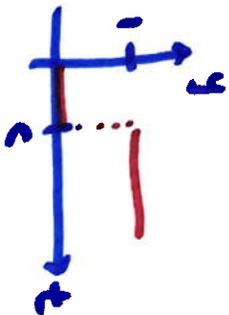


7.6 Impulse Functions

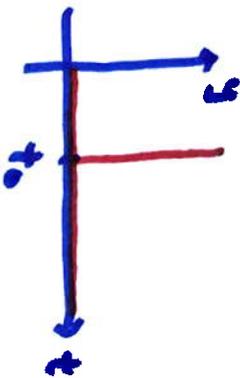
Step function: $u(t-c)$



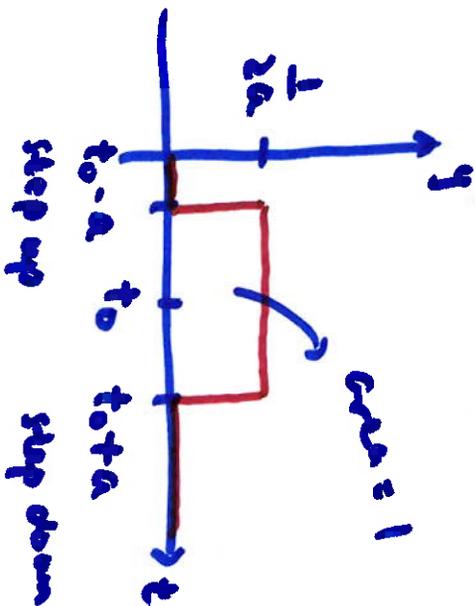
steps on once on

impulse function: very short acting input

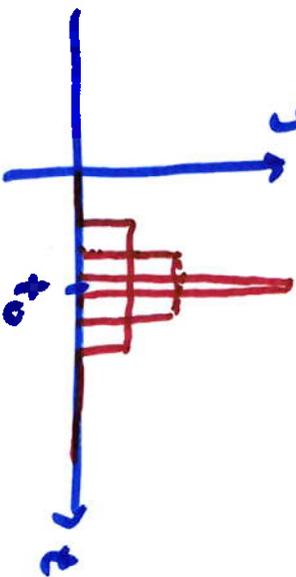
$\delta(t-t_0)$



we can construct impulses from step functions



→ impulse as $a \rightarrow 0$



impulse: $\delta(t-t_0) = \begin{cases} \infty & t=t_0 \\ 0 & t \neq t_0 \end{cases}$ and $\int_{-\infty}^{\infty} \delta(t-t_0) dt = 1$

$\mathcal{L}\{\delta(t-t_0)\} = ?$

$= \mathcal{L}\left\{\lim_{a \rightarrow 0} \left(\frac{1}{2a} u(t-t_0-a) - \frac{1}{2a} u(t-t_0+a)\right)\right\}$

$= \frac{1}{2a} \left(\lim_{a \rightarrow 0} \left(\int_{t_0-a}^{\infty} e^{-st} dt - \int_{t_0+a}^{\infty} e^{-st} dt \right) \right)$

$= \frac{1}{2a} \lim_{a \rightarrow 0} \left(-\frac{1}{s} e^{-st} \Big|_{t_0-a}^{\infty} + \frac{1}{s} e^{-st} \Big|_{t_0+a}^{\infty} \right)$

$= \lim_{a \rightarrow 0} \frac{1}{2a} \left(\frac{1}{s} e^{-(t_0-a)s} - \frac{1}{s} e^{-(t_0+a)s} \right)$

\vdots
 $= e^{-t_0 s}$
 $\mathcal{L}\{\delta(t-t_0)\} = e^{-t_0 s}$
 $\mathcal{L}\{u(t-t_0)\} = \frac{e^{-t_0 s}}{s}$

note if $t_0=0$ $\mathcal{L}\{\delta(t)\} = 1$

Example $x'' + x = 1 + \delta(t - \pi)$ $x(0) = x'(0) = 0$

take Laplace of both sides

$$[s^2 X - \cancel{s x(0)} - \cancel{x'(0)}] + X = \frac{1}{s} + e^{-\pi s}$$

$x(0)=0$ $x'(0)=0$

$$(s^2 + 1)X = \frac{1}{s} + e^{-\pi s}$$

$$X = \frac{1}{s(s^2+1)} + e^{-\pi s} \cdot \frac{1}{s^2+1}$$

$$\frac{1}{s} - \frac{s}{s^2+1}$$

inverse LT: first find $\mathcal{L}^{-1}\left\{\frac{1}{s^2+1}\right\} = \sin t$

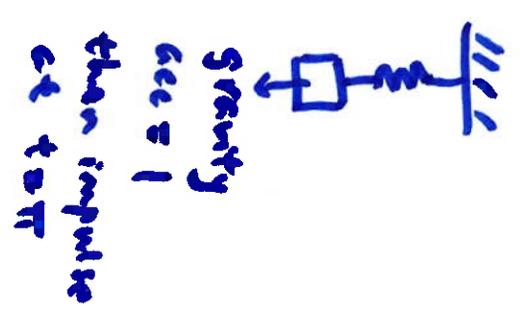
then $\sin(t) \rightarrow \sin(t - \pi)$
 note in t domain
 no impulse but step

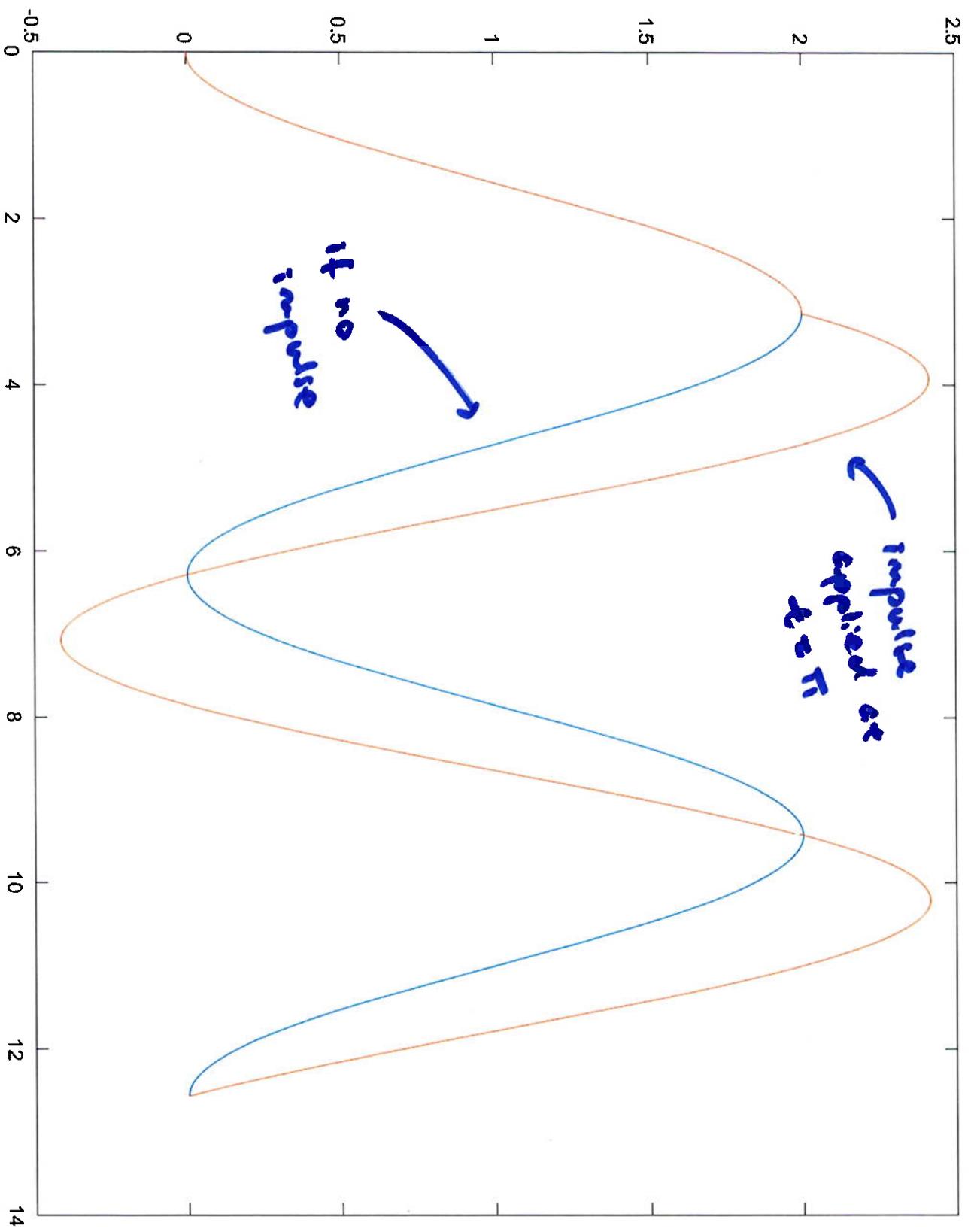
$-\sin t$

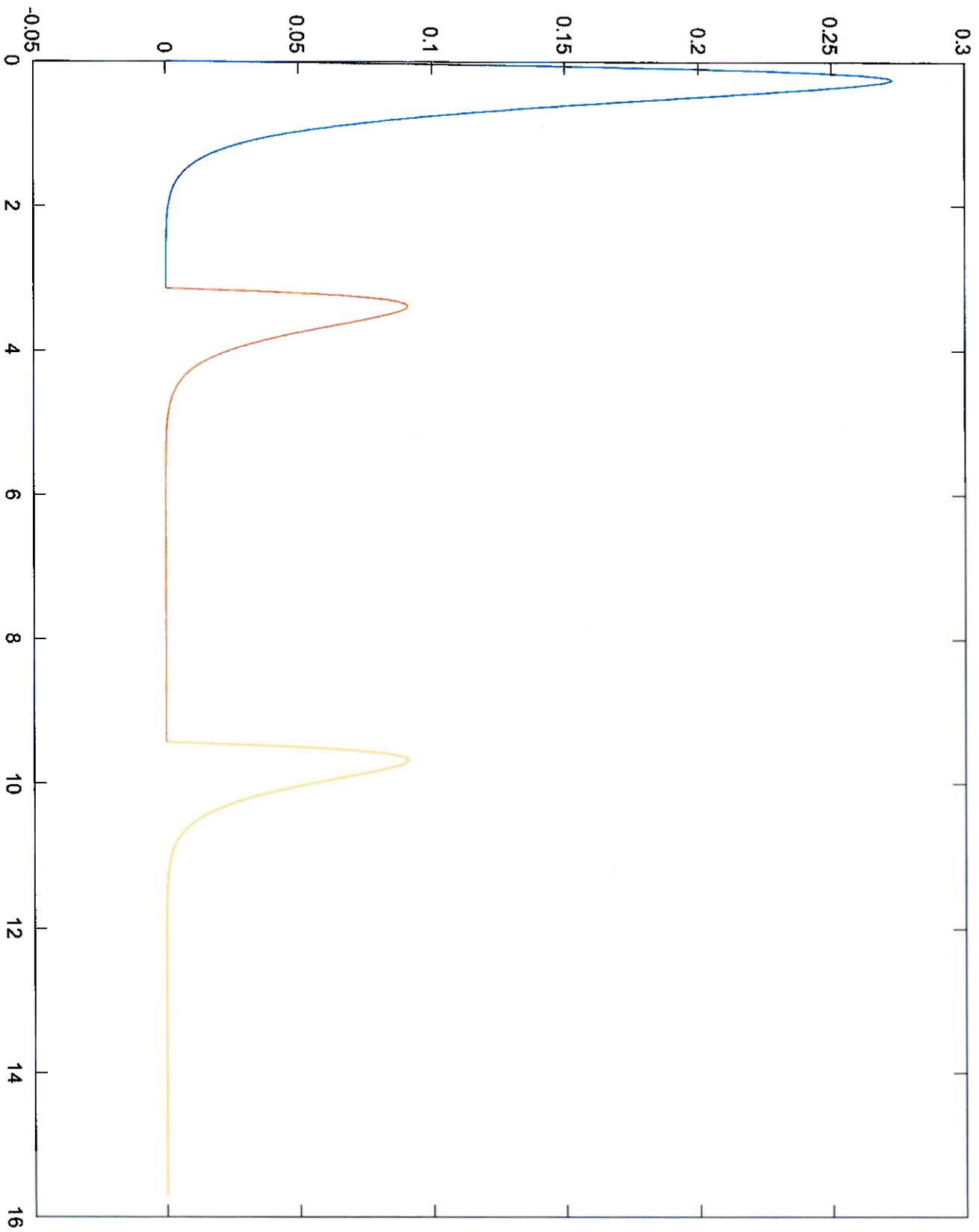
$$X(t) = 1 - \cos t + u(t - \pi) \sin(t - \pi)$$

$$= \boxed{1 - \cos t - u(t - \pi) \sin t}$$

$$= \begin{cases} 1 - \cos t & 0 \leq t < \pi \\ 1 - \cos t - \sin t & t \geq \pi \end{cases}$$







$$y'' + ay' + by = f(t)$$

assume $\mathcal{L}\{f(t)\} = F(s)$ exists

$$y(0) = y'(0) = 0$$

\downarrow
 \mathcal{L}

$$s^2 Y + a s Y + b Y = F$$

$$(s^2 + a s + b) Y = F$$

y : output of system

f : input

$$\frac{\text{output } Y}{\text{input } F} = \frac{1}{s^2 + a s + b}$$

from system parameters

"Transfer function"

→ impulse response of the system

solve w/o knowing $f(t)$

$$\mathcal{L}^{-1}\left\{ \underbrace{\mathcal{L}^{-1}\left\{ \frac{1}{s^2 + a s + b} \right\}}_{\mathcal{L}\{h(t)\}} \cdot \underbrace{F}_{\mathcal{L}\{f(t)\}} \right\} = \int_0^t h(t-\tau) f(\tau) d\tau = \int_0^t h(\tau) f(t-\tau) d\tau = y$$

this is looking at $f(t)$ as a
bunch of impulses

→ "Duhamel's principle"