

• Last time:

- finished proof of Lie theorem
- proved Engel's theorem
- introduced notions of semisimple, simple, reductive Lie algs
- radical  $\text{rad}(\mathfrak{g})$  and Levi theorem
- finished with decomposition of reductive Lie algs (as direct sum!)

$$\mathfrak{g} \simeq \underbrace{\mathfrak{z}(\mathfrak{g})}_{\text{abelian}} \oplus \underbrace{\mathfrak{g}_{\text{s.s.}}}_{\text{semisimple}}$$

(we shall get a different proof of this later)

Example:  $\mathfrak{g} = \mathfrak{gl}_n \rightsquigarrow \mathfrak{g} = \mathbb{C} \cdot \text{Id} \oplus \mathfrak{sl}_n$

• Semisimplicity through invariant bilinear forms

Last time we established simplicity of  $\mathfrak{sl}_2$  by brute force (using  $\text{ad}(h): \mathfrak{sl}_2 \cong \mathbb{Z}$ )

We shall now see how one could check semisimplicity in general.

Exercise: a) Verify that given any  $\mathfrak{g}$ -module  $V$ , the following defines a  $\mathfrak{g}$ -action on the space of all bilinear forms  $V \times V \rightarrow \mathbb{C}$ :

$$x \cdot B(v, w) = -B(x \cdot v, w) - B(v, x \cdot w) \quad \forall x \in \mathfrak{g}$$

We call  $B$  to be  $\mathfrak{g}$ -invariant if  $B(x \cdot v, w) + B(v, x \cdot w) = 0 \quad \forall x \in \mathfrak{g}, v, w$

b) Verify that  $B$  is  $\mathfrak{g}$ -invariant if the corresponding linear map  $V \rightarrow V^*$ ,  $v \mapsto B(v, -)$

is a  $\mathfrak{g}$ -module homom. (check that identifying bil. maps  $V \times V \rightarrow \mathbb{C}$  with linear maps  $V \rightarrow V^*$ , action in a) agrees with that on  $\text{Hom}(V, V^*)$ )

c) If  $V$  is an irreducible  $\mathfrak{g}$ -module, show that the space of  $\mathfrak{g}$ -inv. bilinear forms  $V \times V \rightarrow \mathbb{C}$  is zero or 1-dimensional

d) If  $V = \mathfrak{g}$  w.r.t. adjoint action of  $\mathfrak{g}$ , and  $I \subseteq \mathfrak{g}$ -ideal, then its orthogonal complement  $I^\perp = \{x \in \mathfrak{g} \mid B(x, y) = 0 \quad \forall y \in I\}$  is also ideal.

Example: Let  $\mathfrak{g} = \mathfrak{gl}_n$  and  $B(x, y) := \text{tr}(xy)$ . It is clearly symmetric and invariant.

$$B(x, y)(z + y(x, z)) = \text{tr}(xy z - yx z + yx z - yz x) = \text{tr}(x, yz) = 0$$

Generalizing this example with the same proof, we have:

Lemma 1. For any  $\mathfrak{g}$ -module  $V$ , the following is a symmetric inv. bilinear form on  $\mathfrak{g}$ :

$$B_V(x, y) = \text{tr}_V(\rho_V(x)\rho_V(y))$$

Lecture #12

The reason why the forms from Lemma 1 are important is the following:

Lemma 2: Let  $\mathfrak{g}$  be a Lie alg,  $V$   $f$ .dim.  $\mathfrak{g}$ -module, s.t.  $B_V: \mathfrak{g} \times \mathfrak{g} \rightarrow \mathbb{K}$  is nondegenerate.  
Then:  $\mathfrak{g}$ -reductive

Exercise: Given any filtration  $0 = F_0 V \subseteq F_1 V \subseteq \dots \subseteq F_n V = V$  of a  $\mathfrak{g}$ -module  $V$  by submodules, we have  $B_V(x, y) = \sum_{k=1}^n B_{F_k V / F_{k-1} V}(x, y) \quad \forall x, y \in \mathfrak{g}$

Proof of Lemma 2

To prove  $\mathfrak{g}$ -reductive, it suffices to show that  $[\mathfrak{g}, \text{rad}(\mathfrak{g})] = 0$ .

Pick any  $x \in [\mathfrak{g}, \text{rad}(\mathfrak{g})]$ . Then by [Lecture 11, Prop 1],  $\rho_W(x) = 0$  for any irreducible  $\mathfrak{g}$ -module  $(W, \rho_W)$ . Thus,  $B_W(x, y) = 0 \quad \forall y \in \mathfrak{g} \quad \forall \text{irred. } W$ .

But any  $f$ .dim  $\mathfrak{g}$ -module  $V$  admits a (Jordan-Holder) filtration  $0 = F_0 V \subseteq F_1 V \subseteq \dots \subseteq F_n V = V$  s.t. each  $F_k V / F_{k-1} V$  is an irreducible  $\mathfrak{g}$ -mod. Then  $B_V(x, -) \equiv 0$  by the above Exercise  $\rightarrow$  contradiction!

Now we are ready to state our first key result for today:

Theorem 1: All classical Lie algebras are reductive.

- a) For  $\mathfrak{g} = \mathfrak{gl}_n(\mathbb{K})$ , consider the natural  $\mathfrak{g}$ -action  $\mathfrak{gl}_n(\mathbb{K}) \curvearrowright \mathbb{K}^n =: V$ .  
Then  $B_V(x, y) = \sum_{i,j=1}^n x_{ij} y_{ji}$  is clearly non-degenerate (with  $\{E_{ji}\}$  being dual to  $\{E_{ij}\}$ ).
- b) For  $\mathfrak{g} = \mathfrak{sl}_n(\mathbb{K})$ , we take the same  $V = \mathbb{K}^n$ . Then  $B_V(x, y) = 0$  for  $x \in \mathfrak{sl}_n, y \in \mathbb{C} \cdot \text{Id}$ , hence, non-degeneracy follows from a)
- c) For  $\mathfrak{g} = \mathfrak{so}_n(\mathbb{K})$ , take  $V = \mathbb{K}^n$ . Then:  
 $B_V(x, y) = \sum_{i,j} x_{ij} y_{ji} \frac{x_{ij} = -x_{ji}}{y_{ij} = -y_{ji}} = 2 \sum_{i>j} x_{ij} y_{ij}$ , which is clearly nondegenerate.

Exercise: a) Finish above proof by treating  $\mathfrak{g} = \mathfrak{sp}_n(\mathbb{K}), \mathfrak{g} = \mathfrak{u}_n, \mathfrak{g} = \mathfrak{su}_n$  (explain why other cases follow as well)  
b) Verify that  $\mathfrak{sl}_n(\mathbb{K}), \mathfrak{so}_n(\mathbb{K})$  with  $n > 2, \mathfrak{su}_n, \mathfrak{sp}_n$  are semisimple, while  $\mathfrak{gl}_n(\mathbb{K}) = \mathbb{K} \cdot \text{Id} \oplus \mathfrak{sl}_n(\mathbb{K}), \mathfrak{u}_n = i\mathbb{R} \cdot \text{Id} \oplus \mathfrak{su}_n$

As an important example of the above setup, we can consider  $\mathfrak{g} \stackrel{\text{ad}}{\cong} \mathfrak{g} =: V$ .

Def 1: The Killing form on  $\mathfrak{g}$  is the bilinear form  $B_{\mathfrak{g}}$  from above, i.e.

$$K(x, y) = \text{tr}_{\mathfrak{g}}(\text{ad } x \circ \text{ad } y)$$

Warning: If  $\mathfrak{a} \subseteq \mathfrak{g}$  is a Lie subalgebra, then the Killing form on  $\mathfrak{a}$  is NOT the restriction of the one on  $\mathfrak{g}$  to  $\mathfrak{a} \times \mathfrak{a}$ . Hence, if needed, we shall use  $K^{\mathfrak{a}}$  for the former and  $K^{\mathfrak{g}}$  to the latter.

Exercise: If  $\mathfrak{a}$  is an ideal of  $\mathfrak{g}$ , then  $K^{\mathfrak{a}} = K^{\mathfrak{g}}|_{\mathfrak{a} \times \mathfrak{a}}$ .

Example: Let's work out example of  $\mathfrak{sl}_2$  first of all. Pick a basis  $e, h, f$ :

$$\text{ad}(e) = \begin{pmatrix} 0 & -2 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}, \quad \text{ad}(f) = \begin{pmatrix} 0 & 0 & 0 \\ -1 & 0 & 0 \\ 0 & 2 & 0 \end{pmatrix}, \quad \text{ad}(h) = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -2 \end{pmatrix}$$

$$\text{Thus: } K(e, f) = K(f, e) = 4, \quad K(h, e) = K(e, h) = 0, \quad K(h, f) = K(f, h) = 0 \\ K(h, h) = 8, \quad K(e, e) = 0, \quad K(f, f) = 0.$$

$$\text{So: } K(x, y) = 4 \text{tr}(xy)$$

↑ by Exercise 1c) on p.1, this is not surprising as  $\mathfrak{sl}_2$ -simple.

Our other two Key Results for today are Cartan's Criteria for solvability and semisimplicity of Lie algebras.

Theorem 2 (Cartan's Criteria for solvability):  $\mathfrak{g}$ -solvable iff  $K([\mathfrak{g}, \mathfrak{g}], \mathfrak{g}) = 0$

Theorem 3 (Cartan's Criteria for semisimplicity):

$\mathfrak{g}$ -semisimple  $\iff$  Killing form  $K$  is non-degenerate

It is instructive to compare Thm 3 to Lemma 2.

## Lecture #12

14

Let us first deduce Theorem 3 from Theorem 2.

### Proof of Theorem 3

⇐:  $K$ -nondeg, hence,  $\mathfrak{g}$ -reductive by Lemma 2. Hence, remains to prove  $z(\mathfrak{g}) = 0$ .

Pick  $x \in z(\mathfrak{g})$ , then  $\text{ad}(x) \equiv 0 \Rightarrow K(x, -) \equiv 0 \Rightarrow x \in \text{Ker } K \Rightarrow \emptyset$

⇒: Let  $\mathfrak{g}$ -semisimple, and set  $I := \text{Ker } K$ . By Exercise 1d), with  $I = \mathfrak{g}$ , get  $I \subseteq \mathfrak{g}$ -ideal  $\Rightarrow$  Killing form of  $I$  is the restriction of the one on  $\mathfrak{g}$ .

Thus:  $K^I \equiv 0 \xrightarrow{\text{Thm 2}} I$ -solvable, hence,  $I = 0$  as  $\mathfrak{g}$ -semisimple

The proof of Theorem 2 is based on the following general result in linear alg:

Theorem 4 (Jordan decomposition): Let  $V$  be a fin. dim. complex vector space

a) Any linear operator  $A$  can be uniquely written as

$$A = A_s + A_n, \text{ with } \begin{array}{l} A_n \text{-nilpotent} \\ A_s \text{-semisimple (a.k.a. diagonalizable)} \\ A_s \cdot A_n = A_n \cdot A_s \end{array}$$

b) Define  $\text{ad}(A): \text{End}(V) \ni B \mapsto \text{ad}(A)B := AB - BA = [A, B]$ . Then:

$$\text{ad}(A)_s = \text{ad}(A_s), \quad \text{ad}(A)_n = \text{ad}(A_n)$$

and  $\text{ad}(A_s)$  can be written as

$$\text{ad}(A_s) = p(\text{ad}(A)) \text{ for some } p \in \mathbb{C}[t]$$

c) Define  $\bar{A}_s$  that has the same eigenspaces as  $A_s$ , but conjugate eigenvalues

$$A_s v = \lambda v \Rightarrow \bar{A}_s v = \bar{\lambda} v.$$

Then  $\text{ad}(\bar{A}_s)$  can also be written as

$$\text{ad}(\bar{A}_s) = q(\text{ad}(A)) \text{ for some } q \in \mathbb{C}[t]$$

We shall now first deduce Thm 2 from Thm 4, and then prove Thm 4

Terminology: The operator  $A: V \rightarrow V$  is called semisimple if  $\forall$  subspace  $V' \subseteq V$  s.t.  $A(V') \subseteq V' \exists V''$  s.t.  $A(V'') \subseteq V''$  and  $V = V' \oplus V''$ .

Lecture #12

Proof of Theorem 2

⇒: If  $\mathfrak{g}$ -solvable, then by Lie thm there is a basis in which all  $\text{ad}(x)$  are upper- $\Delta$ . But then, any  $\text{ad}(y)$  with  $y \in [\mathfrak{g}, \mathfrak{g}]$  is strictly upper- $\Delta$ .  
 Therefore,  $K(x, y) = \text{tr}(\text{ad } x \cdot \text{ad } y) = 0 \quad \forall x \in \mathfrak{g}, y \in [\mathfrak{g}, \mathfrak{g}]$

⇐: Assume  $K([\mathfrak{g}, \mathfrak{g}], \mathfrak{g}) = 0$ . Let  $\alpha := \text{ad}(\mathfrak{g}) \subseteq \text{End}(\mathfrak{g})$ . Then, we have  $\text{tr}(xy) = 0 \quad \forall x \in [\alpha, \alpha], y \in \alpha$ . As  $\mathfrak{g}$  fits into the short exact sequence

$$0 \rightarrow \underbrace{\mathfrak{z}(\mathfrak{g})}_{\text{centerly solvable}} \rightarrow \mathfrak{g} \rightarrow \alpha \rightarrow 0$$

it suffices to prove  $\alpha$  is solvable (thus, reducing to subalg. of  $\mathfrak{gl}(?)$ ). This follows from the following general result.

Claim: Let  $V$  be a fin. dim.  $\mathbb{C}$  v. space,  $\alpha \subseteq \mathfrak{gl}(V)$  - Lie subalgebra s.t.  $\text{tr}(xy) = 0 \quad \forall x \in [\alpha, \alpha], y \in \alpha$ . Then:  $\alpha$ -solvable.

▷ Pick any  $x \in [\alpha, \alpha]$  and consider its Jordan decomposition  $x = x_s + x_n$ .

We also consider  $\bar{x}_s$  as in Thm 4c). Then:

$$\text{tr}(x \cdot \bar{x}_s) = \text{tr}(x_s \cdot \bar{x}_s) = \sum |\lambda_i|^2, \text{ where } \lambda_i \text{ are eigenvalues of } x_s \text{ (i.e. gen. eigenv. of } x \text{)}$$

↑ follows from proof of Thm 4

But as  $x \in [\alpha, \alpha]$ , we can write it as  $x = \sum [\gamma_j, z_j]$ , so that

$$\text{tr}(x \cdot \bar{x}_s) = \text{tr}\left(\sum_j [\gamma_j, z_j] \bar{x}_s\right) = \sum_j \text{tr}(\gamma_j [z_j, \bar{x}_s]) = -\sum_j \text{tr}(\gamma_j [\bar{x}_s, z_j])$$

However,  $[\bar{x}_s, -] = \text{ad}(\bar{x}_s) = \mathfrak{g}(\text{ad } x)$  by Thm 4c), with  $\mathfrak{g} \in \mathfrak{t}(\mathbb{C})$ .

Hence,  $[\bar{x}_s, z_j] \in [\alpha, \alpha]$  and so

$$\text{tr}(\gamma_j [\bar{x}_s, z_j]) = 0 \Rightarrow \text{tr}(x \cdot \bar{x}_s) = 0$$

By above,  $\mathfrak{g} \in \mathfrak{t} \quad \sum |\lambda_i|^2 = 0 \Rightarrow$  all  $\lambda_i = 0 \Rightarrow x_s = 0 \Rightarrow x = x_n$  - nilpotent.

Then,  $[\alpha, \alpha]$ -nilpotent Lie algebra (Engel's thm)  $\Rightarrow \alpha$ -solvable. □

Bmk: While the above proof was over  $\mathbb{C}$ , the result also holds over  $\mathbb{R}$ , since both properties are preserved under  $\otimes \mathbb{C}$ .

Lecture #12

Exercise: Let  $V$  be a fin. dim. complex vector space.

- a)  $A: V \rightarrow V$  is semisimple  $\Leftrightarrow A$ -diagonalizable
- b) If  $A: V \rightarrow V$  is semisimple and  $V' \subseteq V$  satisfies  $A(V') \subseteq V'$ , then the corresponding operators  $V' \rightarrow V'$  and  $V/V' \rightarrow V/V'$  are s.s.
- c) If  $A, B: V \rightarrow V$  are s.s. and  $AB = BA$ , then  $A+B$  is also s.s.
- d) If  $A, B: V \rightarrow V$  are nilpotent and  $AB = BA$ , then  $A+B$  is nilpotent

Let us finally prove Theorem 4 (Jordan decomposition).

Know  $V = \bigoplus_{\lambda \in \mathbb{C}} V_{\lambda}$ ,  $V_{\lambda}$  = generalized eigenspace of  $A$  with eigenvalue  $\lambda$ , i.e.  $(A - \lambda \cdot Id)|_{V_{\lambda}}$  is nilpotent

Then, we set  $A_s: V \rightarrow V$  via  $A_s|_{V_{\lambda}} = \lambda \cdot Id$ , and  $A_n := A - A_s$ .

Clearly:  $A_s$ -s.s. (see Exercise above),  $A_n$ -nilpotent,  $[A_s, A_n] = 0$ .

If  $A = A'_s + A'_n$  is any other such decomposition, then  $A'_s, A'_n$  commute with  $A$  and hence with  $A_s, A_n$  (which uses that  $A_s = p(A)$  established below).

Then:  $\underbrace{A_s - A'_s}_{\text{s.s. by Ex c)}} = \underbrace{A'_n - A_n}_{\text{nilpotent by Ex d)}} \Rightarrow A'_s = A_s, A'_n = A_n \Rightarrow \text{uniqueness!}$

By Chinese remainder thm,  $\exists p(t) \in \mathbb{C}[t]$  s.t.  $p(t) \equiv \lambda_i \pmod{(t - \lambda_i)^{\dim V_{\lambda_i}}}$  for any  $\lambda_i \in \mathbb{C}$  s.t.  $V_{\lambda_i} \neq 0$ . Then:  $(A - \lambda_i)^{\dim V_{\lambda_i}} = 0$  on  $V_{\lambda_i}$

Therefore,  $A_s = p(A)$

So far, we have established the unique decomposition of  $A$  into  $A = A_s + A_n$  with  $A_s$ -s.s.,  $A_n$ -nilp.,  $[A_s, A_n]$ , and proved that both  $A_s, A_n$  are pol. in  $A$ . Moreover, if  $V_0 \neq 0$ , then  $p(t) \in t \cdot \mathbb{C}[t]$ .

Finally, note that  $\text{ad}(A) = \text{ad}(A_s) + \text{ad}(A_n): \text{End}(V) \rightarrow \text{End}(V)$ . Here,  $\text{ad}(A_s)$  &  $\text{ad}(A_n)$  - commute,  $\text{ad}(A_s)$ -s.s.,  $\text{ad}(A_n)$ -nilpotent.

Exercise: Check this!

By uniqueness of Jordan decomp  $\text{ad}(A_s) = (\text{ad}(A))_s$ ,  $\text{ad}(A_n) = (\text{ad}(A))_n$ . Moreover, as  $\text{ad}(A)A = 0$ , can write  $\text{ad}(A_s) = p(\text{ad} A)$  with  $p \in \mathbb{C}[t]$ .

Exercise: Prove part c) of Thm 4