

7.3 The Eigenvalue Method (continued)

$$\vec{x}' = A \vec{x}$$

Solution: $\vec{x} = c_1 e^{\lambda_1 t} \vec{v}_1 + c_2 e^{\lambda_2 t} \vec{v}_2 + \dots + c_n e^{\lambda_n t} \vec{v}_n$

λ, \vec{v} are the eigenvalue/eigenvector pairs

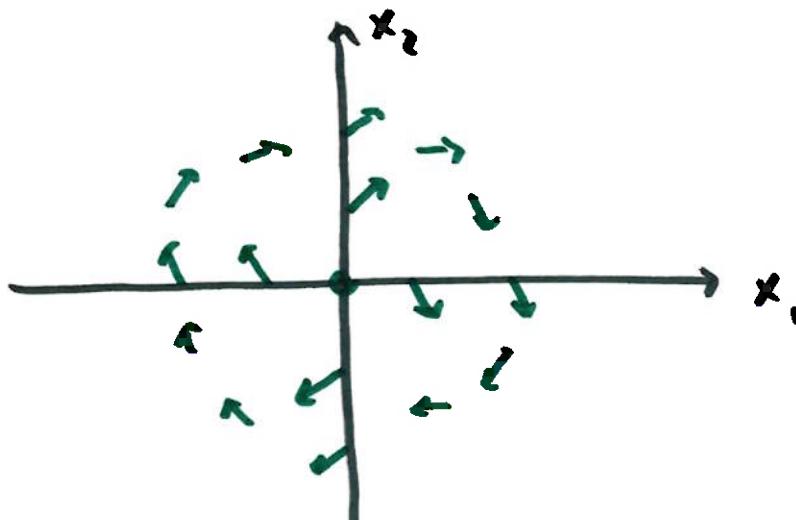
if λ 's are real and distinct, then the \vec{v} 's are always linear independent
so solution is easy to put together

let's now look at complex eigenvalues

example

$$\vec{x}' = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \vec{x}$$

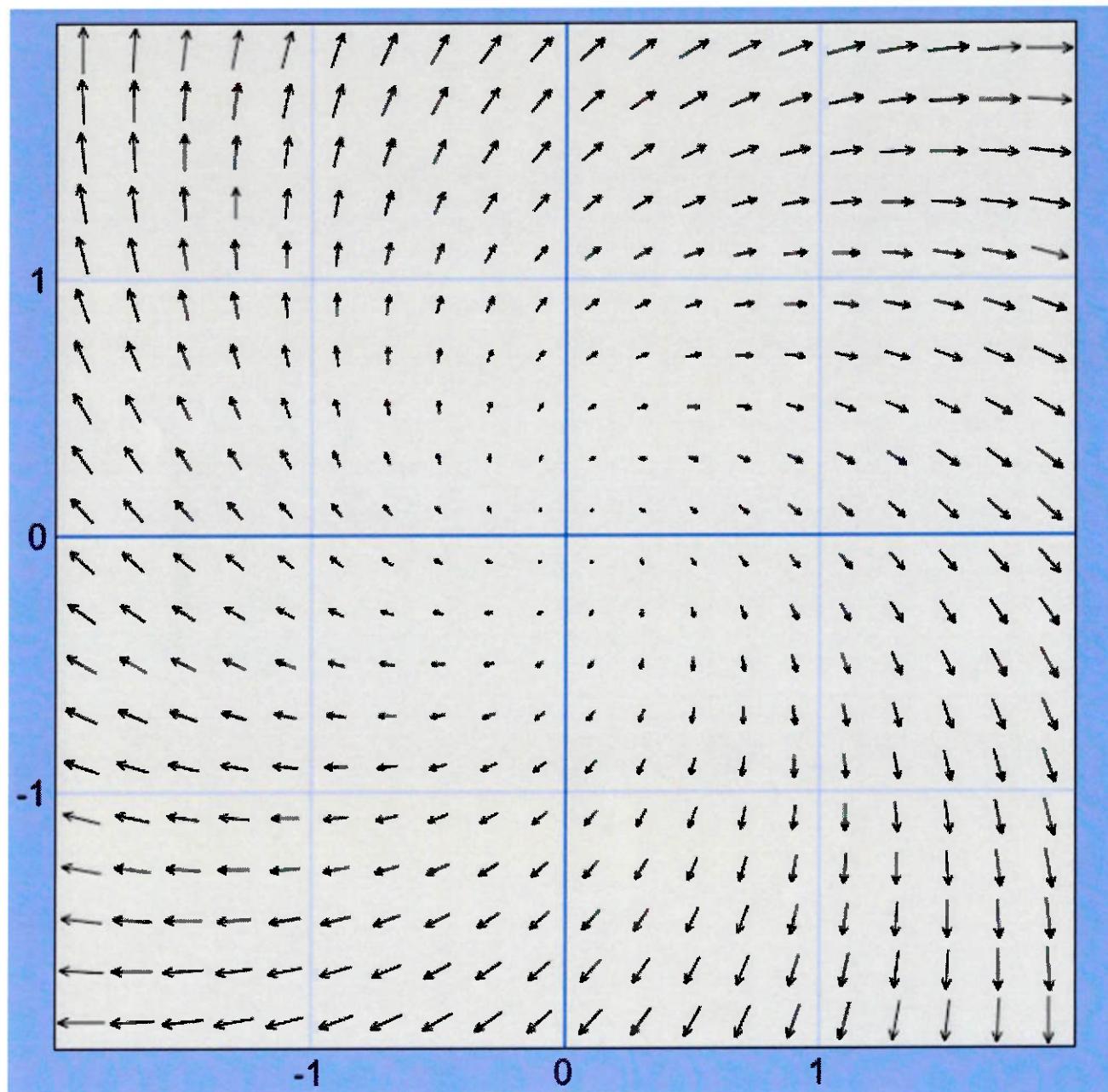
let's take a look at the slope field



$$\begin{aligned}\vec{x} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} & \vec{x}' &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \vec{x} &= \begin{bmatrix} 1 \\ 0 \end{bmatrix} & \vec{x}' &= \begin{bmatrix} 1 \\ -1 \end{bmatrix}\end{aligned}$$

rotation in the slope field

$\rightarrow \lambda$'s are complex



$$\vec{x}' = \begin{bmatrix} 1 & i \\ -i & 1 \end{bmatrix} \vec{x}$$

$$\begin{vmatrix} 1-\lambda & 1 \\ -i & 1-\lambda \end{vmatrix} = 0 \quad (1-\lambda)^2 + 1 = 0 \quad (1-\lambda)^2 = -1$$

$$1-\lambda = i, \quad 1-\lambda = -i$$

$$\lambda = 1-i, \quad \lambda = 1+i$$

conjugate pairs

$$\text{eigenvector: } (A - \lambda I) \vec{v} = \vec{0}$$

$$\underline{\lambda = 1+i} \quad \begin{bmatrix} -i & 1 & 0 \\ -i & 1-i & 0 \end{bmatrix} \rightarrow \dots \rightarrow \begin{bmatrix} 1 & i & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\vec{v} = \begin{bmatrix} 1 \\ i \end{bmatrix} \quad \text{pick } \vec{v} \text{ such that } (A - \lambda I) \vec{v} = \vec{0}$$

$$\underline{\lambda = 1-i} \quad \begin{bmatrix} i & 1 & 0 \\ -i & i & 0 \end{bmatrix} \rightarrow \dots \rightarrow \begin{bmatrix} 1 & -i & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\vec{v} = \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

as expected, \vec{v} 's are also conjugate pairs

Each independent solution is $e^{\lambda t} \vec{v}$

$$\lambda = 1+i, \vec{v} = \begin{bmatrix} 1 \\ i \end{bmatrix}$$

Euler's formula

$$e^{it} = \cos(t) + i \sin(t)$$

$$e^{(1+i)t} \begin{bmatrix} 1 \\ i \end{bmatrix} = e^t e^{it} \begin{bmatrix} 1 \\ i \end{bmatrix} = e^t (\cos t + i \sin t) \begin{bmatrix} 1 \\ i \end{bmatrix}$$

$$= e^t \begin{bmatrix} \cos t + i \sin t \\ -\sin t + i \cos t \end{bmatrix} = e^t \begin{bmatrix} \cos t \\ -\sin t \end{bmatrix} + i e^t \begin{bmatrix} \sin t \\ \cos t \end{bmatrix}$$

$i^2 \sin t = -\sin t$

$$\lambda = 1-i, \vec{v} = \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

$$\begin{aligned} \cos(-t) &= \cos(t) \\ \sin(-t) &= -\sin(t) \end{aligned}$$

$$e^{(1-i)t} \begin{bmatrix} 1 \\ -i \end{bmatrix} = e^t e^{i(-t)} \begin{bmatrix} 1 \\ -i \end{bmatrix} = e^t (\cos t - i \sin t) \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

$$= e^t \begin{bmatrix} \cos t - i \sin t \\ -\sin t - i \cos t \end{bmatrix} = e^t \begin{bmatrix} \cos t \\ -\sin t \end{bmatrix} - i e^t \begin{bmatrix} \sin t \\ \cos t \end{bmatrix}$$

again, complex conjugate pair

general solution: $\vec{x} = c_1 e^{\lambda_1 t} \vec{v}_1 + c_2 e^{\lambda_2 t} \vec{v}_2$

$$\vec{x} = c_1 \left\{ e^t \begin{bmatrix} \cos t \\ -\sin t \end{bmatrix} + i e^t \begin{bmatrix} \sin t \\ \cos t \end{bmatrix} \right\} + c_2 \left\{ e^t \begin{bmatrix} \cos t \\ -\sin t \end{bmatrix} - i e^t \begin{bmatrix} \sin t \\ \cos t \end{bmatrix} \right\}$$

real-valued function, we want to eliminate i (c_1, c_2 are complex)

$$= \underbrace{(c_1 + c_2) e^t \begin{bmatrix} \cos t \\ -\sin t \end{bmatrix}}_{\text{"c,"}} + i \underbrace{(c_1 - c_2) e^t \begin{bmatrix} \sin t \\ \cos t \end{bmatrix}}_{\text{"c,"}}$$

$$\boxed{\vec{x} = c_1 e^t \begin{bmatrix} \cos t \\ -\sin t \end{bmatrix} + c_2 e^t \begin{bmatrix} \sin t \\ \cos t \end{bmatrix}}$$

real part of imaginary part
either solution of either solution

complex λ 's: identify real and imaginary parts of either solution
then use them as the basis solutions of the general solution

example $\vec{x}' = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \vec{x}$

$$\begin{vmatrix} -\lambda & 1 \\ -1 & -\lambda \end{vmatrix} = 0 \quad \lambda^2 + 1 = 0 \quad \lambda = \pm i$$

just need one of these solutions

$\lambda = -i$ $(A - \lambda I) \vec{v} = \vec{0}$

$$\begin{bmatrix} i & 1 & 0 \\ -1 & i & 0 \end{bmatrix} \rightarrow \dots \rightarrow \begin{bmatrix} 1 & -i & 0 \\ 0 & 0 & 0 \end{bmatrix} \vec{v} = \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

how about $\begin{bmatrix} i \\ 1 \end{bmatrix}$?

let's use $\lambda = -i$, $\vec{v} = \begin{bmatrix} i \\ 1 \end{bmatrix}$

also ok, will affect
the form of solution
but still the same

$$\begin{aligned} e^{\lambda t} \vec{v} &= e^{-it} \begin{bmatrix} i \\ 1 \end{bmatrix} = (\cos t - i \sin t) \begin{bmatrix} i \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} \cos t - i \sin t \\ -\sin t - i \cos t \end{bmatrix} = \boxed{\begin{bmatrix} \cos t \\ -\sin t \end{bmatrix}} - i \boxed{\begin{bmatrix} \sin t \\ \cos t \end{bmatrix}} \end{aligned}$$

use these
in gen.
solution

what would it look like if we picked $\vec{v} = [i]$

$$e^{\lambda t} \vec{v} = (\text{cost} - i \text{sint}) [i]$$

$$= \begin{bmatrix} \text{sint} + i \text{cost} \\ \text{cost} - i \text{sint} \end{bmatrix} = \begin{bmatrix} \text{sint} \\ \text{cost} \end{bmatrix} + i \begin{bmatrix} \text{cost} \\ -\text{sint} \end{bmatrix}$$

or these

general solution

$$\vec{x} = c_1 \begin{bmatrix} \text{cost} \\ -\text{sint} \end{bmatrix} + c_2 \begin{bmatrix} \text{sint} \\ \text{cost} \end{bmatrix}$$

or ↑

example

$$\vec{x}' = \begin{bmatrix} 3 & 0 & 1 \\ 9 & -1 & 2 \\ -9 & 4 & -1 \end{bmatrix} \vec{x}$$

possibilities: 3 real λ 's
1 real, 2 complex

$$i \lambda = 3, -1+i, -1-i$$

$$i \vec{v} = \begin{bmatrix} 4 \\ 9 \\ 0 \end{bmatrix}, \begin{bmatrix} -4-i \\ -9+2i \\ 17 \end{bmatrix}, \begin{bmatrix} -4+i \\ -9-2i \\ 17 \end{bmatrix}$$

$$e^{3t} \begin{bmatrix} 4 \\ 9 \\ 0 \end{bmatrix}$$

the other two, follow previous examples
→ form one solution, pick out real and
imaginary parts to go into the gen. solution