

Lecture #4

* Last time

- Equations of the lines $\begin{cases} \vec{r} = \vec{r}_0 + t\vec{v} & \text{(vector equation)} \\ x = x_0 + at, y = y_0 + bt, z = z_0 + ct & \text{(parametric equation)} \end{cases}$

Recall: Given a line by parametric equation, its direction is determined by reading off the coefficients of t , i.e. $\langle a, b, c \rangle$.

- Equations of the planes $\begin{cases} \vec{n}(\vec{r} - \vec{r}_0) = 0 & \text{(vector equation)} \\ a(x - x_0) + b(y - y_0) + c(z - z_0) = 0 & \text{(scalar equation)} \\ ax + by + cz + d = 0 & \text{(linear equation)} \end{cases}$

- Distance formula: given a point $P_1(x_1, y_1, z_1)$ and a plane Π containing $P_0(x_0, y_0, z_0)$ and orthogonal to $\vec{n} = \langle a, b, c \rangle$, the distance D from P_1 to Π is

$$D = \frac{|a(x_1 - x_0) + b(y_1 - y_0) + c(z_1 - z_0)|}{\sqrt{a^2 + b^2 + c^2}}$$

In particular if Π is given by $ax + by + cz + d = 0$ (linear equation), then D equals

$$D = \frac{|ax_1 + by_1 + cz_1 + d|}{\sqrt{a^2 + b^2 + c^2}}$$

Ex 1: Compute a distance from $P(1, 2, -2)$ to the plane $x - 2y + 3z = 8$.

Plugging $a=1, b=-2, c=3, d=-8$ into the above formula, get $D = \frac{20}{\sqrt{14}}$

* Today: Vector functions (§13.1-13.4 in the textbook)

Def: A vector function is a function whose domain is a subset of \mathbb{R} and whose range is a set of vectors

We will be mostly interested in the case of vectors in \mathbb{R}^3 , thus a vector function is an assignment $t \mapsto \vec{r}(t) = \langle f(t), g(t), h(t) \rangle$ $f(t), g(t), h(t)$ - component functions

Domain is the set of t for which $\vec{r}(t)$ is defined, while range - the set of all possible $\vec{r}(t)$.

Limits & Continuity

The limit of a vector function is defined component-wise, e.g. for $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$

$$\lim_{t \rightarrow a} \vec{r}(t) = \langle \lim_{t \rightarrow a} f(t), \lim_{t \rightarrow a} g(t), \lim_{t \rightarrow a} h(t) \rangle$$

← if one of these limits does not exist, so is $\lim_{t \rightarrow a} \vec{r}(t)$.

Def: A vector function $\vec{r}(t)$ is continuous at $a \in \mathbb{R}$ if i.e. iff all components of $\vec{r}(t)$ are continuous at a .

$$\lim_{t \rightarrow a} \vec{r}(t) = \vec{r}(a)$$

Ex 2: Find $\lim_{t \rightarrow 0} \vec{r}(t)$ for $\vec{r}(t) = \langle t + \frac{1}{t+1}, \frac{e^t - 1}{3t}, \frac{\sin 6t}{2t} \rangle$

Use L'Hospital rule to get

$$\lim_{t \rightarrow 0} \vec{r}(t) = \langle 1, 1/3, 3 \rangle$$

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* Space Curves

Def: Let f, g, h be continuous \mathbb{R} -valued functions on an interval I . Then the locus of all points $(x, y, z) \in \mathbb{R}^3$ such that $x=f(t), y=g(t), z=h(t), t \in I$, is called a space curve.

Note that any continuous vector function $\vec{r}(t)$ defines a space curve C , traced out by the tip of $\vec{r}(t)$.

Ex 3: Describe the curves defined by the vector functions:

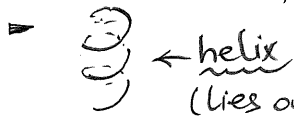
(a) $\vec{r}(t) = \langle 1+3t, 2-4t, 7+2t \rangle$

► line passing through $(1, 2, 7)$ and parallel to $\langle 3, -4, 2 \rangle$.

(b) $\vec{r}(t) = \langle 2\cos t, 2\sin t, 3 \rangle$

► circle of radius 2, centered at $(0, 0, 3)$ and parallel to the xy -plane.

(c) $\vec{r}(t) = \langle 2\cos t, 2\sin t, t \rangle$



(lies on the cylinder)

its projection to the xy -plane is a radius 2 circle, centered at $(0, 0)$.

Ex 4: Find a vector function that represents

(a) a line segment between $P(1, 2, 3)$ and $Q(7, 5, 6)$.

► $\vec{r}(t) = \langle 1, 2, 3 \rangle + t \langle 6, 3, 3 \rangle = \langle 1+6t, 2+3t, 3+3t \rangle$ with $0 \leq t \leq 1$.

(b) the curve of intersection of the cylinder $x^2 + y^2 = 4$ and the plane $x + 2y + z = 1$.

► Being on the cylinder, we see that (x, y) coordinates may be parametrized via $x = 2\cos t, y = 2\sin t, 0 \leq t < 2\pi$.

Finally, being on the plane $x + 2y + z = 1$ determines z via x, y : $z = 1 - x - 2y$.

So: $\vec{r}(t) = \langle 2\cos t, 2\sin t, 1 - 2\cos t - 4\sin t \rangle, 0 \leq t < 2\pi$

Ex 5: Hand out worksheet with matching game.

* Derivatives of vector functions

The formal definition of the derivative of a vector function $\vec{r}(t)$ may be given as for usual \mathbb{R} -valued functions in school:

$$\vec{r}'(t) = \lim_{h \rightarrow 0} \frac{\vec{r}(t+h) - \vec{r}(t)}{h}$$

However, this is not the way we will actually compute derivatives.

Instead, we just compute component-wise, e.g. if $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$, then clearly $\vec{r}'(t)$ equals

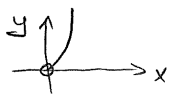
$$\vec{r}'(t) = \langle f'(t), g'(t), h'(t) \rangle$$

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Geometric meaning: 1) From the formal definition of $\vec{r}'(t)$, it is clear that it is tangent to the space curve (determined by \vec{r} at the point $\vec{r}(t)$).
2) If we think of $\vec{r}(t)$ as a coordinate-vector of the particle moving around the trajectory C , then $\|\vec{r}'(t)\|$ = speed of particle

Ex 6: (a) Sketch the plane curve with parametric equation $x = e^t, y = 2e^{3t}$

► $y = 2x^3, x > 0$



(b) Find $\vec{r}'(t)$.

► $\vec{r}'(t) = \langle e^t, 6e^{3t} \rangle$

(c) Find the unit tangent vector at the point with $t = 0$

► $\vec{r}'(0) = \langle e^0, 6e^0 \rangle = \langle 1, 6 \rangle \Rightarrow T(0) = \frac{\vec{r}'(0)}{\|\vec{r}'(0)\|} = \frac{1}{\sqrt{37}} \hat{i} + \frac{6}{\sqrt{37}} \hat{j}$

(d) Sketch the position vector $\vec{r}(t)$ and the tangent vector $\vec{r}'(t)$ for $t = 0$.

Ex 7: Find the parametric equation for the tangent line to the helix $x = 2\cos t, y = 2\sin t, z = t$ at the point $(0, 2, \pi/2)$.

► This point corresponds to $t = \pi/2$

$\vec{r}'(t) = \langle -2\sin t, 2\cos t, 1 \rangle \Rightarrow \vec{r}'(\pi/2) = \langle -2, 0, 1 \rangle$

Thus: tangent line is given by $x = -2s, y = 2, z = \pi/2 + s, s \in \mathbb{R}$

Integrals of vector functions

Integrals are also defined component-wise, e.g. for $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle$

$$\int_a^b \vec{r}(t) dt = \left\langle \int_a^b f(t) dt, \int_a^b g(t) dt, \int_a^b h(t) dt \right\rangle$$

Ex 8: Evaluate $\int_0^1 (te^{t^2} \hat{i} + 2\sin t \cos t \hat{j} + e^{5t} \hat{k}) dt$

► $\int_0^1 te^{t^2} dt = \frac{e^{t^2}}{2} \Big|_{t=0}^{t=1} = \frac{e-1}{2}$; $\int_0^1 2\sin t \cos t dt = \sin^2 t \Big|_{t=0}^{t=1} = \sin^2(1)$; $\int_0^1 e^{5t} dt = \frac{e^{5t}}{5} \Big|_{t=0}^{t=1} = \frac{e^5-1}{5}$

So: get $\left[\frac{e-1}{2} \hat{i} + \sin^2(1) \hat{j} + \frac{e^5-1}{5} \hat{k} \right]$

* Length of a curve

For the case of plane curves given by $x = f(t), y = g(t)$, many of you know that the length of the curve for $a \leq t \leq b$ equals

$$L = \int_a^b \sqrt{f'(t)^2 + g'(t)^2} dt$$

Likewise, given a space curve $\vec{r}(t) = \langle f(t), g(t), h(t) \rangle, a \leq t \leq b$, its length equals

$$L = \int_a^b \sqrt{f'(t)^2 + g'(t)^2 + h'(t)^2} dt$$

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Both formulas for L may be uniformly written as

$$L = \int_a^b \|\vec{r}'(t)\| dt$$

Recalling $\|\vec{r}'(t)\| = \text{speed}$, this formula becomes obvious

! We should request above that the curve is traversed exactly once.

Ex 9: (a) Find the length of the curve given by

$$\vec{r}(t) = \langle 3 \cos t, 3 \sin t, 4t \rangle \text{ from } (3, 0, 0) \text{ to } (3, 0, 16\pi)$$

$$\Rightarrow L = \int_0^{16\pi} \sqrt{(-3 \sin t)^2 + (3 \cos t)^2 + 4^2} dt = \int_0^{16\pi} 5 dt = 20\pi$$

(b) $\vec{r}(t) = \langle 6t, t^3, 3t^2 \rangle, -1 \leq t \leq 1$

$$\Rightarrow L = \int_{-1}^1 \sqrt{6^2 + (3t^2)^2 + (6t)^2} dt = \int_{-1}^1 \sqrt{9t^4 + 36t^2 + 36} dt = \int_{-1}^1 (3t^2 + 6) dt = (t^3 + 6t) \Big|_{-1}^1 = 14$$

* Velocity & Acceleration

Imagine a particle moving in \mathbb{R}^3 with position vector $\vec{r}(t)$. Then, the velocity is the limit of the displacement vector and equals

$$\vec{v}(t) = \vec{r}'(t)$$

The speed at time t equals $\|\vec{v}(t)\| = \|\vec{r}'(t)\|$.

The acceleration of the particle is defined as the derivative of the velocity

$$\vec{a}(t) = \vec{v}'(t) = \vec{r}''(t)$$

Ex 10: A moving particle starts at the initial position $\vec{r}(0) = \langle 2, 0, 3 \rangle$, with initial velocity $\vec{v}(0) = \langle 1, 2, -3 \rangle$ and acceleration $\vec{a}(t) = \langle e^t, -2t, 2 \sin t \rangle$. Find its velocity & position at time t .

$$\begin{aligned} \vec{a}(t) = \vec{v}'(t) &\Rightarrow \vec{v}(t) = \vec{v}(0) + \int_0^t \vec{a}(u) du = \langle 1, 2, -3 \rangle + \int_0^t \langle e^u, -2u, 2 \sin u \rangle du \\ &= \langle 1, 2, -3 \rangle + \langle e^t - 1, -t^2, -2 \cos t + 2 \rangle = \langle e^t, 2 - t^2, -1 - 2 \cos t \rangle \end{aligned}$$

$$\begin{aligned} \vec{v}(t) = \vec{r}'(t) &\Rightarrow \vec{r}(t) = \vec{r}(0) + \int_0^t \vec{v}(u) du = \langle 2, 0, 3 \rangle + \int_0^t \langle e^u, 2 - u^2, -1 - 2 \cos u \rangle du \\ &= \langle 2, 0, 3 \rangle + \langle e^t - 1, 2t - \frac{t^3}{3}, -t - 2 \sin t \rangle = \langle e^t + 1, 2t - \frac{t^3}{3}, 3 - t - 2 \sin t \rangle \end{aligned}$$

□