

Corollary 3.22 Let  $F: M \rightarrow N$ ,  $G: N \rightarrow P$  be smooth.

(a)  $d(G \circ F) = dG \circ dF$

(b)  $d(\text{Id}_M) = \text{Id}_{TM}$

(c) If  $F$  is a diffeomorphism, then  $dF: TM \rightarrow TN$  is a diffeomorphism and

$$d(F^{-1}) = (dF)^{-1}.$$

## Lecture 4.1

Reading: Ch. 4

Practice: Ex. 4.3, 4.4, 4.7, 4.10

HW: 4-4

### Maps of Constant Rank

Def  $F: M^m \rightarrow N^n$  has constant rank  $r$  if  $\text{rank } dF_p = r$  for all  $p \in M$ .  $F$  has full rank if it has constant rank

$$r = \min\{m, n\}.$$

A full rank  $F$  is a submersion if its rank is  $n$ ; it is an immersion if its rank is  $m$ .

Equivalently:  $F: M \rightarrow N$  is a submersion if  $dF_p$  is surjective for all  $p \in M$ . It is an immersion if  $dF_p$  is injective for all  $p \in M$ .

Prop 4.1 Suppose  $F: M \rightarrow N$  smooth and  $p \in M$ . If  $dF_p$  is surjective, then  $F|_U$  is a submersion for some open  $U \ni p$ . If  $dF_p$  is injective, then  $F|_U$  is an immersion for some  $U \ni p$ .

Proof Picking coordinates  $(U, \varphi)^{(v, \psi)}$  gives a map

$$dF_-: U \rightarrow M(m \times n, \mathbb{R})$$

$$q \mapsto dF_q.$$

Since  $dF_-$  is continuous (in fact, smooth), and  $\{A \in M(m \times n, \mathbb{R}) \mid A \text{ has full rank}\}$  is open, we see that  $dF_q$  has full rank in some neighborhood of  $p$ .  $\square$

### Most important examples

1.  $\pi: \mathbb{R}^{n+k} \rightarrow \mathbb{R}^n$

$$(x^1, \dots, x^{n+k}) \mapsto (x^1, \dots, x^n)$$

is a submersion.

2.  $i: \mathbb{R}^n \rightarrow \mathbb{R}^{n+k}$

$$(x^1, \dots, x^n) \mapsto (x^1, \dots, x^n, 0, \dots, 0)$$

is an immersion.

The "rank theorem" says that all full rank smooth maps admit local coordinates that look like these.

### More examples

- $\gamma: J \rightarrow M$  a smooth curve is an immersion if and only if  $\gamma'(t) \neq \vec{0}$  for all  $t \in J$ .
- $\pi: TM \rightarrow M$  (natural projection) is a submersion.

Def  $F: M \rightarrow N$  is a local diffeomorphism if every  $p \in M$  has an open neighborhood  $U$  such that  $F(U)$  is open and  $F|_U: U \rightarrow F(U)$  is a diffeomorphism.

### Thm 4.5 (Inverse function theorem)

Suppose  $F: M \rightarrow N$  smooth and  $p \in M$  such that  $dF_p$  is invertible. Then there exist open neighborhoods  $U$  of  $p$  and  $V$  of  $F(p)$  such that  $F|_U: U \rightarrow V$  is a diffeomorphism.

Proof Use coordinates and apply inverse function theorem in  $\mathbb{R}^n$ . □

Prop 4.8 Suppose  $F: M \rightarrow N$  smooth.

- (a)  $F$  is a local diffeomorphism iff it is both a submersion and an immersion.
- (b) If  $\dim M = \dim N$  and  $F$  has full rank, then  $F$  is a local diffeomorphism.

Proof ... □

See Prop. 4.6 for a bunch of easy/useful properties of local diffeomorphisms.

## Rank theorem

More-or-less completely describes the local structure of smooth maps of constant rank.

Theorem Suppose  $F: M^m \rightarrow N^n$  smooth of constant rank  $r \leq \min\{m, n\}$ . For each  $p \in M$ , there exist coordinates  $(U, \psi)$  centered at  $p$  and  $(V, \varphi)$  centered at  $F(p)$  such that  $F(U) \subseteq V$  in which the coordinate representation of  $F$  is

$$F(x^1, \dots, x^r, x^{r+1}, \dots, x^m) = (x^1, \dots, x^r, \underbrace{0, \dots, 0}_{n-r}).$$

In particular, if  $F$  a submersion, have

$$F(x^1, \dots, x^r, x^{r+1}, \dots, x^m) = (x^1, \dots, x^r)$$

and if an immersion  $F(x^1, \dots, x^m) = (x^1, \dots, x^m, \underbrace{0, \dots, 0}_{n-m})$

We prove this Wednesday. For now:

Corollary Suppose  $M$  connected and  $F: M \rightarrow N$  smooth. TFAE:

(a) for each  $p \in M$ , there exist coordinates so that  $F$  is linear.

(b)  $F$  has constant rank.

Proof (a)  $\Rightarrow$  (b): Use connected and the assumption

(b)  $\Rightarrow$  (a) Use: rank theorem. □

## Lecture 4.2

Reading: Finish Ch. 4. Don't worry too much about section on covering maps.

Practice: 4.16, 4.24, 4.32

HW: 4-4, 4-7, 4-8.

Restate Rank Theorem.

Proof Three steps:

1. Preliminaries: reduce to a problem in  $\mathbb{R}^m$  and  $\mathbb{R}^n$  with some obvious conveniences.

2. Use IFT to find even nicer coordinates ~~where~~ on the domain where the ~~function~~ map looks like coordinate projection composed with inclusion into a graph.