

Lecture #3

- Last time → Vectors, \mathbb{R}^n
 - ↳ Linear combinations, Span of a collection of vectors

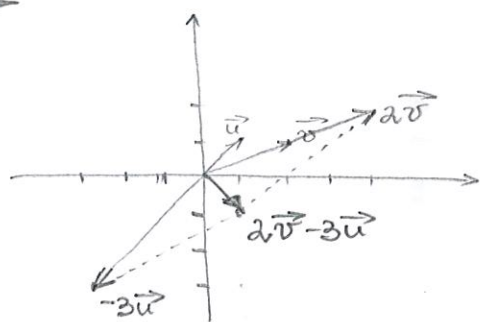
Recall: 1) Addition and scalar multiplication are done coordinate-wise

Warning: NOT TO CONFUSE with dot or cross products!

2) All vectors in this course are column vectors, i.e. we write them as a single column, which is NOT the same as a single row.
E.g. $\begin{bmatrix} 1 \\ 2 \end{bmatrix} \neq [1 \ 2]$

3) Given a vector $\begin{pmatrix} a \\ b \end{pmatrix} \in \mathbb{R}^2$ we can identify it with a point in the plane.
—||— $\begin{pmatrix} a \\ b \\ c \end{pmatrix} \in \mathbb{R}^3$ —||— a point in the space.

Ex 1: Given $\vec{u} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, $\vec{v} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$, visualize vectors $2\vec{v}$, $-3\vec{u}$, and $2\vec{v} - 3\vec{u}$.



$$\left. \begin{aligned} 2\vec{v} &= \begin{pmatrix} 4 \\ 2 \end{pmatrix} \\ -3\vec{u} &= \begin{pmatrix} -3 \\ -3 \end{pmatrix} \end{aligned} \right\} \Rightarrow 2\vec{v} - 3\vec{u} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

Note: All those vectors from above (i.e. $2\vec{v}$, $-3\vec{u}$, $2\vec{v} - 3\vec{u}$) are clearly linear combinations of \vec{u} , \vec{v} (i.e. belong to $\text{Span}\{\vec{u}, \vec{v}\}$).

Q: What about $\vec{0}$?

↳ $\vec{0} \in \text{Span}\{\vec{u}, \vec{v}\}$ as $\vec{0} = 0 \cdot \vec{u} + 0 \cdot \vec{v}$

! We also did a bunch of True/False exproumpt problems - see last page

Warning: Given vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k \in \mathbb{R}^n$, the notation $\{\vec{v}_1, \dots, \vec{v}_k\}$ just denotes this collection, while $\text{Span}\{\vec{v}_1, \dots, \vec{v}_k\}$ denotes their span.

For example: $\begin{pmatrix} 1 \\ 1 \end{pmatrix} \notin \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$ BUT $\begin{pmatrix} 1 \\ 1 \end{pmatrix} \in \text{Span}\left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$.

Ex 2: Given two nonzero vectors $\vec{v}_1, \vec{v}_2 \in \mathbb{R}^3$, describe what $\text{Span}\{\vec{v}_1, \vec{v}_2\}$ looks like.

↳ If \vec{v}_1 and \vec{v}_2 are proportional to each other, then $\text{Span}\{\vec{v}_1, \vec{v}_2\}$ is a line passing through the origin.
Otherwise, $\text{Span}\{\vec{v}_1, \vec{v}_2\}$ is a plane passing through the origin. ①

The next exercise will allow us to relate vector equations

$$x_1 \vec{v}_1 + x_2 \vec{v}_2 + \dots + x_k \vec{v}_k = \vec{w}$$

to linear systems discussed in Lecture 1.

Ex 3: Let $\vec{v}_1 = \begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix}$, $\vec{v}_2 = \begin{pmatrix} -2 \\ 1 \\ 4 \end{pmatrix}$, $\vec{w} = \begin{pmatrix} -4 \\ 9 \\ 8 \end{pmatrix}$

Determine if \vec{w} belongs to $\text{Span}\{\vec{v}_1, \vec{v}_2\}$.

another way to phrase: is \vec{w} a linear combination of \vec{v}_1, \vec{v}_2 .

Using the definition of scalar multiplication and vector addition, this boils down to the question if there are scalars x_1, x_2 such that

$$x_1 \begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix} + x_2 \begin{pmatrix} -2 \\ 1 \\ 4 \end{pmatrix} = \begin{pmatrix} -4 \\ 9 \\ 8 \end{pmatrix} \text{ or equivalently } \begin{pmatrix} x_1 - 2x_2 \\ 3x_1 + x_2 \\ -2x_1 + 4x_2 \end{pmatrix} = \begin{pmatrix} -4 \\ 9 \\ 8 \end{pmatrix}.$$

Hence, we need to verify if the linear system $\begin{cases} x_1 - 2x_2 = -4 \\ 3x_1 + x_2 = 9 \\ -2x_1 + 4x_2 = 8 \end{cases}$ is consistent or not.

Augmented matrix: $\left(\begin{array}{cc|c} 1 & -2 & -4 \\ 3 & 1 & 9 \\ -2 & 4 & 8 \end{array} \right) \xrightarrow[R_3+2R_1]{R_2-3R_1} \left(\begin{array}{cc|c} 1 & -2 & -4 \\ 0 & 7 & 21 \\ 0 & 0 & 0 \end{array} \right) \xrightarrow{\frac{1}{7}R_2} \left(\begin{array}{cc|c} 1 & -2 & -4 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{array} \right)$

encodes linear system $\begin{cases} x_1 = 2 \\ x_2 = 3 \\ 0 = 0 \end{cases} \leftarrow \left(\begin{array}{cc|c} 1 & 0 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{array} \right)$

Thus, there is a unique solution: $x_1=2, x_2=3$.

Answer: Yes! (moreover, $\vec{w} = 2\vec{v}_1 + 3\vec{v}_2$)

Note that we reduced the original question to the consistency of the linear system, whose augmented matrix is formed by placing column vectors $\vec{v}_1, \vec{v}_2, \vec{w}$ one after another.

CONCLUSION: A vector equation $x_1 \vec{a}_1 + x_2 \vec{a}_2 + \dots + x_k \vec{a}_k = \vec{b}$ has the same solution set as the linear system whose augmented matrix is $\left(\begin{array}{ccc|c} \vec{a}_1 & \vec{a}_2 & \dots & \vec{a}_k \\ \hline & & & \vec{b} \end{array} \right)$

In particular, \vec{b} is a linear combination of $\vec{a}_1, \dots, \vec{a}_k$ iff the corresponding linear system is consistent.

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Ex 4: Consider vectors $\vec{v}_1 = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$, $\vec{v}_2 = \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$ in \mathbb{R}^3 .

For which values of parameter g , can $\vec{w} = \begin{pmatrix} 2 \\ 1 \\ g \end{pmatrix}$ be written as a linear combination of \vec{v}_1, \vec{v}_2 .

► Boils down to consistency of the linear system with augmented matrix $\left(\begin{array}{cc|c} 1 & 1 & 2 \\ 2 & -1 & 1 \\ 3 & 1 & g \end{array} \right)$. Performing elementary row operations, get:

$$\left(\begin{array}{cc|c} 1 & 1 & 2 \\ 2 & -1 & 1 \\ 3 & 1 & g \end{array} \right) \begin{array}{l} R_2 \mapsto R_2 - 2R_1 \\ R_3 \mapsto R_3 - 3R_1 \end{array} \left(\begin{array}{cc|c} 1 & 1 & 2 \\ 0 & -3 & -3 \\ 0 & -2 & g-6 \end{array} \right) \begin{array}{l} R_2 \mapsto \frac{1}{-3}R_2 \\ R_3 \mapsto R_3 + 2R_2 \end{array} \left(\begin{array}{cc|c} 1 & 1 & 2 \\ 0 & 1 & 1 \\ 0 & -2 & g-6 \end{array} \right) \begin{array}{l} R_3 \mapsto R_3 + 2R_2 \end{array}$$

$$\rightsquigarrow \left(\begin{array}{cc|c} 1 & 1 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & g-4 \end{array} \right) \begin{array}{l} R_1 \mapsto R_1 - R_2 \end{array} \left(\begin{array}{cc|c} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & g-4 \end{array} \right) \rightsquigarrow \begin{array}{l} \text{corresponds} \\ \text{to linear} \\ \text{system} \end{array} \begin{cases} x_1 = 1 \\ x_2 = 1 \\ 0 = g-4 \end{cases}$$

The latter is consistent iff $g=4$.

Answer: $g=4$

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§1.4 The matrix equation $A\vec{x} = \vec{b}$

We start from the following important definition which provides a convenient way to treat linear combinations of vectors

Def: If A is an $m \times n$ matrix, with n columns $\vec{a}_1, \dots, \vec{a}_n$ (of height m), then the product of A and $\vec{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n$, denoted $A\vec{x}$, is the linear combination of the columns of A with weights being entries of \vec{x}

$$A\vec{x} = x_1\vec{a}_1 + x_2\vec{a}_2 + \dots + x_n\vec{a}_n$$

Example: $\begin{pmatrix} 1 & 3 & 10 \\ 2 & -1 & 5 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ 2 \end{pmatrix} - \begin{pmatrix} 3 \\ -1 \end{pmatrix} + 3 \begin{pmatrix} 10 \\ 5 \end{pmatrix} = \begin{pmatrix} 29 \\ 20 \end{pmatrix}$

$$\begin{pmatrix} 1 & 2 \\ 3 & -1 \\ 10 & 5 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -2 \end{pmatrix} = 1 \cdot \begin{pmatrix} 1 \\ 3 \\ 10 \end{pmatrix} - 2 \cdot \begin{pmatrix} 2 \\ -1 \\ 5 \end{pmatrix} = \begin{pmatrix} -3 \\ 5 \\ 0 \end{pmatrix}$$

! If the height of \vec{x} is not equal to the number of columns of A , then $A \cdot \vec{x}$ is NOT defined.

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In particular, vector equation $x_1 \vec{a}_1 + x_2 \vec{a}_2 + \dots + x_n \vec{a}_n = \vec{b}$ is equivalent to a matrix equation $A \vec{x} = \vec{b}$

$(\vec{a}_1 \vec{a}_2 \dots \vec{a}_n)$ $\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$

CONCLUSION: If A is an $m \times n$ matrix with columns $\vec{a}_1, \dots, \vec{a}_n$, and $\vec{b} \in \mathbb{R}^m$, then the matrix equation $A \vec{x} = \vec{b}$ has the same solution set as the vector equation $x_1 \vec{a}_1 + \dots + x_n \vec{a}_n = \vec{b}$, which in turn has the same solution set as the linear system whose augmented matrix is $(\vec{a}_1 \vec{a}_2 \dots \vec{a}_n | \vec{b})$

Note: The equation $A \vec{x} = \vec{b}$ has a solution iff \vec{b} is a linear combination of the columns of A .

Ex 5: Given three vectors $\vec{v}_1, \vec{v}_2, \vec{v}_3 \in \mathbb{R}^4$, assume $2\vec{v}_1 + 3\vec{v}_2 + 7\vec{v}_3 = \vec{0}$.
Find x_1, x_2 such that $(\vec{v}_1 \vec{v}_2) \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \vec{v}_3$

$$2\vec{v}_1 + 3\vec{v}_2 + 7\vec{v}_3 = \vec{0} \Rightarrow 7\vec{v}_3 = -2\vec{v}_1 - 3\vec{v}_2 \Rightarrow \vec{v}_3 = -\frac{2}{7}\vec{v}_1 - \frac{3}{7}\vec{v}_2$$

Thus: can take $x_1 = -2/7, x_2 = -3/7$

In practice, the product $A \vec{x}$ is computed using the Row-Vector Rule:

If the product $A \vec{x}$ is defined (i.e. size of \vec{x} equals number of columns of A) then the i^{th} entry of $A \vec{x}$ is the sum of products of the corresponding entries from the i^{th} row of A and from the vector \vec{x}

Examples: $\begin{pmatrix} 3 & 5 \\ -2 & 3 \\ 7 & 1 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 4 \end{pmatrix} = \begin{pmatrix} 3 \cdot 2 + 5 \cdot 4 \\ (-2) \cdot 2 + 3 \cdot 4 \\ 7 \cdot 2 + 1 \cdot 4 \end{pmatrix} = \begin{pmatrix} 26 \\ 8 \\ 18 \end{pmatrix}$

$$\begin{pmatrix} 3 & -2 & 7 \\ 5 & 3 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -2 \\ 3 \end{pmatrix} = \begin{pmatrix} 3 \cdot 1 + (-2) \cdot (-2) + 7 \cdot 3 \\ 5 \cdot 1 + 3 \cdot (-2) + 1 \cdot 3 \end{pmatrix} = \begin{pmatrix} 28 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}$$

True / False : $\vec{0}$ is in the span of any collection $\vec{v}_1, \dots, \vec{v}_k \in \mathbb{R}^n$

True / False : $\vec{w} \in \text{Span} \{ \vec{v}_1, \dots, \vec{v}_k \}$

\Downarrow

$\exists \vec{w} \in \text{Span} \{ \vec{v}_1, \dots, \vec{v}_k \}$

True / False : $\vec{w}_1, \vec{w}_2 \in \text{Span} \{ \vec{v}_1, \dots, \vec{v}_k \}$

\Downarrow

$\vec{w}_1 + \vec{w}_2 \in \text{Span} \{ \vec{v}_1, \dots, \vec{v}_k \}$

True / False : $\vec{w}_1 + \vec{w}_2 \in \text{Span} \{ \vec{v}_1, \dots, \vec{v}_k \}$

\Downarrow

$\vec{w}_1, \vec{w}_2 \in \text{Span} \{ \vec{v}_1, \dots, \vec{v}_k \}$

True / False : $\text{Span} \{ \vec{v}_1, \vec{v}_2, \vec{v}_3 \} = \text{Span} \{ \vec{v}_3, \vec{v}_1, \vec{v}_2 \}$