

§1.4 The matrix equation $A\vec{x} = \vec{b}$.

matrix · vector = vector

$$x \begin{bmatrix} 2 \\ 1 \end{bmatrix} + y \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 8 \\ 22 \end{bmatrix}$$

$$x = -2, y = 12.$$

$$\begin{bmatrix} 8 \\ 22 \end{bmatrix} \in \text{Span} \left\{ \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$$

equiv
to a
system
of lin eqns

In fact, \downarrow is \mathbb{R}^2 .

Notation: matrix · vector

$$\begin{bmatrix} 2 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x \begin{bmatrix} 2 \\ 1 \end{bmatrix} + y \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_n \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1 \vec{v}_1 + \dots + x_n \vec{v}_n$$

$m \times n$ $n \times 1$ $m \times 1$

$\in \mathbb{R}^m$.

$$i \rightarrow \begin{bmatrix} 1 \\ \vdots \\ 0 \end{bmatrix} = \vec{e}_i \in \mathbb{R}^n \quad \vec{e}_1, \vec{e}_2, \dots, \vec{e}_n \in \mathbb{R}^n$$

\swarrow I or I_n (n x n) identity matrix

$$\begin{bmatrix} | & | & & | \\ \vec{e}_1 & \vec{e}_2 & \dots & \vec{e}_n \\ | & | & & | \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1 \vec{e}_1 + \dots + x_n \vec{e}_n$$

$$= x_1 \begin{bmatrix} 1 \\ \vdots \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ \vdots \\ 1 \end{bmatrix} + \dots + x_n \begin{bmatrix} 0 \\ \vdots \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} x_1 \\ \vdots \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ \vdots \\ x_2 \end{bmatrix} + \dots + \begin{bmatrix} 0 \\ \vdots \\ x_n \end{bmatrix}$$

$$= \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

$$I_n \vec{x} = \vec{x}$$

for $\vec{x} \in \mathbb{R}^n$.

$$\begin{cases} x + 2y + 3z = 1 \\ 4x + 5y + 6z = 2 \\ 7x + 8y + 9z = 3 \end{cases} \rightsquigarrow \left[\begin{array}{ccc|c} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & 2 \\ 7 & 8 & 9 & 3 \end{array} \right]$$

$$\begin{bmatrix} x + 2y + 3z \\ 4x + 5y + 6z \\ 7x + 8y + 9z \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$= x \begin{bmatrix} 1 \\ 4 \\ 7 \end{bmatrix} + y \begin{bmatrix} 2 \\ 5 \\ 8 \end{bmatrix} + z \begin{bmatrix} 3 \\ 6 \\ 9 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

↑ coeff matrix

↑ vector from constants

System of linear eqns

⇔ Solve for \vec{x} :
 $A\vec{x} = \vec{b}$

$[A | \vec{b}]$

Properties: 1) $A(\vec{v} + \vec{w}) = A\vec{v} + A\vec{w}$

2) $A(c\vec{v}) = c(A\vec{v})$

(Convention: Capital letters = matrices)

lower case $\vec{}$ = vector

lower case = ^{real} number (scalar)

Simple example:

$$[a_1 \dots a_n] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1 [a_1] + \dots + x_n [a_n]$$

$$= [x_1 a_1] + \dots + [x_n a_n]$$

$$= [x_1 a_1 + \dots + x_n a_n]$$

$$\vec{b} = A\vec{x}$$

$$\begin{bmatrix} b_i \end{bmatrix} = \begin{bmatrix} a_{i1} & a_{i2} & \dots & a_{in} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$\begin{aligned}
&= x_1 \begin{bmatrix} a_{i1} \end{bmatrix} + x_2 \begin{bmatrix} a_{i2} \end{bmatrix} + \dots + x_n \begin{bmatrix} a_{in} \end{bmatrix} \\
&= \begin{bmatrix} x_1 a_{i1} \end{bmatrix} + \begin{bmatrix} x_2 a_{i2} \end{bmatrix} + \dots + \begin{bmatrix} x_n a_{in} \end{bmatrix} \\
&= \begin{bmatrix} x_1 a_{i1} + \dots + x_n a_{in} \end{bmatrix}.
\end{aligned}$$

$$b_i = x_1 a_{i1} + \dots + x_n a_{in}.$$

$$\begin{aligned}
\begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} -2 \\ 12 \end{bmatrix} &= \begin{bmatrix} -2 \cdot 2 + 12 \cdot 1 \\ -2 \cdot 1 + 12 \cdot 2 \end{bmatrix} \\
&= \begin{bmatrix} 8 \\ 22 \end{bmatrix}.
\end{aligned}$$

Results:

Thm: $A\vec{x} = \vec{b}$ has a solution
if and only if (iff) \vec{b} is a

linear combination of the columns of A .

(ie \vec{b} is in the span of the columns of A)

Thm: Let A be an $m \times n$ matrix.

Then the following are equivalent (TFAE):

1) $A\vec{x} = \vec{b}$ has a solution for all $\vec{b} \in \mathbb{R}^m$.

$$\vec{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix}$$

2) Each $\vec{b} \in \mathbb{R}^m$ is a linear combo of the columns of A .

3) The span of the columns of A is \mathbb{R}^m .

4) A has a pivot position in each row.

1), 2), & 3) are equivalent
by definitions of $A\vec{x}$ and span.
Why are 1) & 4) equivalent?

If A has a pivot position in
every row, $\text{REF}(A)$ has no
row of 0's and so system is
always consistent.

If A does not have a pivot
position in a row, one can
find \vec{b} so that the augmented
matrix $[A|\vec{b}]$ corresponds to
an inconsistent system.

Indeed row reduce $[A|\vec{b}]$

$$\vec{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} \begin{array}{l} \leftarrow \text{treat} \\ \text{as} \\ \leftarrow \text{variables} \end{array}$$

$$[A | \vec{b}]$$

row
reduce

$$[0 \dots 0 | *]$$

$$* = c_1 b_1 + \dots + c_n b_n$$

for some numbers c_i .

Choose b_i so that $* \neq 0$

and system is inconsistent.