

- Last time: Vector Spaces

Vector Subspaces of vector spaces

Linear Combinations, Span, Spanning set

Ex1: Consider the set of all linear transformations  $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ .  
Can you equip it naturally with a vector space structure?  
What is the zero vector?

Ex2: Given any fixed matrices  $X \in \text{Mat}_{m \times m}$  and  $Y \in \text{Mat}_{n \times n}$ , consider a subset  $\{A \in \text{Mat}_{m \times n} \mid X \cdot A \cdot Y = 0\}$  of  $\text{Mat}_{m \times n}$ .  
Is it a vector subspace of  $\text{Mat}_{m \times n}$ ?

→ Yes. ← discuss

Ex3: a) Is a subset  $\{A \in \text{Mat}_{m \times n} \mid \text{columns are lin. independent}\}$  of  $\text{Mat}_{m \times n}$ , actually a vector subspace?

b) Is a subset  $\{A \in \text{Mat}_{m \times n} \mid \text{columns are lin. dependent}\}$  of  $\text{Mat}_{m \times n}$ , actually a vector subspace?

→ a) No      ← discuss  
b) No

- Discuss § 4.2 following pages 4-5 of Lecture 13 Notes

## Lecture #14

### § 4.3 Linearly independent sets ; Bases

Similarly to the case of  $\mathbb{R}^n$ , we make the following definition

Def: An indexed set of vectors  $\{\vec{v}_1, \dots, \vec{v}_k\}$  in a vector space  $V$  is said to be linearly independent if the vector equation

$$c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_k\vec{v}_k = \vec{0}$$

has only the trivial solution  $c_1 = c_2 = \dots = c_k = 0$

Otherwise, the set  $\{\vec{v}_1, \dots, \vec{v}_k\}$  is said to be linearly dependent

Similarly to the discussion for  $\mathbb{R}^n$ , we have

CLAIM: A set  $\{\vec{v}_1, \dots, \vec{v}_k\}$  ( $k \geq 2$ ) with  $\vec{v}_1 \neq \vec{0}$  is linearly dependent

iff some  $\vec{v}_j$  (with  $1 < j \leq k$ ) is a linear combination of  $\vec{v}_1, \dots, \vec{v}_{j-1}$ .

Q: When a set  $\{\vec{v}_1\}$  is linearly dependent? ← only when  $\vec{v}_1 = \vec{0}$ .

Ex 4: a) Is the set  $\{(1, 1), (2, 3), (0, 1)\}$  of  $\text{Mat}_{2 \times 2}$  linearly independent?

b) Is the set  $\{t^2 - 1, 2t + 3, 5\}$  of  $\mathbb{P}_2$  linearly independent?

c) Is the set  $\{1, \cos t, \sin(t^2), 0, e^t\}$  of  $C(\mathbb{R})$  linearly indep?

► a) No, as  $(-2) \cdot (1, 1) + 1 \cdot (2, 3) + (-1) \cdot (0, 1) = \vec{0}$

b) Yes: if  $\underbrace{a(t^2 - 1) + b(2t + 3) + c \cdot 5 = 0}_{at^2 - a + 2bt + 3b + 5c = 0}$ , then  $a = 0, b = 0, 5c - a + 3b = 0 \Rightarrow c = 0$ .

c) No: it contains 0, e.g.  $1 \cdot 0 = 0$ .

Def: Let  $H$  be a subspace of a vector space  $V$ . A set of vectors  $B$  in  $V$  is a basis for  $H$  if

1)  $B$  is lin. indep. set

2)  $H = \text{Span } B$ , i.e. subspace spanned by  $B$  coincides with  $H$ .

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Ex 5: Verify that

a)  $\{1, x, x^2, \dots, x^n\}$  is a basis for  $\mathbb{P}_n$ .

b)  $\{1, x^2, x^4, \dots, x^{2\lfloor \frac{n}{2} \rfloor}\}$  is a basis for the subspace of "even polynomials" in  $\mathbb{P}_n$ .

c)  $\{E_{ij} = \begin{pmatrix} 0 & \dots & 0 & 1 & 0 & \dots & 0 \\ \vdots & & & \end{pmatrix} \}_{\substack{i \in \{1, \dots, n\} \\ j \in \{1, \dots, n\}}}$  - a basis for  $\text{Mat}_{n \times n}$ .

Ex 6: 1) Find a basis of the subspace of symmetric matrices in  $\text{Mat}_{n \times n}$ .  
2) Find a basis of the subspace of skew-symm. matrices in  $\text{Mat}_{n \times n}$ .

Ex 7: Evoking Ex 4a), find a basis of  $\text{Span}\left\{\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 0 & 2 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}\right\}$  in  $\text{Mat}_{2 \times 2}$ .

As  $\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = -2 \cdot \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} + \begin{pmatrix} 2 & 3 \\ 0 & 2 \end{pmatrix}$ , any element in  $\text{Span}\left\{\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 0 & 2 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}\right\}$  also belongs to  $\text{Span}\left\{\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 0 & 2 \end{pmatrix}\right\}$ .

On the other hand, we claim that the set  $\left\{\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 0 & 2 \end{pmatrix}\right\}$  is lin. indep., since if  $a \cdot \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} + b \cdot \begin{pmatrix} 2 & 3 \\ 0 & 2 \end{pmatrix} = 0 \Rightarrow \begin{cases} a+2b=0 \\ a+3b=0 \end{cases} \Rightarrow a=b=0$ .

So:  $\left\{\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 2 & 3 \\ 0 & 2 \end{pmatrix}\right\}$  - a basis of the above  $\text{Span}$ .

Note: We could also use the same argument to prove that

$\left\{\begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}\right\}$  or  $\left\{\begin{pmatrix} 2 & 3 \\ 0 & 2 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}\right\}$  - also bases.

Based on the same ideas, one proves the following result!

CLAIM: Let  $S = \{\vec{v}_1, \dots, \vec{v}_k\}$  be a set of vectors in a vector space  $V$ .

Let  $H$  be the span of  $\{\vec{v}_1, \dots, \vec{v}_k\}$ , i.e.  $H = \text{Span}\{\vec{v}_1, \dots, \vec{v}_k\}$

a) If one of the vectors in  $S$ , say  $\vec{v}_j$ , is a linear combination of the remaining els in  $S$ , then the set formed from  $S$  by removing  $\vec{v}_j$  still spans  $H$ .

b) If  $H \neq \{\vec{0}\}$ , some subset of  $S$  is a basis for  $H$ .

## Lecture #14

Warning: Each non-zero subspace has infinitely many bases.  
So, the previous claim just provides some of those!

Recall our previous discussions from §2.8, 2.9, where we explicitly described how to find a basis of  $\text{Nel } A$ ,  $\text{Col } A$  for a given  $m \times n$  matrix  $A$ .

Q: How to find a basis of  $\text{Row } A$ ?

Clearly, the elementary row operations do not change  $\text{Row } A$  (unlike  $\text{Col } A$ ), hence, we get:

CLAIM: A set of non-zero rows in an echelon form of  $A$  is a basis for  $\text{Row } A$ .