

## 7.6 Multiple/Repeated Eigenvalues

$$\vec{x}' = A\vec{x} \quad \text{solutions are } e^{\lambda t} \vec{v}$$

gen. solution  $\vec{x} = c_1 e^{\lambda_1 t} \vec{v}_1 + c_2 e^{\lambda_2 t} \vec{v}_2 + \dots + c_n e^{\lambda_n t} \vec{v}_n$

$\lambda, \vec{v}$  pairs

no issues if  $\lambda$ 's are distinct or complex  
potential problems if  $\lambda$ 's are repeated

$$\vec{x}' = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \vec{x} \quad \lambda = 1, 1$$

the eigenvalue of 1  
is repeated twice  
(algebraic multiplicity  
of two)

eigenvector:  $(A - \lambda I) \vec{v} = \vec{0}$

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \vec{v} = \begin{bmatrix} a \\ b \end{bmatrix} \quad \text{here, both } a \text{ and } b \text{ are free}$$

let  $a=r, b=s$

$$\text{then } \vec{v} = \begin{bmatrix} r \\ s \end{bmatrix} = r \begin{bmatrix} 1 \\ 0 \end{bmatrix} + s \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

form solutions using 

general solution:

$$\vec{x} = c_1 e^t \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 e^t \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

if matrix is complete, enough eigenvectors to form linearly indp solutions  $\rightarrow$  solutions are formed the usual way.

the eigenspace has a dimension of two  
 → two basis vectors (eigenvectors)  
 → geometric multiplicity of two  
 if algebraic multiplicity = geo. multiplicity we say the matrix  $A$  is complete

now look at

$$\vec{x}' = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \vec{x} \quad \lambda = 1, 1$$

$$(A - \lambda I) \vec{v} = \vec{0}$$

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \quad \text{only one free variable}$$

$$\vec{v} = \begin{bmatrix} a \\ b \end{bmatrix} \quad b = 0 \\ a = \text{free} = r$$

$$\vec{v} = \begin{bmatrix} r \\ 0 \end{bmatrix} = r \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \begin{array}{l} \text{eigenspace} \\ \text{dimension is } \underline{\text{one}} \\ \text{only } \underline{\text{one}} \text{ eigenvector} \end{array}$$

we are missing a vector

$$\text{first solution: } e^{\lambda_1 t} \vec{v}_1 = e^t \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\text{2nd one: } e^{\lambda_2 t} \vec{v}_2$$

when we are missing eigenvectors,  
we say the matrix A is defective

in scalar case, if the roots of characteristic eq. are repeated, we multiply the existing solution by  $t$  to form a new one

$$y'' + 10y' + 25y = 0$$

$$t^2 + 10t + 25 = 0 \rightarrow t = 5, 5$$

$$y_1 = e^{5t} \quad y_2 = t e^{5t}$$

so, we might expect we form the 2nd solution in  $\vec{x}' = A\vec{x}$  by doing the same thing:

$$\vec{x}_1 = e^{\lambda t} \vec{v}_1$$

~~$$\vec{x}_2 = e^{\lambda t} \vec{v}_1 t$$~~

But, this does NOT work

instead, we need

$$\vec{x}_2 = e^{\lambda t} (t \vec{v}_1 + \vec{v}_2)$$

Ordinary  
eigenvector

need to find  
(generalized  
eigenvector)

how to find  $\vec{v}_2$ ?

$$\vec{x}' = A\vec{x}$$

eigenvalue  $\lambda$  only one eigenvector  $\vec{v}_1$

the second solution is  $\vec{x}_2 = e^{\lambda t} (t\vec{v}_1 + \vec{v}_2) = te^{\lambda t}\vec{v}_1 + e^{\lambda t}\vec{v}_2$

Sub into  $\vec{x}' = A\vec{x}$

$$\vec{x}_2' = t\lambda e^{\lambda t}\vec{v}_1 + e^{\lambda t}\vec{v}_1 + \lambda e^{\lambda t}\vec{v}_2$$

$$t\lambda e^{\lambda t}\vec{v}_1 + e^{\lambda t}\vec{v}_1 + \lambda e^{\lambda t}\vec{v}_2 = Ate^{\lambda t}\vec{v}_1 + Ae^{\lambda t}\vec{v}_2$$

compare like terms

$te^{\lambda t}$  terms:  $\lambda\vec{v}_1 = A\vec{v}_1 \rightarrow$  nothing new, definition of  $\lambda$  being an eigenvalue

and  $\vec{v}_1$  an eigenvector

$$e^{\lambda t} \text{ terms: } \underbrace{\vec{v}_1 + \lambda\vec{v}_2}_{\text{gives us } \vec{v}_2} = A\vec{v}_2$$

gives us  $\vec{v}_2$

$$(A - \lambda I)\vec{v}_2 = \vec{v}_1$$

also, from  $(A - \lambda I) \vec{v}_1 = \vec{v}_1$

multiply by  $A - \lambda I$  on both sides

$$(A - \lambda I)^2 \vec{v}_2 = (A - \lambda I) \vec{v}_1 = \vec{0} \quad \text{because } \vec{v}_1 \text{ is eigenvector}$$

so, there are two ways to find  $\vec{v}_2$

$$(A - \lambda I) \vec{v}_2 = \vec{v}_1$$

or

$$(A - \lambda I)^2 \vec{v}_2 = \vec{0}$$

revisit  $\vec{x}' = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \vec{x}$

$$\lambda = 1, 1 \quad \vec{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \text{1st solution: } e^{\lambda t} \vec{v}_1$$

$$2\text{nd } " \quad e^{\lambda t} (t \vec{v}_1 + \vec{v}_2)$$

let's find  $\vec{v}_2$  using  $(A - \lambda I) \vec{v}_2 = \vec{v}_1$

$$\left[ \begin{array}{cc} 0 & 1 \\ 0 & 0 \end{array} \right] \quad \left[ \begin{array}{c} 1 \\ 0 \end{array} \right]$$

$$b = 1 \quad a = r \quad \vec{v}_2 = \begin{bmatrix} r \\ 1 \end{bmatrix} = r \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

choose ANY  $r$   
here, choose  $r = 0$

$$\vec{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

1st solution:  $e^t \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

2nd solution:  $e^t (t \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix})$

general solution:

$$\vec{x} = c_1 e^t \begin{bmatrix} 1 \\ 0 \end{bmatrix} + c_2 e^t \left( t \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right)$$

second way to find  $\vec{v}_2$ :  $(A - \lambda I)^2 \vec{v}_2 = \vec{0}$

$$A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \quad \lambda = 1$$

$$A - \lambda I = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \quad (A - \lambda I)^2 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \\ = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$(A - \lambda I)^2 \vec{v}_2 = \vec{0}$$

$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \rightarrow \vec{v}_2$  is almost arbitrary

choose ANY  $\vec{v}_2$  EXCEPT  $(A - \lambda I) \vec{v}_2 = \vec{0}$   
basically, ANY  $\vec{v}_2$  that is linearly indep  
from the true eigenvector  $\vec{v}_1$

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

choose ANY  $\vec{v}_2$  indep from that

so, choose  $\vec{v}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  but  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$  is ok, too

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for  $3 \times 3$  matrix (or beyond  $3 \times 3$ ), the second way  
is better

in general, if we are missing  $n-1$  eigenvectors, then

$$(A - \lambda I)^n = \text{zero matrix}$$

so, choose the missing one from  $(A - \lambda I)^n \vec{v} = \vec{0}$   
then build the rest using  $(A - \lambda I) \vec{v}_n = \vec{v}_{n-1}$

example  $\vec{x}' = \begin{bmatrix} 2 & 0 & 0 \\ -4 & 6 & 4 \\ 0 & 0 & 2 \end{bmatrix} \vec{x}$

$$\lambda = 2, 2, 6 \quad \vec{v} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \text{ for } \lambda = 6$$

for  $\lambda = 2$ ,  $(A - \lambda I)\vec{v} = \vec{0}$

$$\begin{bmatrix} 0 & 0 & 0 & 0 \\ -4 & 4 & 4 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \quad \begin{array}{l} \text{two free variables} \\ \rightarrow \text{two eigenvectors} \end{array}$$

$$\vec{v} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

(good, A is complete)

solution is formed normally

$$\vec{x} = c_1 e^{6t} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c_2 e^{2t} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + c_3 e^{2t} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$