

4.2 Vector Space \mathbb{R}^n and Subspaces (continued)

vector space: a "space" that has the 8 fundamental properties from last time

Subspace: a part of a vector space (which is a vector space itself)

→ satisfies ALL 8 properties

all can be summarized as

1. closure under addition
2. closure under scalar multiplication
3. contains the zero vector

example

\mathbb{R}^2 is a subspace of \mathbb{R}^3

↳ xy-plane

↳ 3D coord. system

closure under addition means sum of two vectors from this space remains in the space

→ here, two vectors from xy-plane whose sum remains in the xy-plane

we show it this way:

let $\vec{u} = \begin{bmatrix} a \\ b \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} c \\ d \end{bmatrix}$ be two

\mathbb{R}^2 vectors

a, b, c, d reals

$$\vec{u} + \vec{v} = \begin{bmatrix} a+c \\ b+d \end{bmatrix} = \begin{bmatrix} e \\ f \end{bmatrix} \quad e, f \text{ are again, again, reals}$$

(sum of reals is real)

this shows closure under addition

closure under multiplication:

$$\vec{u} = \begin{bmatrix} a \\ b \end{bmatrix}$$

$$k\vec{u} = \begin{bmatrix} ka \\ kb \end{bmatrix}$$

k, a, b are reals
 $\rightarrow ka, kb$ also reals

clearly still in \mathbb{R}^2

(this shows closure)

last condition: $\vec{0}$ is in the space

$$\mathbb{R}^2: \vec{u} = \begin{bmatrix} a \\ b \end{bmatrix} \quad a, b \text{ reals}$$

so, $\vec{u} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ is also contained in
this space
(origin)
is part of xy -plane

ALL 3 conditions are true (all 8 fundamental
properties hold) so \mathbb{R}^2 is a subspace (and vector
space)

Example

W is a part of \mathbb{R}^3 such that $y = -1$

Is W a subspace?

a part of a vector space is NOT automatically a subspace!

— it must satisfy the three conditions

W contains vectors that look like

$$\begin{bmatrix} x \\ -1 \\ z \end{bmatrix}$$

x, z are reals

add two of them:

$$\begin{bmatrix} x_1 \\ -1 \\ z_1 \end{bmatrix} + \begin{bmatrix} x_2 \\ -1 \\ z_2 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 \\ -2 \\ z_1 + z_2 \end{bmatrix}$$

Since middle component is NOT -1 so sum of two is NOT in W anymore

so, NOT closed under addition

so W is NOT a subspace

a subspace we will frequently see is the null space

→ contains ALL solutions to $A\vec{x} = \vec{0}$

(all \vec{x} that get sent to $\vec{0}$)

example

$$x_1 - 4x_2 - 3x_3 - 7x_4 = 0$$

$$2x_1 - x_2 + x_3 + 7x_4 = 0$$

$$x_1 + 2x_2 + 3x_3 + 11x_4 = 0$$

$$\begin{bmatrix} 1 & -4 & -3 & -7 \\ 2 & -1 & 1 & 7 \\ 1 & 2 & 3 & 11 \end{bmatrix} \vec{x} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

A

$$\begin{bmatrix} 1 & -4 & -3 & -7 & 0 \\ 2 & -1 & 1 & 7 & 0 \\ 1 & 2 & 3 & 11 & 0 \end{bmatrix}$$

→ ... →

$$\begin{bmatrix} \boxed{1} & 0 & 1 & 5 & 0 \\ 0 & \boxed{1} & 1 & 3 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

0 zero \rightarrow free variables: $x_3 = r$
 $x_4 = t$

row 2: ... $\rightarrow x_2 = -r - 3t$

row 1: ... $\rightarrow x_1 = -r - 5t$

all \vec{x} such that $A\vec{x} = \vec{0}$ look like

$$\begin{bmatrix} -r - 5t \\ -r - 3t \\ r \\ t \end{bmatrix} = r \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -5 \\ -3 \\ 0 \\ 1 \end{bmatrix}$$

linear combo of $\begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} -5 \\ -3 \\ 0 \\ 1 \end{bmatrix}$

these are the "contents" of
null space of A

4.3 Linear Combus and Linear Independence

given $\vec{v}_1, \vec{v}_2, \vec{v}_3, \dots, \vec{v}_n$

linearly indep if and only if $c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_n\vec{v}_n = \vec{0}$

means $c_1 = c_2 = \dots = c_n = 0$

if we rewrite it this way:

\vec{v} as columns

$$\underbrace{\begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_n \end{bmatrix}}_A \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

if $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ are linearly indep, then

the only content of null space of A is $\begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \vec{0}$

if A is square, then $\det A \neq 0$ (A^{-1} exists)

but what if A is not square?

example $\vec{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ $\vec{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ $\vec{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ $\vec{v}_4 = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$

are they linearly indep?

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 2 \\ 1 & 0 & 1 & 3 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

we want $c_1 = c_2 = c_3 = c_4 = 0$ being the unique solution

↳ cannot have row of all zeros } free variables
or a variable column w/o pivot }

$$\begin{bmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 2 & 0 \\ 1 & 0 & 1 & 3 & 0 \end{bmatrix}$$

$x_1 \quad x_2 \quad x_3 \quad x_4$

$$\rightarrow \dots \rightarrow \begin{bmatrix} \boxed{1} & 0 & 0 & 1 & 0 \\ 0 & \boxed{1} & 0 & 2 & 0 \\ 0 & 0 & \boxed{1} & 2 & 0 \end{bmatrix}$$

3 pivots, 4 variables \rightarrow one free, solution NOT unique \rightarrow not linearly indep

if vectors have m components (\mathbb{R}^m vectors)
 and there are more than m of them in a set
 then at least one column will NOT have a pivot
 → as a set, these are NOT linearly indep.

but if there are m or fewer, then we can't
 immediately tell → reduce and count pivots

example $\vec{v}_1 = \begin{bmatrix} -1 \\ -17 \\ -3 \\ 9 \end{bmatrix}$ $\vec{v}_2 = \begin{bmatrix} 14 \\ 7 \\ 2 \\ -2 \end{bmatrix}$ $\vec{v}_3 = \begin{bmatrix} 15 \\ 5 \\ 1 \\ -2 \end{bmatrix}$

three \mathbb{R}^4 vectors, may or may not be indep.

$$\begin{bmatrix} -1 & 14 & 15 \\ -17 & 7 & 5 \\ -3 & 2 & 1 \\ 9 & -2 & -2 \end{bmatrix}$$

→ ... → $\begin{bmatrix} \boxed{-1} & 14 & 15 \\ 0 & \boxed{-231} & -250 \\ 0 & 0 & \boxed{1} \\ 0 & 0 & 0 \end{bmatrix}$

3 pivots, 3 vectors
 → no free variables
 despite
 zero row

Span: the things we can make w/ given vectors

example: $\vec{i} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ $\vec{j} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

using linear combos of \vec{i} , \vec{j} , we can make ~~every~~ every possible \mathbb{R}^2 vector

so we say \vec{i} and \vec{j} span \mathbb{R}^2

$$\text{span} \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} = \mathbb{R}^2$$

likewise, $\text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\} = \mathbb{R}^3$

but $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ along do NOT span \mathbb{R}^3

does $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ span \mathbb{R}^3 ?

yes, there is a redundant one \rightarrow not linearly indep

note we need a minimum of n vectors to span \mathbb{R}^n