

Geometric Group Theory

(selected highlights of δ -hyperbolic groups)

- I Basic philosophy
- II Quasi-isometries, Milnor-Svarc (as Schwartz)
- III δ -hyperbolicity, quasi-geodesic stability
- IV The word problem for δ -hyperbolic groups (algorithmic properties of)
- V The Tits alternative for δ -hyperbolic groups (structure of subgroups of)
- VI A smorgasbord

I

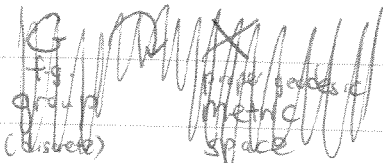


fig. group G (discrete)

properly discontinuously isometrically (cocompactly)

proper, geodesic metric space

closed balls are compact (\Leftrightarrow bdd, in the metric space case) prevents co-dim'l nonsense

various notions coincide for X locally cpt, Hausdorff:

(i) $\forall x \in X \exists U_x$ s.t. $\# \{g \in G \mid g \cdot x \in U\} < \infty$

$d(g \cdot x, g \cdot y) = d(x, y) \forall g \in G \forall x, y \in X$

X/G compact

(ii) $(g, X) \mapsto (x, g \cdot x)$ is proper

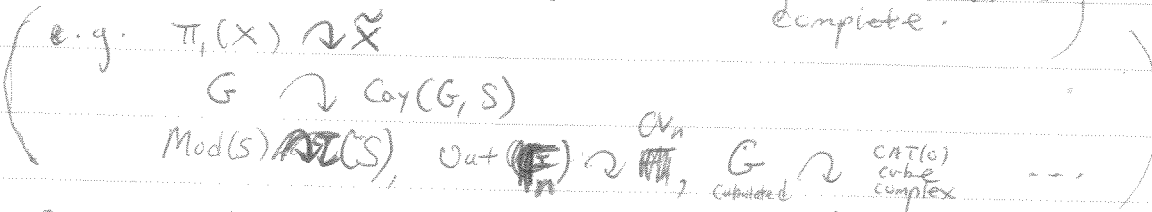
shortest paths exist / dista given by length of shortest path. Gives us a sensible notion of distance.

(iii) $\forall K \subset X$: $\# \{g \in G \mid gK \cap K \neq \emptyset\} < \infty$

POINT: $X \rightarrow X/G$ is a covering map, and X/G is Hausdorff

(Exercise) A Riemannian manifold is proper and geodesic \Leftrightarrow it is complete.

Prop $G \curvearrowright X \Rightarrow G$ f.g.
 Ideal of \mathbb{Z} Take $D = B_2$ dem $\delta = \{g \in G \mid g \cdot D \cap D \neq \emptyset\}$

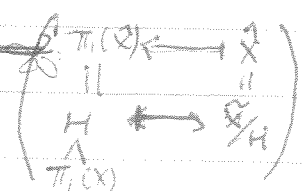


Basic philosophy Use geometry / topology of space to study properties of group, and vice versa.
 do this, we need some additional things

e.g. (topological group theory) ~~Thm $F_n = \pi_1(S_1 \vee \dots \vee S_1)$~~

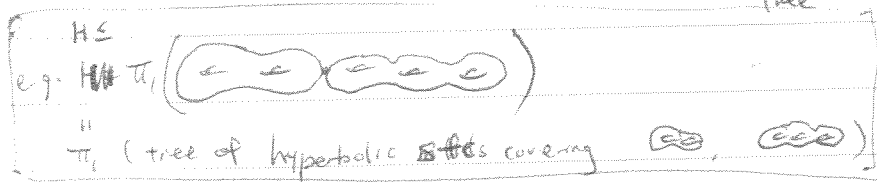
Thm Subgroups of free groups are free.

Sketch of pf $F_n \cong \pi_1(S_1 \vee \dots \vee S_1)$
 n circles



$H \leq F_n \Rightarrow H \cong \pi_1(\text{cover of } S_1 \vee \dots \vee S_1) = \pi_1(\text{quotient of } \infty \text{ 2n-valent tree}) = \pi_1(\text{graph}) = \text{free group}$

can generalize this: Kurosh Subgroup Thm $H \leq G_1 * G_2 \Rightarrow H = F *_{\text{NEC}} H_i$



each conjugate to subgroup of G_1 or G_2

II Groups as geometric objects: given G a f.g. group, S a finite generating set ($s^{-1} = s$)

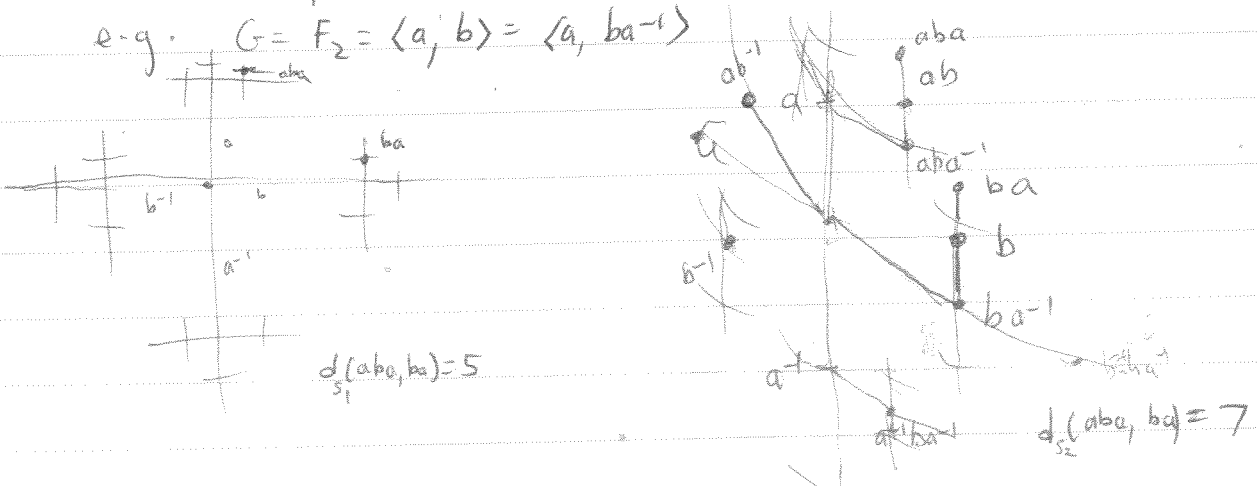
form Cayley graph $\text{Cay}(G, S)$ by:

- {vertices} = G
- $g-h$ is an edge $\iff \exists s \in S$ s.t. $gs = h$ (labelled s)

put word metric on $\text{Cay}(G, S)$ by declaring all edges to have length 1.

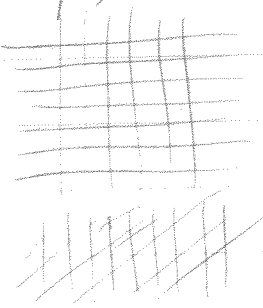
⚠ S not unique / canonical \Rightarrow no canonical word metric on G .

e.g. $G = F_2 = \langle a, b \rangle = \langle a, ba^{-1} \rangle$



BUT " $\text{Cay}(G)$ " / word metric on G is well-defined up to a natural equivalence relation (quasi-isometry)

Idea $\mathbb{Z}^2 = \langle a, b \mid [a, b] \rangle$

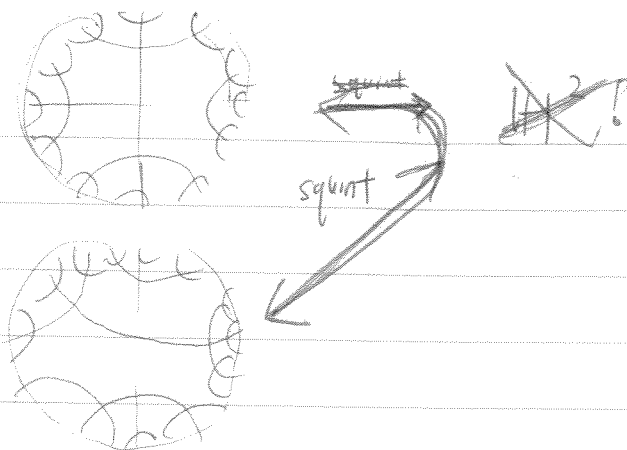


$= \langle b, ab \mid [a, ab] \rangle$

Squint

both kind of look like \mathbb{R}^2 .

or $\mathbb{F}_2 = \langle a, b \rangle$



Defn $h: X \rightarrow Y$ is a quasi-isometric embedding if $\exists k, c > 0$ s.t.
 $\frac{1}{k} d(x, z) - c \leq d(h(x), h(z)) \leq k d(x, z) + c \quad \forall x, z \in X$

h is a quasi-isometry ^{q.i.} if it is also coarsely surjective, i.e.
 $\exists D \geq c$ s.t. $\forall y \in Y: \exists x \in X$ s.t. $d(h(x), y) \leq D$.

e.g. $\text{Cay}(\mathbb{Z}^2, \{a, b\}) \hookrightarrow \mathbb{R}^2$ is a $(\sqrt{2}, \frac{1}{2})$ -quasi-isometry

$\text{Cay}(\mathbb{Z}^3, \{a, ab\}) \leftrightarrow \mathbb{R}^2$ is a $(2, \frac{\sqrt{2}}{2})$ -qi.

~~$\text{Cay}(\mathbb{F}_2, \{a, b\}) \leftrightarrow \mathbb{H}^2$ is a $(2 + \cos(\frac{\pi}{2}), \frac{1}{2})$ -qi~~

Prop A composition of q.i.s is a q.i.

Prop If $h: X \rightarrow Y$ is a q.i, then $\exists j: Y \rightarrow X$ a q.i s.t.

$\exists R \geq 0: d(j(h(x)), x) \leq R, d(h(j(y)), y) \leq R \quad \forall x \in X, y \in Y$.

j is called a quasi-inverse.

Pf idea Choose $j(y)$ to be (any) point in $h(X)$ closest to y .

UPSHOT quasi-isometry is an equivalence relation between ^(proper, geodesic) metric spaces

Prop. $\text{Cay}(G, S) \stackrel{q.i.}{\sim} \text{Cay}(G, S')$ for any two finite generating sets S, S' .

Pf Let $k_1 = \max$ word length of elt of S' in terms of S

~~$k_2 = \dots$~~

Map $s \in S$ onto geodesic path in $\text{Cay}(G, S')$. Then we have

$$d_S(g, h) \leq d_{S'}(g, h) \leq k_1 d_S(g, h)$$

$\frac{b_1}{b_2} \uparrow \downarrow$

Lemma (Milnor-Szarek) $G \curvearrowright X \Rightarrow G$ with any word metric is q_i to X .

(Cor. If $G \curvearrowright X$, $G \curvearrowright Y$, then $X \stackrel{q_i}{\sim} Y$.)

Pf We will prove the ^(any) orbit map is a q_i :

fix $x_0 \in X$, let $\tau: G \rightarrow X$ be given by $\tau(g) = g(x_0)$.

Extend this to a map $\text{Cay}(G, S) \rightarrow X$.

(By cocompactness) τ is coarsely $\text{diam}(X/G)$ -surjective.

To get upper bound $d(\tau(g), \tau(h)) \leq K d_S(g, h) + C$

Let $Q = \max_{s \in S} d(x_0, sx_0)$

$$d(\tau(h), \tau(hg)) = d(\tau(1), \tau(g)) \leq Q d_S(1, g) = Q d_S(h, hg)$$

$$\forall h, g \in G. \quad d(g, h) \leq K d(\tau(g), \tau(h)) + C$$

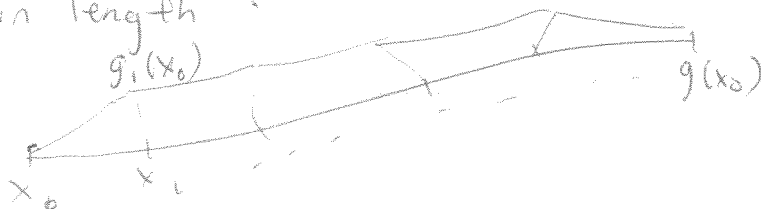
To get lower bound $d(\tau(g), \tau(h)) \geq \frac{1}{K} d(g, h) - C$ (✓)

write $D = \text{diam}(X/G)$. Let $S' = \{g \in G \mid d(x_0, gx_0) \leq 3D\}$, $P = \max_{s \in S'} C_S(1, s')$.

Will write any $g \in G$ as s . (Show any path from x_0 to $g \cdot x_0$ goes through

at least $\frac{d(x_0, gx_0)}{D}$ segments $\leq D$ in length.)

Divide geodesic $[x_0, g(x_0)]$ into $N := \lfloor \frac{d(x_0, gx_0)}{D} \rfloor + 1$ segments each $\leq D$ in length.



For each $i=1, \dots, N$, choose $g_i \in G$ s.t. $d(x_i, g_i(x_0)) \leq D$,

$$g_0 = \text{id}, \quad g_N = g.$$

$$\text{Then } d(g_i(x_0), g_{i+1}(x_0)) \leq 3D$$

$$d(x_0, g_i^{-1}g_{i+1}(x_0)) \leq 3D \Rightarrow g_i^{-1}g_{i+1} \in S'$$

$$g = g_0 (g_0^{-1}g_1) (g_1^{-1}g_2) (g_2^{-1}g_3) \dots (g_{N-1}^{-1}g_N)$$

$$d_S(1, g) \leq N P \leq P \left(\frac{d(x_0, gx_0)}{D} + 1 \right)$$

$$\Rightarrow \frac{D}{P} d_S(h, g) - D \leq d(x_0, gx_0)$$

III

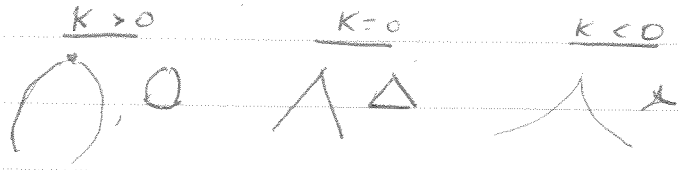
Recall: $\mathbb{R}P^2 \cong \mathbb{S}^2 / \sim$ $F_2 \cong \mathbb{H}^2$

(Milnor-Švarc) $\pi_1(\Sigma_g) \cong \mathbb{H}^2$
(g > 1)

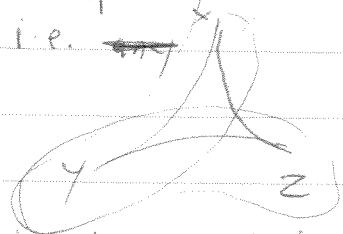
In geometry, negative curvature is often very useful.

What is the analogue of $K < 0$ here?

In Riemannian geometry:



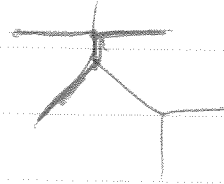
Def 2 (Gromov) X is δ -hyperbolic if geodesic triangles in X are δ -slim, i.e.



any point on \overline{xz} is in a δ -neighborhood of $\overline{xy} \cup \overline{yz}$.

(\Leftrightarrow) ϵ -thin, i.e. geodesic triangles are contained in ϵ -thickenings of corresponding tripod, but this is not the same def 2. For equivalence: exercise, or see Bridson and Haefliger, Chap III.H, Prop. 1.17.)

e.g. (metric) trees are 0-hyperbolic:



\mathbb{H}^2 is $\cosh^{-1}(2)$ -hyperbolic
 exercise! find best constant

Def 2 G is hyperbolic if it acts cocompactly on some δ -hyperbolic metric space.

e.g. $\pi_1(\Sigma_g) \curvearrowright \Sigma_g$, $F_n \curvearrowright$ tree, (all finite groups), ...

Morse Lemma (quasigeodesic stability)

Def 2 A (k, c) -quasigeodesic is the image of a geodesic under a (k, c) -q.l. (embedding)

Let $\gamma: [a, b] \rightarrow X$ be a (k, c) -quasigeodesic. Then $\exists D = D(k, c, \delta)$ s.t.

$$\delta([a, b]) \subset \mathcal{N}_D([\gamma(a), \gamma(b)]), \quad [\gamma(a), \gamma(b)] \subset \mathcal{N}_D(\delta([a, b]))$$



NOTE same is not true in $K \geq 0$!

also log spirals are quasigeodesics in \mathbb{E}^2 .



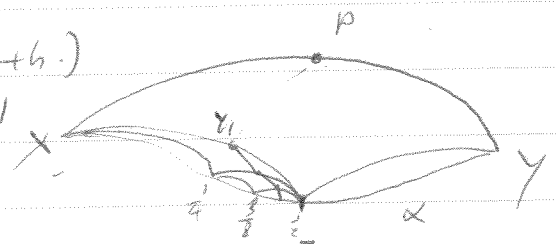
Pf ~~Lemma (Exponential divergence of geodesics)~~ ... even before that:
 (Technical Lemma) Arbitrary quasi-geodesics are $D' = D'(k, c)$ close to rectifiable (k', c') -quasi-geodesics, where $(k', c') = f(k, c)$.

Lemma (Exponential divergence of geodesics) X δ -hyperbolic,
 $p \in [x, y] \subset X$, $\alpha: [0, 1] \rightarrow X$ rectifiable path joining x to y . Then
 $d(p, \alpha([0, 1])) \leq \delta \log_2(\ell(\alpha)) + 1$.

Pf (Parametrize α prop. to arclength.)

choose $N \in \mathbb{N}$ s.t. $2^N \leq \ell(\alpha) < 2^{N+1}$

(so $1 \leq \ell(\alpha[\frac{k}{2^N}, \frac{k+1}{2^N}]) < 2$)



Consider geodesic $\Delta [x, y] \cup [x, \alpha(\frac{1}{2})] \cup [\alpha(\frac{1}{2}), y]$.

Pick $y_1 \in [x, \alpha(\frac{1}{2})]$ s.t. $d(p, y_1) < \delta$.

Consider $\Delta [x, \alpha(\frac{1}{2})] \cup [x, \alpha(\frac{1}{4}), \alpha(\frac{1}{2})]$

Pick $y_2 \in [\alpha(\frac{1}{4}), \alpha(\frac{1}{2})]$ s.t. $d(y_1, y_2) < \delta$

... continue until we get $y_N \in [\alpha(\frac{k}{2^N}), \alpha(\frac{k+1}{2^N})]$

s.t. $d(y_N, y_{N-1}) < \delta$.

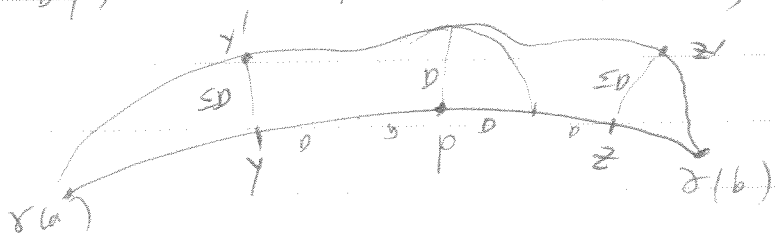
Then $d(p, \alpha([0, 1])) \leq d(p, y_N) + d(y_N, \alpha([0, 1]))$
 $< \delta N + 1$
 $\leq \delta \log_2(\ell(\alpha)) + 1$.

To show $\gamma([a, b]) \subset \mathcal{N}_D(\gamma(a), \gamma(b))$ for $D = D(k, c, \delta)$ the smallest D s.t. ... holds

Let $D =$ Hausdorff distance from $\gamma([a, b])$ to $[\gamma(a), \gamma(b)]$, holds

$p \in [\gamma(a), \gamma(b)]$ be s.t. $d(p, \gamma) = D$

~~$B_D(p)$~~ Pick $y, z \in (\gamma(a), \gamma(b))$, $y', z' \in \gamma([a, b])$ as shown



$d(y, y'), d(z, z') \leq D \Rightarrow d(y', z') \leq 6D$
 $\Rightarrow d(\gamma([y', z'])) \leq 6k'D + c'$

Exponential divergence of geodesics $\leq 6k'0 + c'$

$$d(p, red) = D \leq 8 \log_2 (6k'0 + c'4D) + 1$$

~~logs~~ logs are dominated by linears

\Rightarrow inequality only true up to some max $D = D(k, c, \delta)$.

To show $\mathcal{N}_D(\gamma[a, b]) \subset \mathcal{N}_D(\gamma[a', b'])$

Pick $q \in \gamma[a, b]$ maximizing $d(q, [\gamma(a), \gamma(b)])$,
let p be corresponding furthest point on $[\gamma(a), \gamma(b)]$.

If $D_q := d(q, p) \leq D_0$, done

Else: Choose $q_1, q_2 \in \gamma[a, b]$ s.t.

$d(q_1, q_2) \leq D_0$. Then γ btw q_1, q_2
has length $\leq k'D_0 + c'$

~~Choose p_1~~

Choose $p_1, p_2 \in [\gamma(a), \gamma(b)]$ s.t. $d(q_1, p_1), d(q_2, p_2), d(p_1, p_2) \leq D_0$
and $p \in p_1 p_2$.

Then $d(p_1, p_2) \leq 4D_0$, so $D_1 \leq 2D_0 + 2D_0 = 4D_0$.

Corollary δ -hyperbolicity is q_i -invariant (i.e. X δ -hyperbolic,
 $f: X \rightarrow Y$ a $q_i \Rightarrow Y$ δ' -hyperbolic (where $\delta' = \delta'(k, \delta, \delta)$.)

IV

Recall: X is δ -hyperbolic if it has δ -slim triangles
Def: A f.g. group G is δ -hyperbolic if it acts cocompactly
on some δ -hyperbolic space (WLOG, can take space to be $\text{Cay}(G, S)$)
e.g. $\pi_1(\Sigma_g) \curvearrowright \Sigma_g$, $F_n \curvearrowright$ tree, (all finite groups), \dots
 $\text{Mod}(S) \curvearrowright \mathcal{C}(S)$
 $\text{Out}(F_n) \curvearrowright \mathcal{PT}_n$

Why: δ -hyperbolic groups have good algorithmic properties
e.g. • word problem solvable in linear time (are automatic)
• conjugacy problem solvable (have decidable marked isomorphism)

Word problem Given $G = \langle S \mid R \rangle$, w a word in elems of S ,
decide if $w \sim id_G$

One way to solve this Defn A finite presentation $\Gamma = \langle S; R \rangle$ is a
Dehn presentation if whenever w is a word in S s.t.
 $w \sim id_G$, \exists subword w_0 of w which is "more than $\frac{1}{2}$ a relator"
e.g. $\left(\begin{array}{l} aba^{-1}b^{-1} \text{ relator} \\ aba^{-1} \end{array} \right) > \frac{1}{2}$ $\left(\begin{array}{l} bcab^{-1} \text{ relator} \\ bca \end{array} \right)$ more than half

i.e. \exists word w_0 s.t. $l(w_0) < l(w)$, $w_0 w_0 \in R$.

Prop. If G has a Dehn presentation, then ^{the} word problem in G
is solvable in linear time

Pf Consider the algorithm:
(1) Given w , search w for subwords which are $> \frac{1}{2}$ a relator

(2) If none, $w \sim id_G$.

(3) Else! have w_0 s.t. $v_0 w_0 \in R$, $l(w_0) < l(w)$
Write $w = aw_0b \sim av_0^{-1}b =: w'$. $l(w') < l(w)$.

(4) If $w' = id$, win. Else, repeat.

This terminates in $\leq l(w)$ steps.

(linear in length of word)
* implied constant/s depend on #relators, length of relators, performance of substring search.

Thm Hyperbolic groups have Dehn presentations.
(In particular, they are finitely presented, and have solvable word problem)

Pf Let A be any finite generating set, R be
 R be $\{ \text{words } w \text{ with } w \sim id_G, l(w) < 16\delta + 2 \}$.

We claim $\langle A \mid R \rangle$ is a Dehn presentation.

Key Lemma (Defn) A k -local geodesic is a path $\alpha: [a, b] \rightarrow X$
s.t. $s, t \in [a, b]$ with $|s-t| < k \Rightarrow \alpha|_{[s, t]}$ geodesic.

(NOTE: not necessarily geodesics, e.g.  is a $(\frac{k}{2})$ -local geodesic)

If $k > 8\delta$, then ~~non-constant~~ k -local geodesics in X are not closed loops.

Let $z \sim id$ be a word in A . By Key Lemma, z is not a $(8\delta+1)$ -local geodesic
(a closed loop based at $id_G \in Cay(G, A)$)

$\Rightarrow \exists$ subword z_0 of length $\leq 8\delta + 1$ which is not a geodesic.
 Let z_0' be a geodesic joining endpoints of z_0 . $l(z_0') < l(z_0)$

Now $z_0(z_0')^{-1} \sim id$, $l(z_0(z_0')^{-1}) < 2(8\delta + 1) = 16\delta + 2$

$\Rightarrow z_0(z_0')^{-1} \in R$

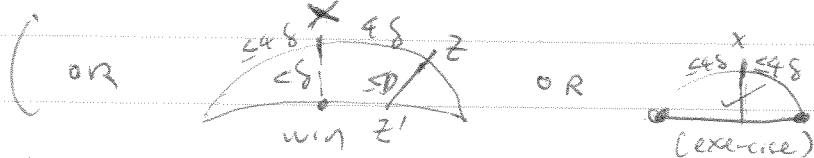
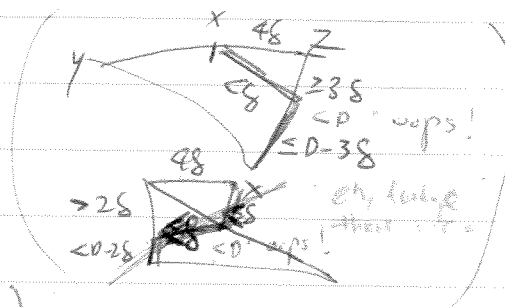
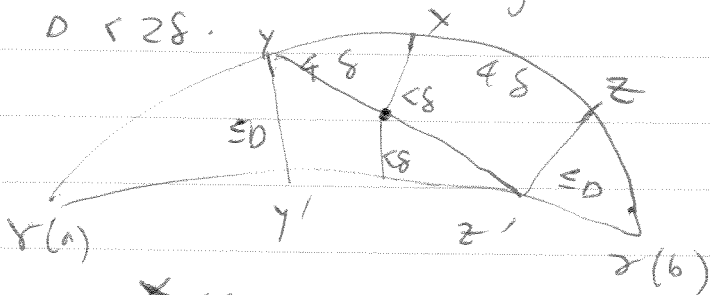
$\Rightarrow z$ has a subword which is $> \frac{1}{2}$ a relator in R \square

Sketch of PF of Lemma ~~1.1~~ (1) ~~a~~ a k -local geodesic

$\Rightarrow \gamma([a, b]) \subset N_{2\delta}(\gamma(a), \gamma(b))$.

Choose $x \in \gamma([a, b])$ maximizing $D := d(x, [\gamma(a), \gamma(b)])$.

WTS $D \leq 2\delta$.



(In fact, $[\gamma(a), \gamma(b)] \subset N_{2\delta}(\gamma([a, b]))$)

γ is a $(\frac{k+4\delta}{k-4\delta}, 2\delta)$ -quasigeodesic

[" k -local geodesics make roughly linear progress"]

(2) If $|a-b| \leq k$, γ a geodesic \Rightarrow not a nontrivial closed loop

(3) Else (if $|a-b| \geq k > 8\delta$) $\gamma|_{[a, a+4\delta]}$ is a geodesic, so $d(\gamma(a), \gamma(a+4\delta)) = 4\delta$

But if γ were a closed loop, then $N_{2\delta}([\gamma(a), \gamma(b)]) = B_{2\delta}(\gamma(a))$
 in γ $\gamma(a+4\delta) \notin B_{2\delta}(\gamma(a))$

Remark • Conjugacy problem solvable for δ -hyperbolic groups, ~~etc also~~
 • they contain finitely many conjugacy classes of finite-order
 elts — this can also be proven using Dehn presentations.

Remark In fact, G has a Dehn presentation iff it is δ -hyperbolic.

Suggested reading for Fri, if you haven't seen hyperbolic
 geometry before.

V What can we say abt so far $G \curvearrowright X$; δ -hyperbolic spaces and groups;

δ -hyperbolic groups have good algorithmic properties.

Today Subgroups of δ -hyperbolic groups satisfy the Tits Alternative



Thm G δ -hyperbolic, $\Gamma \leq G \Rightarrow$ OOTFH

- (1) Γ virtually cyclic
- (2) Γ contains a free group of rank 2

(cf. Thm (Tits, 1970s) $\Gamma \leq SL_2(\mathbb{R})$, ~~not~~ OOTFH: (1) Γ virtually solvable; (2) $\Gamma \geq F_2$.)

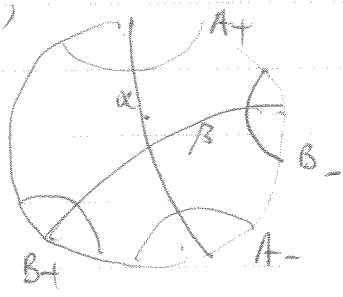
(Outline of) Proof

For $(PSL_2 \mathbb{R} \cong \text{Isom}(\mathbb{H}^2))$:

- (1) Any $\gamma \in PSL_2 \mathbb{R}$ is conjugate to one of
 - "hyperbolic" (a) $\begin{pmatrix} \lambda & 0 \\ 0 & \lambda^{-1} \end{pmatrix}, \lambda > 1$ — fixes pair of points in $\partial \mathbb{H}^2$ (axis) — translates along geodesic between them by $2 \log \lambda$ — "north-south dynamics"
 - repelling 
 - attracting fixed pt
 - "parabolic" (b) $\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ — fixes point in $\partial \mathbb{H}^2$, flowlines are horocycles
 - 
 - "elliptic" (c) $\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$ — fixes point in \mathbb{H}^2

(2) Lemma If Γ contains 2 hyperbolic elements with distinct fixed point sets, then $\Gamma \geq F_2$.

Idea of Pf Ping-pong



$$\alpha((A^\pm)^c) \subset A^\mp$$

$$\beta((B^\pm)^c) \subset B^\mp$$

(3) If $\Gamma \not\geq F_2$ such hyperbolics, shog and get virtual solvability.

FOR δ -hyperbolic groups

δ -hyperbolic

① To get similar classification of elts of $\text{Isom}(X)$, we will develop notion of $\partial_\infty X$:

Defn $\partial_\infty X$ (the Gromov boundary or visual boundary of X) is defined as $\{ \text{quasigeodesic (by Morse lemma) geodesic rays} \} / \text{bdd Hausdorff distance}$

with topology of convergence $([\alpha_n] \rightarrow [\alpha] \stackrel{\text{def}}{\iff} X_n \rightarrow X \in \partial_\infty X)$,
geodesic segment \uparrow geodesic ray
in compact-open topology

and closed sets in $\bar{X} = X \cup \partial_\infty X$ contain all of their limit points.

(or defined using basis $\{B(x, r) \subset X\} \cup \{x \in \bar{X} \mid d(x, c_0) > r, d(p \cdot (x), c(r)) < \epsilon\}$)

Key properties

• Visibility: ① $\forall p \in X, z \in \partial_\infty X: \exists$ geodesic ray α s.t. $[\alpha] = z, \alpha(0) = p$

ingredients
 Key in proof: Arzelà-Ascoli, δ -hyperbolicity

② If $z_1 \neq z_2 \in \partial_\infty X, \exists$ geodesic $\gamma: \mathbb{R} \rightarrow X$ s.t. $[\gamma|_{[0, \infty)}] = z_1, [\gamma|_{(-\infty, 0]}] = z_2$.

not new unique!

• Bordification: $X \cup \partial_\infty X$ is compact.

• Extension of maps: $f: X \rightarrow Y$ q_i extends to $\partial f: \partial_\infty X \rightarrow \partial_\infty Y$

(Conditions: $\partial_\infty \Gamma$ well-defined for Γ a δ -hyperbolic group) a. b. Lipschitz homeo (given by $\partial f([\alpha]) = [f \circ \alpha]$)

~~Chore~~ Now we can classify our isometries: -

Defn An isometry of X is -

• ... elliptic if some orbit $\{\gamma^n(x_0)\}$ is bounded

• ... parabolic if some orbit $\{\gamma^n(x_0)\}$ has exactly one accumulation point

• ... hyperbolic if $n \mapsto \gamma^n(x_0)$ is a q -l embedding for some (and hence all) x_0 .

~~(q, l, p, v, i, s)~~ other we can take γ instead -

Fact δ not elliptic or parabolic $\Rightarrow \delta$ hyperbolic, exhibits NS dynamics on \bar{X} , i.e. \exists fixed points $\partial_{\pm} \delta \in \partial_{\infty} X$ s.t. $\delta^n(z) \rightarrow \partial_{\pm} \delta$ $\forall z \in \bar{X} \setminus \{\partial_{\mp} \delta\}$, uniformly on compact subsets of $\bar{X} \setminus \{\partial_{\mp} \delta\}$.

(Lemma If $\{\delta^n(z_0)\}$ accumulates at $a \in \partial_{\infty} X$, then $\partial \delta(a) = a$.)

Fact δ hyperbolic $\Rightarrow \exists m > 0$ s.t. δ^m has an invariant geodesic axis (not necessarily unique) ($\uparrow m \geq 1$, possibly, for same reason)

Proofs involve lots of sequences / convergence arguments, quasigeodesic stability and δ -slim triangles.

$\frac{1}{\sqrt{5}}$

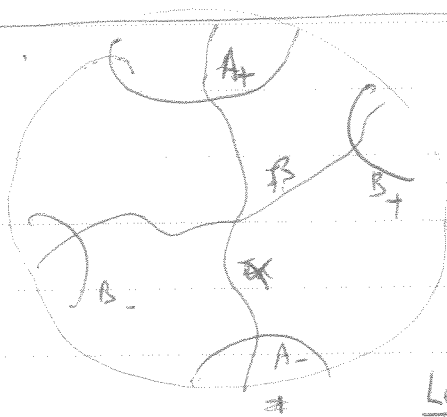
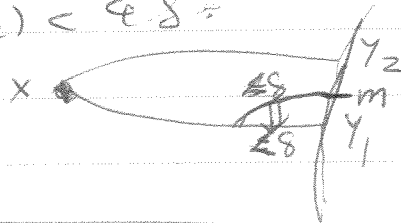
(2) δ -Hyperbolic ping-pong.

Lemma Given Γ δ -hyperbolic, $\gamma_1, \gamma_2 \in \Gamma$ hyperbolic w/ distinct fixed point sets (in $\partial_{\infty} \Gamma$). Then $\exists N > 0$ s.t. $\langle \gamma_1^N, \gamma_2^N \rangle \cong F_2$.

Proof Lemma (Projection onto geodesics is coarsely well-behaved in Shyp. spaces)

Given $I \subset X$ geodesic Shyp, $x \in X$ and $y_1, y_2 \in I$ s.t. $d(y_1, x) = d(y_2, x) = d(x, I)$, we have $d(y_1, y_2) < 4\delta$.

Sketch of Pf



Define $A_{\pm} := \{x \in \text{Cay}(\Gamma) \mid \exists t_i \in \mathbb{R} : d(x, \partial_{\pm}) = d(x, \alpha(t_i))\}$
i.e. x projects to \mathbb{R} part of invariant axis

sim. $A_{-} := \{x \in \text{Cay}(\Gamma) \mid \exists t_i < -R : d(x, \alpha) = d(x, \alpha(t_i))\}$
and for B_{\pm}

Lemma $\Rightarrow R > 4\delta$ suffices to separate A_{\pm} .

To separate A_{\pm} from B_{\pm} : let $\hat{\rho} = \max \{d(\alpha(0), 1), d(\beta(0), 1)\}$
such ρ exists by Shyp. $\rho > 0$ be s.t. $[\alpha, \beta] \cap B_{\rho}(0) \neq \emptyset$
whenever $\alpha \in A, \beta \in B$



Choose $R > 2\rho + 2\hat{\rho} + 4\delta$.

Then:

Claim All ∞ -order elts of Γ share both fixed points $\Rightarrow \Gamma$ virtually cyclic

PF WLOG (up to an index-2 subgroup) Γ preserves fixed points.

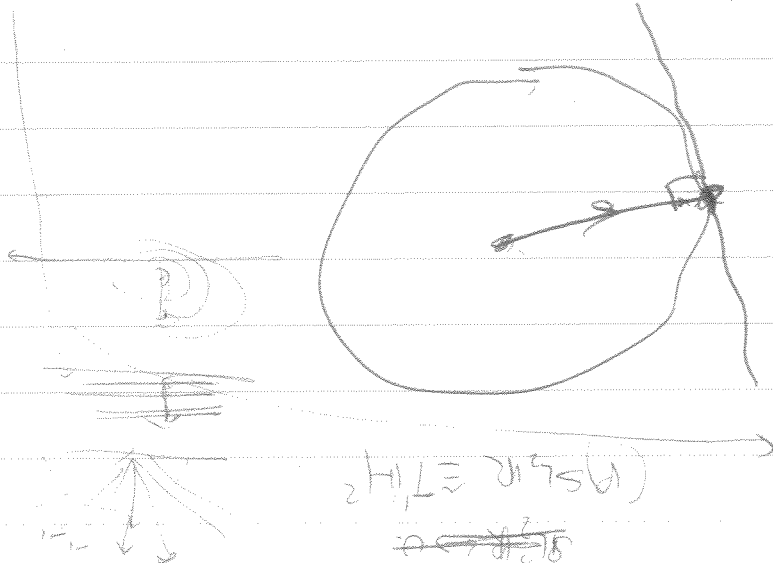
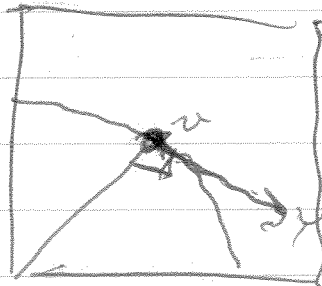
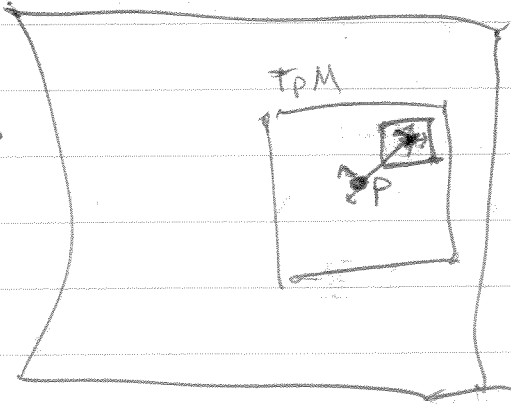
(idea) \exists finitely many ^(say, 8) possible invariant axes; take $\phi: \Gamma \rightarrow S_n$
 and $\Gamma_1 = \ker \phi$. This is a f.i.i. subgroup of Γ ,
 and cyclic since $\Gamma_1 \curvearrowright \mathbb{R}^2$ freely, properly.

(idea for pf of previous claim: consider conjugates $\alpha^{-n} \beta \alpha^n$. These $\xrightarrow{\text{wlog}} \beta$
 as $n \rightarrow \infty$, so there are finitely many choices for $\alpha^{-n} \beta \alpha^n$; but this
 implies $\alpha^n \in Z(\langle \beta \rangle) = \text{cyclic}$, i.e. $\alpha^n = \beta^m$ virtually $\exists N, m: \alpha^N = \beta^m$)

V
 From Dynamics
 in Houston.

Alex
 Blumenthal \rightarrow

Yon



(PSLR $\cong \mathbb{Z}^2$)

~~PSLR $\cong \mathbb{Z}^2$~~

geodesic flow

\mathbb{R}

\cong

\mathbb{T}^2

$$\begin{pmatrix} 2/3 \cos \theta & 2/3 \sin \theta \\ 2/3 \sin \theta & 2/3 \cos \theta \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ x & 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ 2 & 1 \end{pmatrix}$$



~~AMS~~ Beyond δ -hyperbolic groups

- CAT(0) groups: $G \curvearrowright X$
 - Thm (Agol, Wise) G hyperbolic, cubulated $\Rightarrow G$ virtually embeds in RAAG
 - Thm (Haglund-Wise, Kahn-Markovic) $\pi_1(M_{hyp})$ for M a closed hyperbolic 3-manifold is cubulated
- CAT(0) a slightly different generalization of KSO
- \Rightarrow Virtually Haken Thm.

- Groups from topology / geometry, e.g. $Mod(S) \supset Teich(S) \supset COB$

- Growth, divergence, isoperimetric functions ^(Serre)

Bromov's theorem on groups of polynomial growth

G has polynomial growth IFF it is virtually nilpotent.

• ...

5
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