

Lesson 27

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Eigenvalues/vectors and Theory for Systems (7.3, 7.4)

Let $\{\vec{v}_1, \dots, \vec{v}_n\}$ be a set of vectors. A linear combination is of the form $c_1\vec{v}_1 + \dots + c_n\vec{v}_n$ for scalars c_1, \dots, c_n .

Notice that the zero vector $\vec{0}$ is always a linear combination of any set of vectors (choose $c_1 = \dots = c_n = 0$).

A set of vectors is linearly independent if this is the only way to write the $\vec{0}$ vector as a linear combination of the vectors. Otherwise, the set is linearly dependent.

Ex 1. Show that the collection $\{\vec{x}^{(1)}, \vec{x}^{(2)}\}$ is linearly independent where $\vec{x}^{(1)} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$, $\vec{x}^{(2)} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$

$$\text{Suppose } c_1\vec{x}^{(1)} + c_2\vec{x}^{(2)} = \vec{0}$$

$$\begin{pmatrix} 2c_1 \\ c_1 \end{pmatrix} + \begin{pmatrix} 0 \\ -c_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} 2c_1 + c_2 \\ c_1 - c_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$2c_1 + c_2 = 0 \text{ and } c_1 - c_2 = 0$$

$$2c_1 = 0 \Rightarrow c_1 = 0$$

$$0 + c_2 = 0 \Rightarrow c_2 = 0$$

We could also form the matrix $\begin{pmatrix} \vec{x}^{(1)} & \vec{x}^{(2)} \end{pmatrix}$ and take the determinant.

$$\begin{vmatrix} 2 & 1 \\ 1 & -1 \end{vmatrix} = -2 - 1 = -3 \neq 0$$

A set of 2 2-vectors is linearly independent if and only if the determinant $|\vec{x}^{(1)} \vec{x}^{(2)}| \neq 0$.

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Ex 2. Show that $\{\vec{x}^{(1)}, \vec{x}^{(2)}\}$ is linearly dependent
where $\vec{x}^{(1)} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$, $\vec{x}^{(2)} = \begin{pmatrix} -4 \\ -6 \end{pmatrix}$

$$\begin{vmatrix} 2 & -4 \\ 3 & -6 \end{vmatrix} = -12 + 12 = 0 \quad \text{or}$$

$$c_1 \vec{x}^{(1)} + c_2 \vec{x}^{(2)} = \vec{0} \\ \begin{pmatrix} 2c_1 & -4c_2 \\ 3c_1 & -6c_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$2c_1 - 4c_2 = 0, \quad 3c_1 - 6c_2 = 0$$

$$6c_1 - 12c_2 = 0, \quad -6c_1 + 12c_2 = 0 \\ 0 = 0$$

Choose any value for c_1 . Say $c_1 = 2$.

$$4 - 4c_2 = 0 \quad \text{so} \quad c_2 = 1$$

$$\text{Then } 2\vec{x}^{(1)} + 1\vec{x}^{(2)} = \vec{0}$$

Let A be a matrix. A scalar λ is called an eigenvalue of A and \vec{x} is called an eigenvector of A associated with λ if $\vec{x} \neq \vec{0}$ and $A\vec{x} = \lambda\vec{x}$.

To find the eigenvalues of A , we get a polynomial, called the characteristic polynomial of A , and find its roots. The characteristic polynomial of A is $\det(A - \lambda I)$, where I is the identity matrix.

For 2×2 matrices $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$,

$$\det(A - \lambda I) = \begin{vmatrix} a-\lambda & b \\ c & d-\lambda \end{vmatrix} = (a-\lambda)(d-\lambda) - cb$$

If λ_0 is an eigenvalue of A , we find an associated eigenvector $\vec{x}^{(0)}$ by solving the system $A\vec{x} = \lambda_0\vec{x}$, or equivalently, $(A - \lambda_0 I)\vec{x} = \vec{0}$

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If $\vec{x}^{(0)}$ is an eigenvector of A associated with λ_0 , then for any scalar $c \neq 0$, $c\vec{x}^{(0)}$ is also such an eigenvector, so we have a choice.

Ex 3. Find the eigenvalues and eigenvectors of

$$\begin{pmatrix} -2 & 1 \\ 1 & -2 \end{pmatrix}$$

$$\text{Find char poly: } \begin{vmatrix} -2-\lambda & 1 \\ 1 & -2-\lambda \end{vmatrix} = (-2-\lambda)^2 - (1)(1) \\ = 4 + 4\lambda + \lambda^2 - 1$$

$$\lambda^2 + 4\lambda + 3 = (\lambda+3)(\lambda+1)$$

$$\lambda_1 = -1, \lambda_2 = -3$$

To find eigenvectors, solve

$$\lambda_1 = -1: \begin{pmatrix} -2-(-1) & 1 & | & 0 \\ 1 & -2-(-1) & | & 0 \end{pmatrix} = \begin{pmatrix} -1 & 1 & | & 0 \\ 1 & -1 & | & 0 \end{pmatrix}$$

$$\begin{aligned} x_1 + x_2 &= 0 \Rightarrow \text{get } x_1 = x_2 \\ x_1 - x_2 &= 0 \end{aligned}$$

We can choose any value for x_1 , say $x_1 = 1$. Then $x_2 = 1$
so $\vec{x}^{(1)} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$$\lambda_2 = -3: \begin{pmatrix} -2-(-3) & 1 & | & 0 \\ 1 & -2-(-3) & | & 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 & | & 0 \\ 1 & 1 & | & 0 \end{pmatrix}$$

$$\begin{aligned} x_1 + x_2 &= 0 \\ x_1 + x_2 &= 0 \end{aligned} \Rightarrow \text{get } x_1 = -x_2$$

choose any value for x_1 , say $x_1 = 1$, then $x_2 = -1$.
so $\vec{x}^{(2)} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$

$$\boxed{\lambda_1 = -1, \vec{x}^{(1)} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}; \lambda_2 = -3, \vec{x}^{(2)} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}}$$

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If A is a real-valued matrix (all entries are real numbers) and λ_1 is a non-real complex number eigenvalue of A , then $\lambda_2 = \overline{\lambda_1}$ is also an eigenvalue. Moreover, if $\vec{x}^{(1)}$ is an eigenvector (assoc. λ_1), then $\vec{x}^{(2)} = \overline{\vec{x}^{(1)}}$ (conjugate) is an eigenvector (assoc. λ_2).

Ex 4. Find eigenvalues and eigenvectors of

$$\begin{pmatrix} 1 & 5 \\ -1 & -1 \end{pmatrix}$$

$$\text{Char poly: } \begin{vmatrix} -\lambda & 5 \\ -1 & -1-\lambda \end{vmatrix} = ((-\lambda)(-1-\lambda)) + 5 = -(-\lambda - \lambda + \lambda^2 + 5) = \lambda^2 + 4$$

$$\lambda_1 = 2i, \quad \lambda_2 = -2i$$

$$\text{Eigenvectors: } \left(\begin{array}{cc|c} 1-2i & 5 & 0 \\ -1 & -1-2i & 0 \end{array} \right)$$

$$(1-2i)x_1 + 5x_2 = 0 \quad \Rightarrow \quad -\frac{(1-2i)x_1}{5} = x_2$$

$$-x_1 + (-1-2i)x_2 = 0$$

Choose $x_1 = 5$. Then $x_2 = -1+2i$.

$$\vec{x}^{(1)} = \begin{pmatrix} 5 \\ -1+2i \end{pmatrix}$$

$$\text{Then } \vec{x}^{(2)} = \overline{\vec{x}^{(1)}} = \begin{pmatrix} \overline{5} \\ \overline{-1+2i} \end{pmatrix} = \begin{pmatrix} 5 \\ -1-2i \end{pmatrix}$$

$$\boxed{\lambda_1 = 2i, \quad \vec{x}^{(1)} = \begin{pmatrix} 5 \\ -1+2i \end{pmatrix}; \quad \lambda_2 = -2i, \quad \vec{x}^{(2)} = \begin{pmatrix} 5 \\ -1-2i \end{pmatrix}}$$

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(K1.5)

A system of differential equations can be written as $\vec{x}' = P(t)\vec{x} + \vec{g}(t)$.

If $\vec{g}(t) = \vec{0}$, then the system is homogeneous.

Principle of Superposition. If $\vec{x}^{(1)}$ and $\vec{x}^{(2)}$ are solutions to a homogeneous system as above, then for any scalars c_1 and c_2 , $c_1\vec{x}^{(1)} + c_2\vec{x}^{(2)}$ is also a solution.

"Wronskian". If $\vec{x}' = P(t)\vec{x}$ is a system of 2 linear ODEs and $\{\vec{x}^{(1)}, \vec{x}^{(2)}\}$ is a linearly independent set of solutions (i.e., $(\vec{x}^{(1)}, \vec{x}^{(2)}) \neq \vec{0}$), then $\{\vec{x}^{(1)}, \vec{x}^{(2)}\}$ is a fundamental set of solutions. (i.e., all solutions to $\vec{x}' = P(t)\vec{x}$ can be written as $c_1\vec{x}^{(1)} + c_2\vec{x}^{(2)}$ for some scalars c_1, c_2 .)

$c_1\vec{x}^{(1)} + c_2\vec{x}^{(2)}$ is called the general solution in this case.