

3.5 Inverses of Matrices

scalar: "1" is a number such that $1 \cdot a = a \cdot 1 = a$

and the scalar inverse is a^{-1} such that $a^{-1}a = a a^{-1} = 1$

matrix: I is the identity matrix such that $IA = AI = A$

and ~~some~~ matrix inverse A^{-1} is such that $A^{-1}A = AA^{-1} = I$

$$I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

2×2

ones on main diagonal, zeros everywhere else

$$n \times n: I = \begin{bmatrix} 1 & \dots & 0 \\ 0 & \ddots & 0 \\ \vdots & & \vdots \\ 0 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$AI = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$IA = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$\underbrace{A^{-1}A = AA^{-1} = I}$$

implies A has to be square matrix to have an inverse

not every matrix has an inverse (just like 0 (scalar) doesn't have an inverse)

if A^{-1} exists $\rightarrow A$ is invertible

if A^{-1} doesn't exist $\rightarrow A$ is singular

$$\text{if } A \text{ is } 2 \times 2, A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\text{then } A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$ad-bc$ is the determinant of A

A^{-1} exists only if $\det(A) \neq 0$

example

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$A^{-1} = \frac{1}{1 \cdot 4 - 2 \cdot 3} \begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix}$$

check: $AA^{-1} = I$ AND $A^{-1}A = I$

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} -2 & 1 \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} -2 & 1 \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

inverse can be used to solve matrix equations

scalar: $ax = b \rightarrow x = a^{-1}b$ because $\underbrace{a^{-1}a}_1 x = a^{-1}b$

matrix: $A\vec{x} = \vec{b} \rightarrow \underbrace{A^{-1}A}_I \vec{x} = A^{-1}\vec{b} = \vec{x} = A^{-1}\vec{b}$

example

$$x_1 + 2x_2 = 5$$

$$3x_1 + 4x_2 = 6$$

$$\underbrace{\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}}_A \underbrace{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}}_{\vec{x}} = \underbrace{\begin{bmatrix} 5 \\ 6 \end{bmatrix}}_{\vec{b}}$$

solved by $\vec{x} = A^{-1}\vec{b}$

$$A^{-1} = \begin{bmatrix} -2 & 1 \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix} \text{ (last example)}$$

$$\vec{x} = \begin{bmatrix} -2 & 1 \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix} \begin{bmatrix} 5 \\ 6 \end{bmatrix}$$

$$= \begin{bmatrix} -4 \\ \frac{9}{2} \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

no formulas for A^{-1} for $n \times n$ where $n > 2$

but there is a general algorithm that works for all $n \times n$

make an augmented matrix w/ A on left and I on right

$$\left[A \quad \vdots \quad I \right] \text{ for readability only}$$

perform row operations until left half is I

then whatever is on the right is A^{-1}

$$\begin{array}{c} \vdots \\ \left[I \quad \vdots \quad A^{-1} \right] \end{array}$$

try on $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$

$$\left[\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 3 & 4 & 0 & 1 \end{array} \right] \rightarrow \left[\begin{array}{cc|cc} 1 & 2 & 1 & 0 \\ 0 & -2 & -3 & 1 \end{array} \right]$$

$$\rightarrow \begin{bmatrix} 1 & 0 & \vdots & -2 & 1 \\ 0 & -2 & \vdots & -3 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & \vdots & -2 & 1 \\ 0 & 1 & \vdots & \frac{3}{2} & -\frac{1}{2} \end{bmatrix} \underbrace{\hspace{10em}}_{A^{-1}}$$

example

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$$

find A^{-1} if it exists

$$\begin{bmatrix} 1 & 0 & 0 & \vdots & 1 & 0 & 0 \\ 1 & 1 & 0 & \vdots & 0 & 1 & 0 \\ 1 & 1 & 1 & \vdots & 0 & 0 & 1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 0 & 0 & \vdots & 1 & 0 & 0 \\ 0 & 1 & 0 & \vdots & -1 & 1 & 0 \\ 0 & 1 & 1 & \vdots & -1 & 0 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & \vdots & 1 & 0 & 0 \\ 0 & 1 & 0 & \vdots & -1 & 1 & 0 \\ 0 & 0 & 1 & \vdots & 0 & -1 & 1 \end{bmatrix} \underbrace{\hspace{10em}}_{A^{-1}}$$

example

$$A = \begin{bmatrix} 1 & -2 & -1 \\ -1 & 5 & 6 \\ 5 & -4 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & -1 & \vdots & 1 & 0 & 0 \\ -1 & 5 & 6 & \vdots & 0 & 1 & 0 \\ 5 & -4 & 5 & \vdots & 0 & 0 & 1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & -2 & -1 & \vdots & 1 & 0 & 0 \\ 0 & 3 & 5 & \vdots & 1 & 1 & 0 \\ 0 & 6 & 10 & \vdots & -5 & 0 & 1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & -2 & -1 & \vdots & 1 & 0 & 0 \\ 0 & 3 & 5 & \vdots & 1 & 1 & 0 \\ 0 & 0 & 0 & \vdots & x & x & x \end{bmatrix}$$

can't turn into I

so A is not invertible

Why does $[A : I] \xrightarrow{\text{ops}} [I : A^{-1}]$ work?

$$a x_1 + b x_2 = e$$

$$c x_1 + d x_2 = f$$

solution of x_1, x_2 is

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} e \\ f \end{bmatrix} \quad \begin{bmatrix} a & b & : & e \\ c & d & : & f \end{bmatrix} \rightarrow \begin{bmatrix} I & : & \vec{x} \end{bmatrix}$$

finding inverse is the same idea

$$A X = I \quad X = A^{-1}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} e & f \\ g & h \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

same logic

$$\begin{bmatrix} a & b & : & 1 & 0 \\ c & d & : & 0 & 1 \end{bmatrix}$$

$$\xrightarrow{\text{ops}} \begin{bmatrix} I & : & e & f \\ & & g & h \end{bmatrix}$$

$$\underbrace{\quad\quad\quad}_{X = A^{-1}}$$