

Lecture #7

Last time: $\left\{ \begin{array}{l} \text{Linear transformations} \\ T: \mathbb{R}^n \rightarrow \mathbb{R}^m \end{array} \right\} = \left\{ \begin{array}{l} \text{Matrix transformations} \\ \mathbb{R}^n \xrightarrow{\psi} \mathbb{R}^m \\ \vec{x} \mapsto \underbrace{A \cdot \vec{x}}_{m \times n \text{ matrix}} \end{array} \right\}$

In particular, we associated the standard matrix A to any linear T , explicitly given by:

$$A = \left(\begin{array}{c} T\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, T\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \dots, T\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \end{array} \right)$$

Q1: Provide an example of a linear map $\mathbb{R}^n \rightarrow \mathbb{R}^m$ which is:

- a) onto and 1-to-1
- b) onto but not 1-to-1
- c) 1-to-1 but not onto
- d) neither onto nor 1-to-1

Q2: a) Does there exist a 1-to-1 linear transformation $\mathbb{R}^3 \rightarrow \mathbb{R}^2$

b) Does there exist an onto linear transformation $\mathbb{R}^2 \rightarrow \mathbb{R}^3$

Conclusions from last week:

- 1) $\vec{x} \mapsto A\vec{x}$ is 1-to-1 iff A has no free variables
- 2) $\overset{\text{linear}}{T: \mathbb{R}^n \rightarrow \mathbb{R}^m}$ is 1-to-1 iff $T(\vec{x}) = \vec{0}$ has only the trivial solution
- 3) linear $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is onto iff columns of A span \mathbb{R}^m (A is the standard matrix of T)
- 4) linear $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is 1-to-1 iff columns of A are linearly independent

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For the rest of today (to be continued next time), we shall discuss:
various operations with matrices.

§2.1 Matrix Operations

First, given an $m \times n$ -matrix A , we use a_{ij} ($\begin{smallmatrix} 1 \leq i \leq m \\ 1 \leq j \leq n \end{smallmatrix}$) to denote
 m rows, n columns its entry in the i^{th} row & j^{th} column:

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2n} \\ \vdots & & & & \\ a_{m1} & a_{m2} & a_{m3} & \dots & a_{mn} \end{pmatrix}$$

Zero matrix: if all $a_{ij} = 0$ (Note: For any m, n we have a zero matrix of size $m \times n$)

Diagonal matrix: if $m=n$ and $a_{ij}=0$ for $i \neq j$, i.e. $A = \begin{pmatrix} * & * & \dots & * \\ 0 & * & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & * \end{pmatrix}$

The identity matrix: if $m=n$ and $a_{ij} = \begin{cases} 0, & \text{if } i=j \\ 1, & \text{else} \end{cases}$: $I_n = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{pmatrix}$

Sum of matrices

If A, B are $m \times n$ matrices (they must be of the same size), then $A+B$ is the $m \times n$ matrix, whose $(i,j)^{\text{th}}$ entry is the sum of $(i,j)^{\text{th}}$ entries of A, B
the "sum of A & B "

$$a_{ij} + b_{ij}$$

Scalar Multiple of matrices

Given an $m \times n$ matrix A and a scalar $c \in \mathbb{R}$, the scalar multiple cA is the $m \times n$ matrix whose columns are c times columns of A , i.e.
 $(i,j)^{\text{th}}$ entry of cA equals $c \cdot a_{ij}$

Q3: Let $A = \begin{pmatrix} 1 & 2 \\ -3 & 5 \\ 7 & -4 \end{pmatrix}$, $B = \begin{pmatrix} -2 & 1 \\ 1 & 3 \\ -1 & 4 \end{pmatrix}$. Compute $2A - 3B$

$$2A - 3B = \begin{pmatrix} 8 & 1 \\ -9 & 1 \\ 17 & -20 \end{pmatrix}$$

Properties:
 A, B, C - of the
same
size
 $c, d \in \mathbb{R}$ - scalars

- | | |
|----------------------|--|
| 1) $A+B=B+A$ | 4) $c \cdot (A+B)=c \cdot A+c \cdot B$ |
| 2) $(A+B)+C=A+(B+C)$ | 5) $(c+d)A=cA+dA$ |
| 3) $A+0=A=0+A$ | 6) $c(dA)=(cd)A$ |

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So far, the addition and scalar multiplication were quite similar to the same named operations on \mathbb{R} . However, we'll soon discuss the very different features of the product and inverse of matrices (when they exist).

Q4: If $T_1: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear operator with the standard matrix A

$$T_2: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

B,

construct linear operator $\mathbb{R}^n \rightarrow \mathbb{R}^m$ which corresponds to:

a) $A + B$

b) $c \cdot A$

- A:** a) $T = T_1 + T_2$, i.e. $T(\vec{x}) = T_1(\vec{x}) + T_2(\vec{x})$
 b) $T = c \cdot T_1$, i.e. $T(\vec{x}) = c \cdot T_1(\vec{x})$

Which other operations can be applied to linear operators?
 We cannot multiply them clearly, but we can take compositions

$$\mathbb{R}^n \xrightarrow{T} \mathbb{R}^m \xrightarrow{S} \mathbb{R}^k$$

$\vec{x} \mapsto S(T(\vec{x}))$ ← clearly it is a linear operator.
 (check this!)

Hence, one can treat it as a matrix transformation.

Q: If the standard matrix of T is B (size $m \times n$) and the standard matrix of S is A (size $k \times m$), what is the standard matrix of their composition ($\vec{x} \mapsto S(T(\vec{x}))$)?

A: If $\vec{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \Rightarrow T(\vec{x}) = B \cdot \vec{x} = (\overrightarrow{b_1} \dots \overrightarrow{b_n}) \cdot \vec{x} = x_1 \overrightarrow{b_1} + \dots + x_n \overrightarrow{b_n}$
 $\Rightarrow S(\vec{x}) = S(x_1 \overrightarrow{b_1} + \dots + x_n \overrightarrow{b_n}) = x_1 S(\overrightarrow{b_1}) + \dots + x_n S(\overrightarrow{b_n}) = x_1 (A \cdot \overrightarrow{b_1}) + \dots + x_n (A \cdot \overrightarrow{b_n})$

and the latter can be written as

$$((\overrightarrow{A \cdot b_1}) \dots (\overrightarrow{A \cdot b_n})) \cdot \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$

the looked-after matrix

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This brings us to the following:

Def: If A is an $k \times m$ matrix, B is an $m \times n$ matrix, then the product AB is the $k \times n$ matrix whose columns are $\vec{A}\vec{b}_1, \dots, \vec{A}\vec{b}_n$.

$$AB = \left(\begin{array}{c} \vec{A}\vec{b}_1 \\ \vdots \\ \vec{A}\vec{b}_n \end{array} \right)$$

← note that this construction is much less obvious (not just component-wise)

Ex 1: Compute

$$a) \begin{pmatrix} 1 & 2 & 3 \\ -4 & 0 & 6 \end{pmatrix} \begin{pmatrix} 1 & -2 \\ 2 & 1 \\ 4 & 0 \end{pmatrix} = \begin{pmatrix} 1 \cdot 1 + 2 \cdot 2 + 3 \cdot 4 & 1 \cdot (-2) + 2 \cdot 1 + 3 \cdot 0 \\ -4 \cdot 1 + 0 \cdot 2 + 6 \cdot 4 & -4 \cdot (-2) + 0 \cdot 1 + 6 \cdot 0 \end{pmatrix} = \begin{pmatrix} 17 & 0 \\ 20 & 8 \end{pmatrix}$$

$$b) \begin{pmatrix} 1 & -2 \\ 2 & 1 \\ 4 & 0 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ -4 & 0 & 6 \end{pmatrix}$$

Note: For the product $A \cdot B$ to be well-defined, the number of columns in A must coincide with the number of rows in B .

Evolving the matrix-column rule for computation of AB , we get

$$(A \cdot B)_{ij} = a_{i1} \cdot b_{1j} + a_{i2} \cdot b_{2j} + \dots + a_{in} \cdot b_{nj}$$

↑ row-column rule for computing $A \cdot B$

(reads: to find the $(i,j)^{\text{th}}$ entry of $A \cdot B$, take the sum of products of elements in the i^{th} row of A with corresponding elements in the j^{th} column of B .)

$$\underline{\text{Ex 2:}} \text{ Compute } \begin{pmatrix} 100 & 0 & 0 \\ 0 & -10 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 19 & 17 & 134 \end{pmatrix} = 0 \quad \leftarrow$$

3x3
ZERO
MATRIX

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Properties of Matrix Multiplication

Let A be an $m \times n$ matrix and B, C be two matrices of appropriate size.

- 1) $A(BC) = (AB)C$
- 2) $A(B+C) = AB + AC$
- 3) $(B+C)A = BA + CA$
- 4) $r \cdot (AB) = (rA) \cdot B = A \cdot (rB) \quad r \in \mathbb{R}$
- 5) $I_m \cdot A = A = A \cdot I_n$, where $I_k = \begin{pmatrix} 1 & & & \\ & \ddots & & \\ & & 1 & \\ & 0 & \cdots & 0 \end{pmatrix}_k^T$ - the identity matrix

Upshot: The addition and product of matrices satisfy the same rules as real numbers, in particular, can open parentheses in a usual way.

However: $AB \neq BA$ even when both products are well-defined.

Ex3: Compute AB and BA for

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 5 \end{pmatrix}, \quad B = \begin{pmatrix} -3 & 7 \\ 1 & 6 \end{pmatrix}$$

$$\Rightarrow AB = \begin{pmatrix} -1 & 19 \\ -4 & 51 \end{pmatrix}, \quad BA = \begin{pmatrix} 18 & 29 \\ 19 & 32 \end{pmatrix}. \quad \text{Clearly } AB \neq BA$$

More Warnings:

- 1) If $AB=0$, it is not true that $A=0$ or $B=0$, see Ex2.
- 2) If $AB=AC$, it is not true that $B=C$.

Q5: For which matrices $A \cdot A$ makes sense?

Def: Given an $n \times n$ matrix A and positive integer $k > 0$, define
 k -th power of A as $A^k := \underbrace{A \cdot A \cdot \dots \cdot A}_{k \text{ times}}$

Convention: $A^0 := I_n$

Q6 $A^k \cdot A^l = ?$ $\approx A^{k+l}$

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There is one more important operation on matrices that will come handy:

Def: Given an $m \times n$ matrix $A = (a_{ij})$, the transpose of A , denoted A^T , is the $n \times m$ matrix whose columns are formed from the corresponding rows of A . In other words:

$$(A^T)_{ij} = a_{ji}$$

example : $\begin{pmatrix} 1 \\ 3 \\ 5 \end{pmatrix}^T = (1 \ 3 \ 5)$

$$\begin{pmatrix} 1 & -3 \\ 2 & -5 \\ 7 & 10 \end{pmatrix}^T = \begin{pmatrix} 1 & 2 & 7 \\ -3 & -5 & 10 \end{pmatrix}$$

Properties

1) $(A^T)^T = A$

2) $(A + B)^T = A^T + B^T$

3) $(c \cdot A)^T = c \cdot A^T, c \in \mathbb{R}$

4) $(A \cdot B)^T = B^T \cdot A^T$

WARNING: note the reversed order in the product on the right-hand side.

Ex 4: For $\vec{u} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ and $\vec{v} = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$, evaluate $\vec{u}^T \cdot \vec{v}$ and $\vec{v} \cdot \vec{u}^T$

$\vec{u}^T \cdot \vec{v} = (1 \ 2) \begin{pmatrix} 3 \\ 2 \end{pmatrix} = (7)$

$\vec{v} \cdot \vec{u}^T = \begin{pmatrix} 3 \\ 2 \end{pmatrix} (1 \ 2) = \begin{pmatrix} 3 & 6 \\ 2 & 4 \end{pmatrix}$

□