

Lecture # 18

- Last time
- Characteristic equation, characteristic polynomial
 - multiplicity of eigenvalues
 - Similarity transformation $A \mapsto P^{-1}AP$
 - Diagonalizable square matrices ($A = PDP^{-1}$, D -diagonal)

Ex 1: Is $A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$ diagonalizable?

Char. polynomial of A is $(1-\lambda)^4 \Rightarrow$ only eigenvalue $\lambda=1$ (multiplicity=4)
 If A was diagonalizable, i.e. $A = PDP^{-1}$ with D -diagonal, then char. pol. of D should be the same, i.e. $(1-\lambda)^4$. But as D -diagonal, this implies all diagonal entries of D are 1.
 Hence, $D = I_4 \Rightarrow PDP^{-1} = P \cdot I_4 \cdot P^{-1} = I_4 \neq A \Rightarrow$ Contradiction!

So: A is not diagonalizable. ■

Last time, we also had the following two claims at the very end:

Claim: An $n \times n$ matrix A is diagonalizable iff A has n linearly independent eigenvectors

Claim: We have $A = PDP^{-1}$ with D -diagonal iff the columns of P are n linearly indep. eigenvectors of A , while the diagonal entries of D are the corresponding eigenvalues

Def: Given an $n \times n$ matrix A , a basis of \mathbb{R}^n consisting of eigenvectors of A is called an eigenvector basis of \mathbb{R}^n .

Combining 1st claim with lin. indep. of eigenvectors for different eigenvalues, get:

Claim: An $n \times n$ matrix with n distinct eigenvalues is diagonalizable.

Lecture #18

Ex2: Diagonalize the matrix $A = \begin{pmatrix} 2 & 1 \\ 0 & 3 \end{pmatrix}$, if possible.

Step 1: Find eigenvalues.

A -triangular \Rightarrow eigenvalues are $\lambda = 2, 3$.

Step 2: Find lin. ind. eigenvectors

$\lambda = 2$: $A - 2I_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$: $\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} y \\ 0 \end{pmatrix} \Rightarrow$ eigenvectors are $\begin{pmatrix} a \\ 0 \end{pmatrix}$

Can take $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$.

$\lambda = 3$: $A - 3I_2 = \begin{pmatrix} -1 & 1 \\ 0 & 0 \end{pmatrix}$: $\begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} -x+y \\ 0 \end{pmatrix} \Rightarrow$ eigenvectors are $\begin{pmatrix} a \\ a \end{pmatrix}$.

Can take $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

Step 3: Construct P from above eigenvectors.

$$P = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

Step 4: Construct D from eigenvalues

$$D = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$$

Sol: $\begin{pmatrix} 2 & 1 \\ 0 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix} \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}^{-1}$ \leftarrow This was used in Ex7 in Lecture #17

Q: Can someone suggest an alternative proof of Ex 1?

Step 1: $\lambda = 1$ - the only eigenvalue

$$A - \lambda I_4 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} : \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \mapsto \begin{pmatrix} x_2 \\ 0 \\ x_4 \\ 0 \end{pmatrix} \Rightarrow \text{eigenspace} = \left\{ \begin{pmatrix} * \\ 0 \\ * \\ 0 \end{pmatrix} \right\} - 2\text{-dim}$$

\Rightarrow can not pick an eigenbasis!

Lecture #18

Ex 3: Diagonalize the matrix $A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 1 \\ 0 & 0 & 0 & 4 \end{pmatrix}$, if possible.

Step 1: Find eigenvalues.

$$\lambda = 1, 2, 3, 4.$$

Step 2: Find eigenvectors.

$$\lambda = 1 \Rightarrow A - \lambda I_4 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 3 \end{pmatrix} : \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \mapsto \begin{pmatrix} x_2 \\ x_2 \\ 2x_3 + x_4 \\ 3x_4 \end{pmatrix} - \text{vanishes} \\ \text{iff } x_2 = x_3 = x_4 = 0$$

$$\text{Can take } \vec{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\lambda = 2 \Rightarrow A - \lambda I_4 = \begin{pmatrix} -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 2 \end{pmatrix} : \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \mapsto \begin{pmatrix} -x_1 + x_2 \\ 0 \\ x_3 + x_4 \\ 2x_4 \end{pmatrix} - \text{vanishes} \\ \text{iff } x_1 = x_2 \text{ \& } x_3 = x_4 = 0$$

$$\text{Can take } \vec{v}_2 = \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$

$$\lambda = 3 \Rightarrow A - \lambda I_4 = \begin{pmatrix} -2 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix} : \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \mapsto \begin{pmatrix} -2x_1 + x_2 \\ x_2 \\ x_4 \\ x_4 \end{pmatrix} - \text{vanishes} \\ \text{iff } x_1 = x_2 = x_4 = 0$$

$$\text{Can take } \vec{v}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$\lambda = 4 \Rightarrow A - \lambda I_4 = \begin{pmatrix} -3 & 1 & 0 & 0 \\ 0 & -2 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} : \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} \mapsto \begin{pmatrix} -3x_1 + x_2 \\ -2x_2 \\ -x_3 + x_4 \\ 0 \end{pmatrix} - \text{vanishes} \\ \text{iff } x_1 = x_2 = 0 \text{ \& } x_3 = x_4$$

$$\text{Can take } \vec{v}_4 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix}$$

Step 3: Construct P

$$P = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Step 4: Construct D

$$D = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 4 \end{pmatrix}$$

Lecture #18

Let us conclude this discussion with the following criteria when a square matrix with less than n distinct eigenvalues is diagonalizable:

Claim: Let A be an $n \times n$ matrix with distinct eigenvalues $\lambda_1, \dots, \lambda_k$.

- 1) The dimension of the eigenspace for λ_j ($1 \leq j \leq k$) is at most the multiplicity of the eigenvalue λ_j .
- 2) A is diagonalizable iff
 - the characteristic polynomial factors into linear factors
 - AND
 - the dimension of the eigenspace for each λ_j equals exactly the multiplicity of λ_j .
- 3) If 2) holds, and B_j is a basis for the eigenspace corresponding to λ_j for each $1 \leq j \leq k$, then the union of all B_j ($1 \leq j \leq k$) forms an eigenvector basis for \mathbb{R}^n .

Lecture #18

§ 5.4 Eigenvectors and linear transformations

Let's generalize the above discussion, by replacing:

- \mathbb{R}^n with a general vector space V
- $n \times n$ matrix A with a linear transformation $T: V \rightarrow V$.

Def: Let V be a vector space. An eigenvector of a linear transf. $T: V \rightarrow V$ is a nonzero $\vec{v} \in V$ such that $T(\vec{v}) = \lambda \cdot \vec{v}$ for some scalar λ , called an eigenvalue of T .

Examples: 1) $V = \mathcal{C}^1(\mathbb{R})$, $T: f(x) \mapsto f'(x)$ - linear operator.
differentiable f 's

Then: $f(x) = e^{\lambda x}$ is an eigenvector with eigenvalue λ .

2) $V = \mathbb{S}$, $T: (\dots, y_{-2}, y_{-1}, y_0, y_1, y_2, \dots) \mapsto (\dots, y_{-1}, y_0, y_1, y_2, \dots)$

Then: $(\dots, \frac{1}{\lambda^2}, \frac{1}{\lambda}, 1, \lambda, \lambda^2, \dots) \in \mathbb{S}$ is an eigenvector with eigenvalue λ .

Ex 4: Find all eigenvalues of $T: \mathbb{P}_n \rightarrow \mathbb{P}_n$ defined via $p(x) \mapsto p'(x)$.

▶ If $p(x)$ is a degree $k \geq 1$ polynomial, then $p'(x)$ is a degree $k-1$ polynomial. Hence, it may not happen that $p'(x) = \lambda \cdot p(x)$ unless $p(x)$ is a degree 0 polynomial, i.e. $p(x) = p_0$ - constant. Then $p'(x) = 0 = 0 \cdot p(x)$.

So: The only eigenvalue is $\lambda = 0$.

Lecture #18

For the rest of today, we assume V to be fin. dimensional!

Choose a basis $B = \{\vec{b}_1, \dots, \vec{b}_n\}$ of V . Then, for any $\vec{x} \in V$, recall the coordinate vector $[\vec{x}]_B \in \mathbb{R}^n$ defined as $\begin{pmatrix} r_1 \\ \vdots \\ r_n \end{pmatrix}$ with $\vec{x} = r_1 \vec{b}_1 + \dots + r_n \vec{b}_n$.

We also have $[T(\vec{x})]_B \in \mathbb{R}^n$.

Q: What is the exact relation b/w $[\vec{x}]_B$ and $[T(\vec{x})]_B$?

$$\text{If } [\vec{x}]_B = \begin{pmatrix} r_1 \\ \vdots \\ r_n \end{pmatrix} \Rightarrow \vec{x} = r_1 \vec{b}_1 + \dots + r_n \vec{b}_n \Rightarrow T(\vec{x}) = r_1 T(\vec{b}_1) + \dots + r_n T(\vec{b}_n)$$

$$\Rightarrow [T(\vec{x})]_B = r_1 [T(\vec{b}_1)]_B + \dots + r_n [T(\vec{b}_n)]_B = M \cdot [\vec{x}]_B,$$

where M is an $n \times n$ matrix given by $M = \left([T(\vec{b}_1)]_B \quad \dots \quad [T(\vec{b}_n)]_B \right)$

matrix for T relative to the basis B
also denoted $[T]_B$.

Ex5: In the setup of Ex4, determine $[T]_B$, where $B = \{1, x, x^2, \dots, x^n\}$.

$$[T]_B = \begin{pmatrix} 0 & 1 & & & \\ & 0 & 2 & & \\ & & 0 & 3 & \\ & & & \ddots & \ddots \\ & & & & 0 & n \\ & & & & & 0 \end{pmatrix} \begin{matrix} \uparrow \\ \vdots \\ \downarrow \\ \leftarrow \\ \rightarrow \\ \downarrow \\ \leftarrow \\ \rightarrow \end{matrix} \begin{matrix} n+1 \\ n+1 \end{matrix}$$

In the particular case $V = \mathbb{R}^n$, we have a natural identification b/w $\{\text{linear transformations } \mathbb{R}^n \rightarrow \mathbb{R}^n\}$ and $\{n \times n \text{ matrices}\}$.

In particular, our previous discussion yields:

Claim: Suppose $A = PDP^{-1}$, P -invertible $n \times n$ matrix, D -diagonal $n \times n$ matrix.
If B is the basis for \mathbb{R}^n formed by the columns of P ,
then D is the B -matrix for the transformation $\vec{x} \mapsto A\vec{x}$.

Lecture #18

More generally, if A & C are similar, i.e.

$$A = PCP^{-1}$$

then C is the B -matrix for the transformation $\vec{x} \mapsto A\vec{x}$ when the basis B is formed by the columns of P .

! The converse is also true.

So, we get:

Claim: The set of all matrices similar to $A \in \text{Mat}_{n \times n}$ coincides with the set of all matrix representations of the linear transformation $\vec{x} \mapsto A\vec{x}$.

Important Technical Remark !!!

To compute $P^{-1}AP$, one does not need actually to evaluate P^{-1} .

Instead:

1) Compute $A \cdot P$

2) Row reduce $[P \mid AP]$ to $[I_n \mid P^{-1}AP]$