

Corollary 8.39 Every Lie group admits a left-invariant <sup>smoothly</sup> global frame. In particular, every Lie group is parallelizable.

Also worth knowing

Thm 8.44 (roughly) If  $F: G \rightarrow H$  is a Lie group homomorphism, then <sup>each</sup> left  $G$ -invariant vector field on  $G$  is  $F$ -related to a unique left  $H$ -invariant vector field on  $H$ . In other words, get a Lie algebra homomorphism:

$$dF_e: \text{Lie}(G) = T_e G \rightarrow T_e H = \text{Lie}(H). \quad \square$$

## Lecture 8.2

Reading: First two sections of Ch. 9

Practice: 9.5

announcement: Out of town Friday. Rather have live Zoom class, or just <sup>pre-</sup>recorded?

## Integral curves

Def Let  $V$  be a vector field on  $M$ . An integral curve of  $V$  is a smooth curve  $\gamma: J \rightarrow M$  such that  $\gamma'(t) = V_{\gamma(t)}$  for all  $t \in J$ .



## 7 Examples

-  $M = \mathbb{R}^2$ ,  $V = \frac{\partial}{\partial x}$ . Every integral curve of form  
 $\gamma(t) = (t+a, b)$  for some  $(a, b) \in \mathbb{R}^2$ .

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-  $M = \mathbb{R}^2$ ,  $V = x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x}$ . Every integral curve  
looks like  $(a \cos t - b \sin t, a \sin t + b \cos t)$  for some  
 $(a, b) \in \mathbb{R}^2$ .

We call them "integral" curves because they  
are found by solving — or integrating — an  
autonomous system of ODEs, given initial conditions  
and coordinates. The existence of solutions to  
such (see Theorem D.1(a)) immediately implies

Prop 9.2 If  $V$  a smooth v.f. on  $M$  and  $p \in M$ ,  
then there exists an  $\varepsilon > 0$  and a smooth curve  
 $\gamma: (-\varepsilon, \varepsilon) \rightarrow M$  that is an integral curve of  $V$   
with  $\gamma(0) = p$ . □

Using full strength of Theorem D.1, we can do much  
better, addressing ~~with~~ "how big"  $\varepsilon$  can be taken,  
and how  $\gamma$  depends on  $p$ . Need more terminology  
e.g.  $\inf_{p \in M} \sup \varepsilon = 0$ ? first



# Flows

Def A <sup>(smooth)</sup> global flow on  $M$  is a <sup>(smooth)</sup> continuous map

$$\begin{aligned} \Theta: \mathbb{R} \times M &\rightarrow M \\ (t, p) &\mapsto \Theta(t, p) \end{aligned}$$

such that

$$- \Theta(t, \Theta(s, p)) = \Theta(t+s, p) \quad \forall t, s \in \mathbb{R}, \forall p \in M$$

$$- \Theta(0, p) = p \quad \forall p \in M.$$

(In other words, a flow on  $M$  is a continuous group action of  $\mathbb{R}$  on  $M$ .)

In each  $t \in \mathbb{R}$ , can define a diffeo.

$$\begin{aligned} \Theta_t: M &\rightarrow M \\ p &\mapsto \Theta(t, p). \end{aligned}$$

Note that  $\Theta_{t+s} = \Theta_t \circ \Theta_s$ .

For each  $p \in M$ , can define a curve

$$\begin{aligned} \Theta^{(p)}: \mathbb{R} &\rightarrow M \\ t &\mapsto \Theta(t, p). \end{aligned} \quad \text{Note that } \Theta^{(p)'}(0) \in T_p M$$

Prop 9.7 Let  $\Theta: \mathbb{R} \times M \rightarrow M$  be a smooth global flow. Then

$$V_p := \Theta^{(p)'}(0)$$

defines a smooth v.f. on  $M$  such that each curve  $\Theta^{(p)}$  is integral. Call  $V_p$  the infinitesimal



generator of  $\theta$ .

Proof To show  $V_p$  smooth, suffices to show

$\nabla F$  is smooth for any  $F \in C^\infty(M)$ .

$$\nabla F(p) = V_p F = \theta^{(p)'}(0)F = \left. \frac{d}{dt} \right|_{t=0} F(\theta^{(p)}(t))$$

$$= \left. \frac{d}{dt} \right|_{t=0} F(\theta(t, p))$$

Since  $F \circ \theta$  is smooth,  $\nabla F$  is smooth at  $p$ .

To show  $\theta^{(p)}$  is integral, consider need

$\theta^{(p)'}(t_0)$  to show that for each  $s \in \mathbb{R}$ ,  
 $\theta^{(p)'}(s) = \theta^{(q)'}(0)$ , where  $q = \theta^{(p)}(s)$ . Well,

~~$$\theta^{(p)}(t) = \theta(t, p) = \theta_t \theta_0(p) = \theta_t(q) =$$~~

$$\theta^{(q)}(t) = \theta(t, q) = \theta(t, \theta^{(p)}(s)) = \theta(t+s, p)$$

$$= \theta^{(p)}(t+s)$$

In particular,

$$\theta^{(q)'}(0) = \left. \frac{d}{dt} \right|_{t=0} \theta^{(p)}(t+s) = \theta^{(p)'}(s). \quad \square$$



## Examples

Each of the v.f.'s on  $\mathbb{R}^2$  given earlier is the infinitesimal generator of a global flow.

$$\tau: \mathbb{R} \times \mathbb{R}^2 \rightarrow \mathbb{R}^2 \\ (t, (x, y)) \mapsto (x+t, y)$$

$$\theta: \mathbb{R} \times \mathbb{R}^2 \rightarrow \mathbb{R}^2 \\ (t, (x, y)) \mapsto \begin{pmatrix} \cos t & -\sin t \\ \sin t & \cos t \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}.$$

Unfortunately, not every v.f. is the infinitesimal generator of a smooth global flow. Those that are are called complete v.f.'s, and <sup>always</sup> have integral curves defined for all  $t \in \mathbb{R}$  (i.e. can take  $\varepsilon = +\infty$  in Prop 9.2).

## Nonexamples

- Silly: let  $M = \mathbb{R}^2 - \{0\}$  and  $V = \frac{d}{dx}$  as

before.

- Less silly:  $M = \mathbb{R}$ ,  $V = x^2 \frac{d}{dx}$ . <sup>Any</sup> ~~unique~~ integral curve  $\gamma$  with  $\gamma(0) = 1$  is of form  $\gamma(t) = \frac{1}{1-t}$  for  $t \in J$  where  $J \subseteq (-\infty, 1)$ .

We can fix these issues by allowing for more general definition of flow.



Def a flow domain for  $M$  is an open subset  $\mathcal{D} \subseteq \mathbb{R} \times M$  such that for every  $p \in M$ , the set  $\mathcal{D}^{(p)} := \{t \in \mathbb{R} \mid (t, p) \in \mathcal{D}\} \subseteq \mathbb{R}$  is an open interval containing 0. A smooth flow on  $M$  is a continuous (smooth) map  $\theta: \mathcal{D} \rightarrow M$  such that

-  $\theta(0, p) = p \quad \forall p \in M$ , and

- for all  $s \in \mathcal{D}^{(p)}$ ,  $t \in \mathcal{D}^{(\theta(s, p))}$  such that  $s+t \in \mathcal{D}^{(p)}$ , have

$$\theta(t, \theta(s, p)) = \theta(t+s, p).$$

Exactly as before, can define for each  $p \in M$  and  $(t, p) \in \mathcal{D}$  integral curve

$$\theta_t(p) = \theta^{(p)}(t) = \theta(t, p).$$

and have

Prop 9.11 If  $\theta: \mathcal{D} \rightarrow M$  a smooth flow, then

$$V_p := \theta^{(p)'}(0)$$

is a smooth v.f. on  $M$  called the infinitesimal generator of  $\theta$ . Each  $\theta^{(p)}$  is an integral curve of  $V$ .



Def An <sup>smooth</sup> flow  $\theta: \mathcal{D} \rightarrow M$  is maximal if there does not exist a larger flow domain  $\tilde{\mathcal{D}} \supseteq \mathcal{D}$  and a <sup>smooth</sup> flow on  $\tilde{\mathcal{D}}$  extending  $\theta$ .

Thm 9.12 (Fundamental theorem on flows)

If  $V$  is a smooth v.f. on  $M$ , then there exists a unique maximal smooth flow on  $M$  whose infinitesimal generator ~~is~~ is  $V$ . We call this the flow generated by  $V$ . See book for more details, e.g. (9) for each  $p \in M$ ,  $\theta^{(p)}: \mathcal{D}^{(p)} \rightarrow M$  is unique maximal integral curve w/  $\theta^{(p)}(0) = p$ .

Ex What is the ~~maximal~~ domain of the flow on  ~~$\mathbb{R}$~~   $\mathbb{R} - \{0\}$  generated by  $V|_x = \frac{d}{dx}$ ?

Rather than prove this (proof uses full strength of Theorem D.1), let's note some situations that guarantee completeness: ~~By Lemma 9.16,~~ Note that  $V$  is complete iff  $\mathcal{D} = \mathbb{R} \times M$ .

Corollary 9.17 On a compact smooth manifold, every flow is complete.

Theorem 9.18 Every left-invariant v.f. on a Lie group is complete.



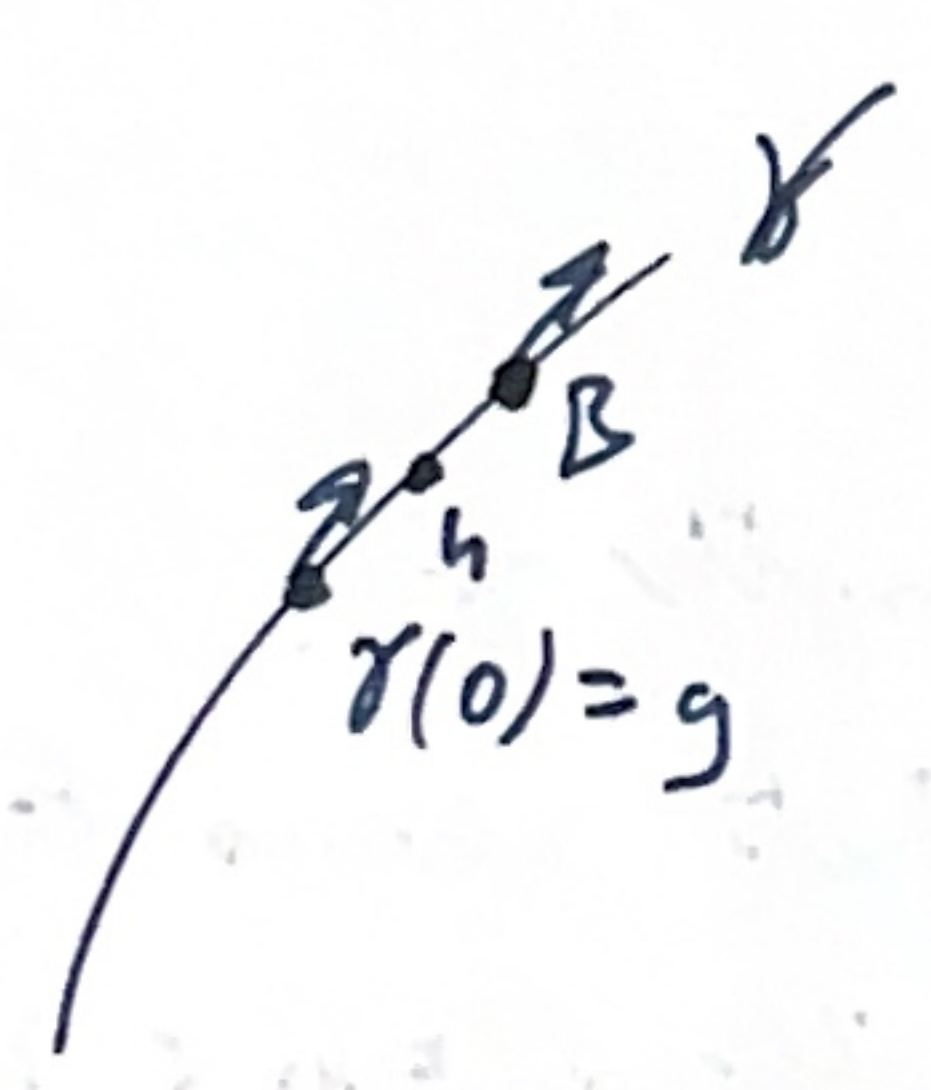
Proof Let  $X \in \text{Lie}(\mathfrak{G})$  and let  $\theta: \mathcal{D} \rightarrow \mathfrak{G}$   
~~be~~ be the flow generated by  $X$ . It suffices to  
 show that ~~if~~ ~~every~~ ~~integral~~ ~~curve~~  
~~can~~ ~~be~~ ~~taken~~ has domain  $\mathbb{R}$ . Suppose, by contradiction,  
 $\theta(g)$  is an <sup>maximal</sup> integral curve <sup>starting at  $g$</sup>  with domain  
 $J$  where  $\sup J = B < \infty$ . Now let us assume

~~$B \in \mathcal{D}$~~ . Define  ~~$\gamma = J + \epsilon$~~  let  $h = \theta(g)(\frac{B}{2})$ .  
~~By left invariance~~ of  $X$ ,  $\theta^{(h)}$  has maximal  
 domain  $J$ , too, (since

$$\gamma(t) := \begin{cases} \theta(g)(t) & t \in J \\ \theta(h) & t = B \end{cases}$$

$$\theta^{(h)} = L_h \cdot \theta(g)$$

But then



$$\gamma(t) := \begin{cases} \theta(g)(t) & \text{for } t \in J \\ \theta^{(h)}(t - \frac{B}{2}) & \text{for } t \in J + \frac{B}{2} \end{cases}$$

is also an integral curve starting at  $g$   
 with a larger domain of definition.  $\square$