

Last time : - recalled basics of simple fin. dim. Lie algebras + Chevalley-Serre realization
 - introduced contragredient Lie algebras of (A)
 - presented Chevalley-Serre realization for $\mathfrak{g}(A)$ where A - generalized Cartan

Today : Relate this to affine Lie algebras from Lecture 2.

Def 1 : A generalized indecomposable Cartan matrix A is called affine if it's diagonalizable and can be done so that $D = \text{diag}(d_i)$ with $d_i \in \mathbb{R}_{>0}$ satisfies $D \cdot A = (D \cdot A)^T$ and defines a positive semidefinite form (but not positive definite)

The main result from today shows that $\hat{\mathfrak{g}}$ are such for simple $\mathfrak{g}$.

Input : $\mathfrak{g}$ -simple Lie algebra, A-Cartan matrix of $\mathfrak{g}$, so that $a_{ij} = \frac{2(\alpha_i, \alpha_j)}{(\alpha_i, \alpha_i)}$

• $(,)$ - invariant symmetric form on $\mathfrak{g}$

Know : $(,): \mathfrak{h} \times \mathfrak{h} \rightarrow \mathbb{C}$ is nondegenerate $\Rightarrow$ allows to identify

$\mathfrak{h} \simeq \mathfrak{h}^*$ and also pull $(,)$ to form on $\mathfrak{h}^*$

Normalization of $(,)$ is as before: $(\theta, \theta) = 2$, where θ = highest root, i.e. the one with maximal sum of coeff-s in $\theta = \sum_{i \in \mathbb{Z}_{>0}} k_i \alpha_i$ simple

Note : $e_\alpha, f_\alpha, h_\alpha$ satisfy $\mathfrak{sl}_2$ -rel-s imply $[h_\alpha, e_\alpha] = \underbrace{\alpha(h_\alpha)}_{2e_\alpha} \cdot e_\alpha \Rightarrow$

$\Rightarrow \alpha(h_\alpha) = 2$, which implies that under above identification

$$h_\alpha \in \mathfrak{h} \iff \alpha^\vee = \frac{2}{(\alpha, \alpha)} \alpha \in \mathfrak{h}^*$$

in particular :

$$a_{ij} = \alpha_j(h_{\alpha_i}) = \frac{2}{(\alpha_i, \alpha_i)} (\alpha_i, \alpha_j)$$

Theorem 1 : $\hat{\mathfrak{g}}$ is an affine Kac-Moody algebra with affine Cartan matrix

$$\hat{A} = \begin{pmatrix} 2 & a_{0i} \\ a_{i0} & A \end{pmatrix}$$

with a_{0i}, a_{i0} expressed below

Lecture #21

This result is the main reason why affine Kac-Moody algebras are so well-studied

Let $\{e_i, f_i, h_i\}_{i \in \hat{I}}$ be the Chevalley generators of $\mathfrak{g}$, as discussed last time.

Step 1: Generators

Let $I = \{1, \dots, n\}$ and $\hat{I} = I \cup \{0\}$. For $i \in \hat{I} \setminus \{0\}$, we define e_i, f_i, h_i as the corresponding el's of $\mathfrak{g} = \mathfrak{g} \cdot t^0 \subseteq \hat{\mathfrak{g}}$. Let $\theta =$ highest root of $\mathfrak{g}$. Then

$$\text{set: } \boxed{e_0 := f_\theta \cdot t, \quad f_0 := e_\theta \cdot t^{-1}, \quad h_0 := K - h_\theta}$$

Remark: For $\mathfrak{g} = \mathfrak{sl}_n$, we have $\theta = \alpha_1 + \dots + \alpha_{n-1} = E_1 - E_n \Rightarrow e_\theta = E_{n1}, f_\theta = E_{n1}$

$\Rightarrow e_0 = E_{n1}t, f_0 = E_{n1}t^{-1}, h_0 = K - E_{11} + E_{nn}$ which we already encountered as $\mathfrak{sl}_2^{(0)}$ generators in the end of Lecture 17

We first claim that these $\{e_i, f_i, h_i\}_{i \in \hat{I}}$ generate all $\hat{\mathfrak{g}}$. Indeed, taking $i \in I \subseteq \hat{I}$ we can generate all $\mathfrak{g} \cdot t^0 \subseteq \hat{\mathfrak{g}}$. As $\mathfrak{g} \xrightarrow{\text{ad}} \mathfrak{g}t^n \subseteq \hat{\mathfrak{g}}$ is isomorphic to $\text{ad: } \mathfrak{g} \rightarrow \mathfrak{g}$ and $\mathfrak{g}$ -simple $\Rightarrow$ any $x \cdot t^n$ with $x \in \mathfrak{g} \setminus 0, n \in \mathbb{Z}$ would generate all $\mathfrak{g} \cdot t^n$ under this action. Thus, we can generate all $\mathfrak{g}t, \mathfrak{g}t^{-1}$. But these respectively generate all $\mathfrak{g}t^n, \mathfrak{g}t^{-n} \forall n > 0$, as $[\mathfrak{g}, \mathfrak{g}] = \mathfrak{g}$. Finally, K is a linear combination of $h_i, i \in \hat{I}$.

Step 2: Chevalley type relations

1) $[h_i, h_j] = 0$ are clear!

2) $[h_i, e_j] = a_{ij} \cdot e_j$ for all $i, j \in \hat{I}$

- for $i, j \neq 0$, this follows from Chevalley rel's for $\mathfrak{g}$

- for $i=0, j \neq 0$: $[h_0, e_j] = [K - h_\theta, e_j] = -[h_\theta, e_j] = \underbrace{-\alpha_j(h_\theta)}_{\text{our } a_{0j}} \cdot e_j$

but let's express it solely through the pairing:

$$\boxed{a_{0j} = -\alpha_j(h_\theta) = (-\alpha_j, \theta^\vee) = (-\alpha_j, \theta)}$$

Lecture #21

(Continuation)

- for $i=0, j=0$: $[h_0, e_0] = [K - h_0, f_0 t] = \theta(h_0) \cdot f_0 t = (\theta, \theta^\vee) f_0 t = 2 \cdot f_0 t$

- for $i \neq 0, j=0$: $[h_i, e_0] = [h_i, f_0 t] = \frac{-\theta(h_i)}{a_{i0}} f_0 t$

and using the pairing we get: $a_{i0} = (-\theta, \alpha_i^\vee) = \frac{2}{(\alpha_i, \alpha_i)} \cdot (-(\alpha_i, \theta)) = -(\alpha_i, \theta) \cdot \frac{(\theta, \theta)}{(\alpha_i, \alpha_i)}$

[Remark. One has $\frac{(\theta, \theta)}{(\alpha_i, \alpha_i)} \in \{1, 2, 3\}$

3) The relations $[h_i, f_j] = -a_{ij} f_j \quad \forall i, j \in \hat{I}$ are verified analogously.

4) $[e_i, f_j] = \delta_{ij} \cdot h_i \quad \forall i, j \in \hat{I}$

- if $i, j \neq 0$, then it follows from such rel's by

- if $i=0, j \neq 0 \Rightarrow [e_0, f_j] = [f_0 t, f_j] \in \underbrace{\sigma_{-\theta - \alpha_j} t}_{\text{"0 as } \theta\text{-highest root}} \Rightarrow [e_0, f_j] = 0$

- if $i \neq 0, j=0 \Rightarrow [e_i, f_0] = [e_i, e_0 t] \in \underbrace{\sigma_{\theta + \alpha_i} t}_{\text{"0 as } \theta\text{-highest root}} \Rightarrow [e_i, f_0] = 0$

- if $i=j=0$, then $[e_0, f_0] = [f_0 t, e_0 t] = -h_0 + K \cdot (f_0, e_0)$

it remains to show that $(f_0, e_0) = 1$. To this end, note:

$$\begin{aligned} ([h_0, f_0], e_0) &= (h_0, [f_0, e_0]) = (h_0, -h_0) = -(\theta^\vee, \theta^\vee) = -(\theta, \theta) = -2 \\ &\quad (-2 f_0, e_0) \Rightarrow \boxed{(f_0, e_0) = 1} \end{aligned}$$

This completes our verification of all Chevalley relations.

• Moreover: $\hat{A}$ is now fully recovered from A and $\begin{cases} a_{i0} = -(\alpha_i, \theta) \\ a_{0i} = -(\alpha_i, \theta) \cdot \frac{(\theta, \theta)}{(\alpha_i, \alpha_i)} \end{cases}$

Note: $(\alpha_i, \theta) \geq 0$ as otherwise $\theta + \alpha_i$ would be a root

(due to the property of root systems) contradicting θ -highest so that $\hat{A}$ is indeed generalized Cartan matrix

$\hat{A}$ -indecomposable, which can be checked just case-by-case.

Also: If $\hat{D} := \text{diag}(\frac{1}{d_1}, d_2, \dots, d_n)$ with $d_i = \frac{(\alpha_i, \alpha_i)}{2}$, then $\hat{D} \cdot \hat{A}$ -symmetric

($d_0 \cdot a_{0j} = -(\alpha_j, \theta) = a_{j0} \cdot d_j$, $d_i \cdot a_{ij} = a_{ji} d_j = (\alpha_i, \alpha_j)$ for $i, j \neq 0$)

Lecture #21

(Continuation)

4

We claim that $\hat{D} \cdot \hat{A}$ defines a positive semi-definite form. To this end, we note that $\forall \vec{x} = \begin{pmatrix} x_0 \\ x_1 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^{n+1}$ we have:

$$\vec{x}^T \cdot \hat{D} \hat{A} \cdot \vec{x} = (x_0 \cdot (-\theta) + x_1 d_1 + \dots + x_n d_n, x_0 \cdot (-\theta) + x_1 d_1 + \dots + x_n d_n) \in \mathbb{R}_{\geq 0}$$

Moreover, it's zero iff $\theta = \frac{x_1}{x_0} d_1 + \dots + \frac{x_n}{x_1} d_n$. Evoking $\theta = a_1 d_1 + \dots + a_n d_n$ with some $a_i \in \mathbb{Z}_{\geq 0}$ (actually $a_i \in \mathbb{Z}_{>0}$) we get that all $\vec{x} \in \mathbb{R}^{n+1}$ s.t. $\vec{x}^T \hat{D} \hat{A} \vec{x} = 0$ are multiples of $\begin{pmatrix} 1 \\ a_1 \\ \vdots \\ a_n \end{pmatrix}$. In particular, $\hat{D} \hat{A}$ is not positive definite.

To finish the proof, we need either to check Serre rel's, which we leave as an exercise

Exercise: Verify Serre rel's for der_i , f_i ($i \in \hat{I}$)

OR use the last condition of contragredient Lie algebras:

Step 3: Any graded ideal I of $\hat{\mathfrak{g}}$ intersects $\hat{\mathfrak{h}} = \mathfrak{h} \oplus \mathbb{C}K$ nontrivially.

Assume contrary. Then it gives rise to graded nonzero ideal $\bar{I}$ in $\text{Log} \hat{\mathfrak{g}} = \hat{\mathfrak{g}}/K$. But if $x t^n \in \bar{I}$ then $[x t^n, y t^m] = y t^{n+m} \Rightarrow \bar{I} = \text{Log} \hat{\mathfrak{g}} \Rightarrow \bar{I} \cap \hat{\mathfrak{h}} \neq 0 \Rightarrow \nabla$.

Remark: The corresponding root lattice $\hat{Q} = \mathbb{Z} d_0 \oplus \mathbb{Z} d_1 \oplus \dots \oplus \mathbb{Z} d_n = \mathbb{Z} d_0 \oplus Q$ where $Q = \text{root lattice of } \mathfrak{g}$. Alternatively, if $\delta := d_0 + \theta$, then $\hat{Q} = Q \oplus \mathbb{Z} \delta$ and δ generates the kernel of above pairing given by $\hat{D} \cdot \hat{A}$. In the loop realization, we get $\deg(x t^n) = \underbrace{\deg(x)}_{\in \mathbb{Q}} + n \cdot \delta$ for any $x \in \mathfrak{g}$, $n \in \mathbb{Z}$. We also should have noted in the proof: $\hat{\mathfrak{g}}_0 = \hat{\mathfrak{h}}$ has basis $\text{thil}_i \vec{e}_0$, $\hat{\mathfrak{g}}_{\alpha_i} = \mathbb{C} e_i$, $\hat{\mathfrak{g}}_{-\alpha_i} = \mathbb{C} f_i$ $\forall i \in \hat{I}$.

Remark: To fix the issue of $\delta \in \text{Ker}(\text{pairing})$, we shall be adding derivatives/degree generators next time.

