partial L_2}{\partial L_1} \neq 0$$

$$\frac{\partial v}{\partial L_2} = L_2 \frac{\partial}{\partial L_2} (L_1 L_3 Q) \Rightarrow \frac{\partial^2 v}{\partial L_1 \partial L_2} \Big|_{z_3} = \frac{\partial L_2}{\partial L_1} \frac{\partial}{\partial L_2} (L_1 L_3 Q) \Big|_{z_3} + L_2 \frac{\partial^2}{\partial L_1 \partial L_2} (L_1 L_3 Q) \Big|_{z_3}$$

$$\frac{\partial}{\partial L_2} (L_1 L_3 Q)(z_3) = L_3 Q \frac{\partial L_1}{\partial L_2} \Big|_{z_3}$$

$$\underline{L_1(m_1) = 0} \Rightarrow 0 = \frac{\partial v}{\partial n_1}(m_1) = \frac{\partial L_1}{\partial n_1} L_2(m_1) L_3(m_1) Q(m_1) \Rightarrow Q(m_1) = 0$$

$$\Rightarrow Q(m_2) = Q(m_3) = 0$$

$$\Rightarrow Q = 0 \Rightarrow v \equiv 0 \text{ on K.}$$

$C^1(\Gamma)$ element in \mathbb{R}^1

$$p(x_i^-) = p(x_i^+)$$

$$p'(x_i^-) = p'(x_i^+)$$

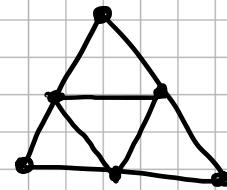
$\Rightarrow 4 \text{ at each } [x_{i-1}, x_i]$

$\Rightarrow \text{cubic polynomial}$

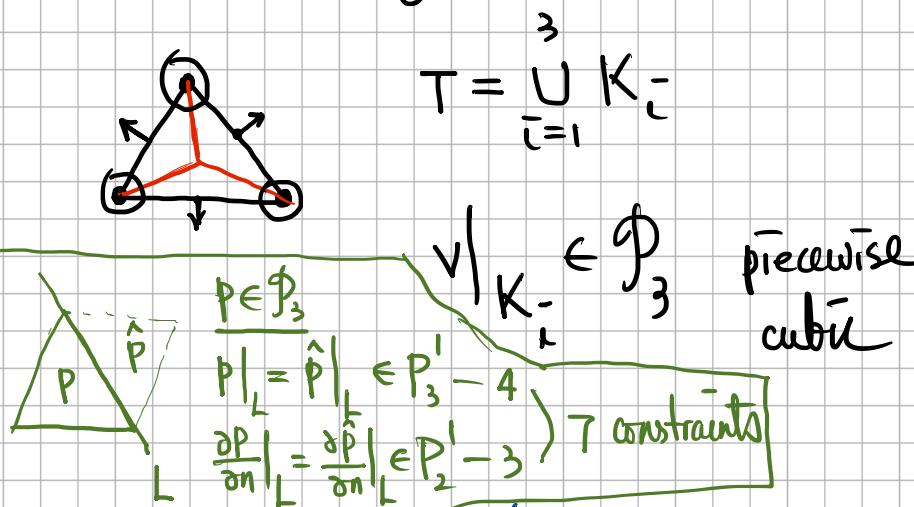


The Composite Elements

(1) C^0 macro piecewise linear element



(2) Hsieh-Clough-Tocher element $C^1(\Omega)$



- nodal values at vertices 3
 - gradient at vertices 2×3
 - normal der. at midpts 3
- dim = 12

motivation

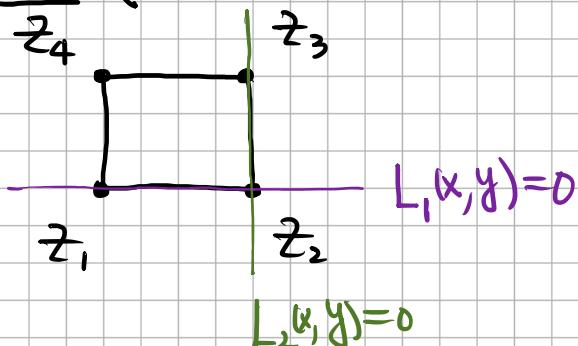
$$v(x, y) = \left(\sum_i v_x^i \varphi_i(x) \right) \left(\sum_j v_y^j \psi_j(y) \right)$$

$$= \sum_{i,j} v_x^i v_y^j \varphi_i(x) \psi_j(y)$$

Rectangular Element (tensor product element)

$$Q_k = \left\{ p(x) \tilde{f}(y) \mid p, \tilde{f} \in \Phi_k^1 \right\}, \text{ where } \Phi_k^1 - \text{poly. of degree } \leq k \text{ of one variable}$$

$k=1$ (bi-linear element)



$$Q_1 = \text{span} \{ 1, x, y, xy \}$$

N_1 — nodal values at vertices

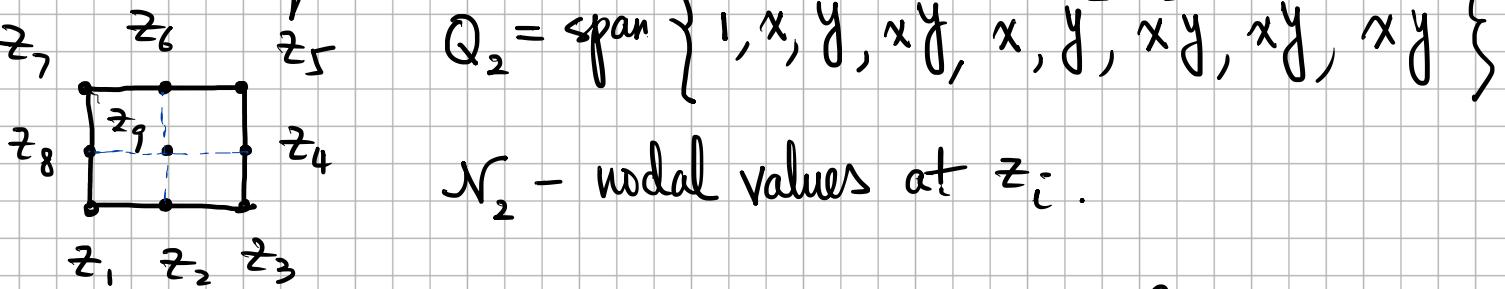
N_1 determines Q_1

$$v(z_1) = 0 \quad \forall v \in Q_1$$

$$v(z_4) = 0$$

$$\Rightarrow v = c L_1 L_2 \xrightarrow{c=0} v=0 \text{ on } K.$$

$k=2$ (bi-quadratic element)



\mathcal{N}_2 - nodal values at z_i .

Lemma $v \in \mathcal{P}_2 \implies \exists c_i \text{ s.t. } v(z_q) = \sum_{i=1}^8 c_i v(z_i)$

Proof $\forall v \in \mathcal{P}_2, v(x, y) = \sum_{i=1}^6 v(z_i) \varphi_i(x, y) \Rightarrow v(z_q) = \sum_{i=1}^8 c_i v(z_i)$ #

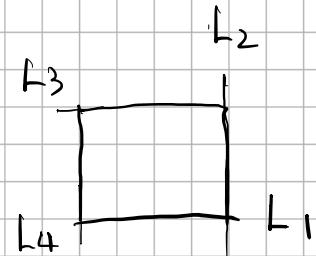
$$c_i = \varphi_i(z_q), i=1 \dots 6, c_7 = c_8 = 0$$

The Serendipity element

$$\mathcal{P} = \left\{ v \in Q_2 \mid \sum_{i=1}^8 c_i v(z_i) - v(z_q) = 0 \right\}$$

\mathcal{N} = nodal values at z_i for $i=1 \dots 8$

\mathcal{N} determines \mathcal{P}



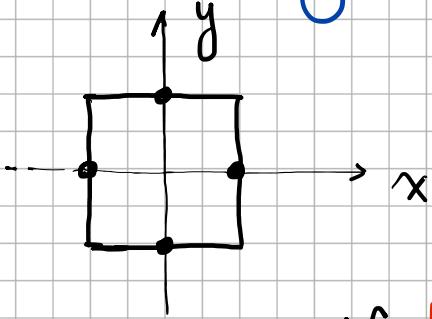
$$v(z_i) = 0 \text{ for } i=1 \dots 8 \implies v = c L_1 L_2 L_3 L_4$$

$$\Rightarrow 0 = \sum_{i=1}^8 c_i v(z_i) = v(z_q) = c L_1(z_q) L_2(z_q) L_3(z_q) L_4(z_q)$$

$$\Rightarrow c = 0 \implies v \equiv 0 \text{ on } K$$

#

The Rectangular non-conforming element



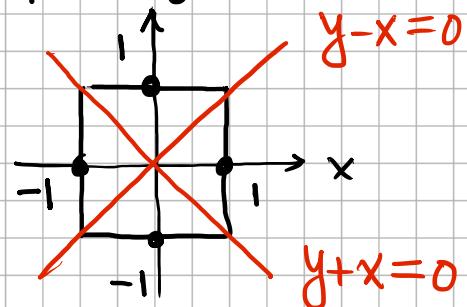
$$\Phi = Q_1 = \text{span} \{ 1, x, y, xy \}$$

N - nodal values at midpts

N does not determine Q_1

Proof xy vanishes at all 4 midpts.

$$\Phi = \{ 1, x, y, (y-x)(y+x) \} .$$



N determines Φ

Proof Let $v(x, y) = c_0 + c_1 x + c_2 y + c_3 (y^2 - x^2)$

at $(\pm 1, 0)$ $0 = v(\pm 1, 0) = c_0 \pm c_1 - c_3 \Rightarrow \begin{cases} c_0 = c_3 \\ c_1 = 0 \end{cases}$

at $(0, \pm 1)$ $0 = v(0, \pm 1) = c_0 \pm c_2 + c_3 \Rightarrow \begin{cases} c_0 = -c_3 \\ c_2 = 0 \end{cases}$

$\Rightarrow c_i = 0 \Rightarrow v \equiv 0 \text{ on } K$.

#

§3.3 The Interpolant

- local interpolant for finite element (K, ϕ, N)

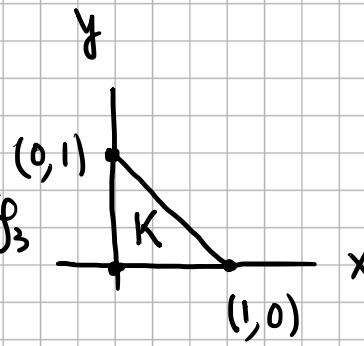
$$I_K v(x) = \sum_{i=1}^k N_i(v) \varphi_i(x), \quad x \in K$$

where $\phi = \text{span} \{ \varphi_i \}_{i=1}^k$.

e.g. $f(x, y) = e^{x+y}$, $\phi_1 = \text{span} \{ \varphi_i \}_{i=1}^3$

$$I_K f = f(0,0) \varphi_1(x,y) + f(1,0) \varphi_2 + f(0,1) \varphi_3$$

$$= (1-x-y) + x + y = 1$$



Properties

(1) I_K is linear

(2) $N_i(I_K f) = N_i(f)$ for $i = 1, \dots, k$

$$\text{N}_i \left(\sum_j N_j(f) \varphi_j \right) = \sum_j N_j(f) N_i(\varphi_j) = N_i(f)$$

(3) $I_K(f) = f \quad \forall f \in \phi$. $\Rightarrow I_K^2 = I_K$, i.e., I_K is a projection

- global interpolant

$$\left. I_g f \right|_K = I_K f \quad \forall K \in \mathcal{T}.$$

§3.4 Neural Nets

$$\mathcal{N}_N(\vec{\theta}) = \left\{ c_0 + \sum_i c_i \sigma_k^{\vec{w}_i \cdot \vec{x} - b_i} : c_i, b_i \in \mathbb{R}, \vec{w}_i \in S^{d_1} \right\}$$

$$\sigma_k(t) = \max \{0, t^k\} = \begin{cases} t^k, & t > 0 \\ 0, & t \leq 0. \end{cases}$$