

# MTH 165: Linear Algebra with Differential Equations

Final Exam

May 6, 2013

NAME (please print legibly): Solutions

Your University ID Number: \_\_\_\_\_

Indicate your instructor with a check in the box:

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- The presence of electronic devices (including calculators), books, or formula cards/sheets at this exam is strictly forbidden.
- Show your work and justify your answers. You may not receive full credit for a correct answer if insufficient work is shown or insufficient justification is given.
- Clearly circle or label your simplified final answers.
- You are responsible for checking that this exam has all 11 pages.

QUESTION	VALUE	SCORE
1	10	
2	10	
3	10	
4	10	
5	10	
6	10	
7	10	
8	10	
9	10	
10	10	
TOTAL	100	

1. (10 points) Solve the following initial value problems:

(a) (5 points)

$$(x^2 + 1) \frac{dy}{dx} + 3xy = 6x, \quad y(0) = 3;$$

$$(x^2 + 1) \frac{dy}{dx} = 6x - 3xy = 3x(2-y). \quad \text{So} \quad \frac{dy}{2-y} = \frac{3x}{x^2+1}$$

$$\text{Integrating} \quad \int \frac{dy}{2-y} = \int \frac{3x}{x^2+1} \Rightarrow -\ln|2-y| = \frac{3}{2} \ln(x^2+1) + C.$$

$$\text{Set } x=0: \quad -\ln|2-3| = \frac{3}{2} \ln(1) + C \Rightarrow C=0.$$

$$\text{So } \ln|2-y| = -\frac{3}{2} \ln(x^2+1) = \ln[(x^2+1)^{-3/2}]$$

$$|2-y| = (x^2+1)^{-3/2} \quad \text{Looking at } x=0 \quad \text{where } y=3 \text{ and not } y=1 \quad \sim \quad y-2 = (x^2+1)^{-3/2} \text{ or}$$

(b) (5 points)

$$y' + \frac{y}{x^2} = \frac{2}{x^2}, \quad y(1) = 1.$$

$$\boxed{y = 2 + (x^2+1)^{-3/2}}$$

Integrating factor  $I(x) = e^{\int \frac{dx}{x^2}} = e^{-1/x}$ .

Multiply both sides of the equation:

$$e^{-1/x} y' + \frac{e^{-1/x}}{x^2} y = 2 \frac{e^{-1/x}}{x^2} \Rightarrow [e^{-1/x} y]' = 2 \frac{e^{-1/x}}{x^2}$$

$$\text{Integrating: } e^{-1/x} y = 2 \int \frac{e^{-1/x}}{x^2} dx \stackrel{u=1/x}{=} 2 e^{-1/x} + C$$

$$\text{Setting } x=1: \quad e^{-1} \cdot 1 = 2 \cdot e^{-1} + C \Rightarrow C = -e^{-1}.$$

$$\text{So } e^{-1/x} y = 2 e^{-1/x} - e^{-1} \Rightarrow \boxed{y = 2 - e^{-1} e^{1/x}}$$

Note: Can also separate variables!

## 2. (10 points)

(a) (5 points) Find the value of  $k$  which satisfies

$$\det \begin{bmatrix} 2a_1 & 2a_2 & 2a_3 \\ 3b_1 + 5c_1 & 3b_2 + 5c_2 & 3b_3 + 5c_3 \\ 7c_1 & 7c_2 & 7c_3 \end{bmatrix} = k \cdot \det \begin{bmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix}.$$

$$\begin{vmatrix} 2a_1 & 2a_2 & 2a_3 \\ 3b_1+5c_1 & 3b_2+5c_2 & 3b_3+5c_3 \\ 7c_1 & 7c_2 & 7c_3 \end{vmatrix} = 2 \cdot 7 \begin{vmatrix} a_1 & a_2 & a_3 \\ 3b_1+5c_1 & 3b_2+5c_2 & 3b_3+5c_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

$$= 2 \cdot 7 \begin{vmatrix} a_1 & a_2 & a_3 \\ 3b_1 & 3b_2 & 3b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

$$= 2 \cdot 7 \cdot 3 \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

So  $k = 42$

(b) (5 points) Construct two matrices  $A$  and  $B$  of appropriate dimensions such that

$$\text{rank}(AB) < \min\{\text{rank}(A), \text{rank}(B)\}.$$

Let  $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$   $B = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$ , then  $AB = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

$\text{rank}(A) = \text{rank}(B) = 1$  so  $\min\{\text{rank}(A), \text{rank}(B)\} = 1$

However  $\text{rank}(AB) = 0 < 1$ .

3. (10 points) For each of the following subsets of  $P_2$  (i.e., the vector space of polynomials with real coefficients and degree at most 2) determine whether it is a subspace. If that is the case, find its dimension.

(a) (5 points)  $S$  is the set of polynomials  $p \in P_2$  satisfying

$$p'(x) + p(x) = x^2.$$

Not a subspace - The zero polynomial  $0(x)$  does not lie in  $S$ :  
 $0'(x) + 0(x) = 0 + 0 = 0$

(b) (5 points)  $S$  is the set of polynomials  $p \in P_2$  verifying

$$p(x) + p(-x) = 0.$$

This is a subspace.

(i)  $0(x) \in S$  because  $0(x) + 0(-x) = 0 + 0 = 0$  ✓

(ii) Let  $p, q \in S$ . Then  $(p+q) \in S$  because

$$\begin{aligned} (p+q)(x) + (p+q)(-x) &= p(x) + q(x) + p(-x) + q(-x) \\ &= (p(x) + p(-x)) + (q(x) + q(-x)) = 0 + 0 = 0. \end{aligned}$$

(iii) Let  $p \in S$ ,  $\lambda \in \mathbb{R}$ . Then  $(\lambda p) \in S$  because

$$(\lambda p)(x) + (\lambda p)(-x) = \lambda p(x) + \lambda p(-x) = \lambda (p(x) + p(-x)) = \lambda \cdot 0 = 0.$$

To find a basis we determine a minimal spanning set. Take  $p(x) = ax^2 + bx + c$ . Suppose  $p(x) \in S$ . Then

$$\begin{aligned} 0 &= p(x) + p(-x) = ax^2 + bx + c + a(-x)^2 + b(-x) + c \\ &= 2ax^2 + 2c \end{aligned}$$

Therefore must have  $a = c = 0$ . So  $S$  is the span of  $\{x\}$ . So  $\{x\}$  is a basis for  $S$  and  $\dim(S) = 1$ .

4. (10 points) Compute the reduced row-echelon form for the matrix

$$\begin{bmatrix} 7 & 4 & 1 & 7 \\ 4 & 3 & 2 & 4 \\ 3 & 2 & 1 & 3 \end{bmatrix}$$

and deduce from there a basis and the dimension of its row space.

$$\begin{bmatrix} 7 & 4 & 1 & 7 \\ 4 & 3 & 2 & 4 \\ 3 & 2 & 1 & 3 \end{bmatrix} \xrightarrow{R_1 = -r_1 + r_2 + r_3} \begin{bmatrix} 0 & 1 & 2 & 0 \\ 4 & 3 & 2 & 4 \\ 3 & 2 & 1 & 3 \end{bmatrix} \xrightarrow{R_2 = r_2 - r_1} \begin{bmatrix} 0 & 1 & 2 & 0 \\ 1 & 1 & 1 & 1 \\ 3 & 2 & 1 & 3 \end{bmatrix}$$

$$\begin{matrix} R_1 = r_2 \\ R_2 = r_1 \end{matrix} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 0 \\ 3 & 2 & 1 & 3 \end{bmatrix} \xrightarrow{R_3 = r_3 - 3r_1} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 0 \\ 0 & -1 & -2 & 0 \end{bmatrix}$$

$$\begin{matrix} R_3 = r_2 + r_3 \\ R_1 = r_1 - r_2 \end{matrix} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -1 & 1 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Is the reduced row-echelon form.

$$\text{Basis for row space} = \text{set of non-zero rows of the reduced row-echelon form} = \left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \\ 0 \end{bmatrix} \right\}$$

$$\text{Dimension of row space} = 2.$$

5. (10 points) Let  $M_{2 \times 2}(\mathbb{R})$  denote the vector space of  $2 \times 2$  square matrices with real entries. Define  $T : M_{2 \times 2}(\mathbb{R}) \rightarrow M_{2 \times 2}(\mathbb{R})$  by

$$T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a+b & 0 \\ c & a+d \end{pmatrix}.$$

(a) (3 points) Show that  $T$  is a linear transformation.

$$T \left[ \begin{pmatrix} a & b \\ c & d \end{pmatrix} + \begin{pmatrix} e & f \\ g & h \end{pmatrix} \right] = T \begin{pmatrix} a+e & b+f \\ c+g & d+h \end{pmatrix} = \begin{pmatrix} a+e+b+f & 0 \\ c+g & a+e+d+h \end{pmatrix}$$

$$= \begin{pmatrix} a+b & 0 \\ c & a+d \end{pmatrix} + \begin{pmatrix} e+f & 0 \\ g & e+h \end{pmatrix} = T \begin{pmatrix} a & b \\ c & d \end{pmatrix} + T \begin{pmatrix} e & f \\ g & h \end{pmatrix}.$$

$$T \left[ \lambda \begin{pmatrix} a & b \\ c & d \end{pmatrix} \right] = T \begin{pmatrix} \lambda a & \lambda b \\ \lambda c & \lambda d \end{pmatrix} = \begin{pmatrix} \lambda a + \lambda b & 0 \\ \lambda c & \lambda a + \lambda d \end{pmatrix} = \lambda \begin{pmatrix} a+b & 0 \\ c & a+d \end{pmatrix} = \lambda T \begin{pmatrix} a & b \\ c & d \end{pmatrix}.$$

(b) (3 points) Determine a basis for  $\text{Ker}(T)$ . What is  $\dim[\text{Ker}(T)]$ ?

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \text{Ker}(T) \Leftrightarrow T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \Leftrightarrow \begin{pmatrix} a+b & 0 \\ c & a+d \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\Leftrightarrow -a + b = d, c = 0.$$

$$\Leftrightarrow \begin{pmatrix} a & b \\ c & d \end{pmatrix} = a \begin{pmatrix} 1 & -1 \\ 0 & -1 \end{pmatrix}$$

So  $\left\{ \begin{pmatrix} 1 & -1 \\ 0 & -1 \end{pmatrix} \right\}$  is a basis for  $\text{Ker}(T)$ . Its dimension is 1.

(c) (2 points) Find  $\dim[\text{Rng}(T)]$ .

By Rank-Nullity:

$$\dim M_{2 \times 2}(\mathbb{R}) = \dim(\text{Ker } T) + \dim(\text{Rng}(T))$$

$$4 = 1 + \dim(\text{Rng}(T)) \text{ so } \boxed{\dim(\text{Rng}(T)) = 3}$$

(d) (2 points) Is the matrix  $\begin{pmatrix} 1 & 0 \\ 2 & 3 \end{pmatrix}$  in the range of  $T$ ? Explain.

Yes it is.  $\begin{pmatrix} 1 & 0 \\ 2 & 3 \end{pmatrix} = \begin{pmatrix} 2-1 & 0 \\ 2 & 2+1 \end{pmatrix} = T \begin{pmatrix} 2 & -1 \\ 2 & 1 \end{pmatrix}.$

or  $T \begin{pmatrix} 1 & 0 \\ 2 & 2 \end{pmatrix}$  etc.

6. (10 points) Consider the matrix

$$A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}.$$

(a) (4 points) Determine its eigenvalues and their multiplicities.

Characteristic polynomial  $p(t) = \det(A - tI) = \begin{vmatrix} -t & 1 & 1 \\ 1 & -t & 1 \\ 1 & 1 & -t \end{vmatrix}$

$$= -t \begin{vmatrix} -t & 1 \\ 1 & -t \end{vmatrix} - 1 \begin{vmatrix} 1 & 1 \\ 1 & -t \end{vmatrix} + 1 \begin{vmatrix} 1 & -t \\ 1 & 1 \end{vmatrix} = -t(t^2 - 1) - (-t - 1) + (1 - t)$$

$$= -t(t-1)(t+1) + 2(t+1) = (t+1)(-t(t-1) + 2) = (t+1)(t^2 - t - 2)$$

$$= -(t+1)^2(t-2)$$

Eigenvalues:  $\lambda = -1$  multiplicity 2,  $\lambda = 2$  multiplicity 1

(b) (4 points) Compute the eigenspaces corresponding to each of the eigenvalues and their dimensions.

$\lambda = -1$ :  $(A - \lambda I)\vec{v} = \vec{0} \Leftrightarrow \begin{bmatrix} 1 & 1 & 1 & | & 0 \\ 1 & 1 & 1 & | & 0 \\ 1 & 1 & 1 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$   $x_2, x_3$  free  
 $x_1 = -x_2 - x_3$

$\Rightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$   $\Rightarrow$  eigenspace =  $\text{span} \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$   
of dimension 2.

$\lambda = 2$ :  $(A - 2I)\vec{v} = \vec{0} \Leftrightarrow \begin{bmatrix} -2 & 1 & 1 & | & 0 \\ 1 & -2 & 1 & | & 0 \\ 1 & 1 & -2 & | & 0 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2 + R_3} \begin{bmatrix} 0 & 0 & 0 & | & 0 \\ 1 & -2 & 1 & | & 0 \\ 1 & 1 & -2 & | & 0 \end{bmatrix}$

$R_1 \leftrightarrow R_2 + R_3$   
 $R_3 \leftrightarrow R_1$   
 $\sim \begin{bmatrix} 0 & 3 & -3 & | & 0 \\ 1 & -2 & 1 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 1 & | & 0 \\ 0 & 3 & -3 & | & 0 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$   $x_3$  free,  $x_2 = x_3$ ,  $x_1 = x_3$

$\Rightarrow$  eigenspace =  $\text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$  of dimension 1.

(c) (2 points) Conclude, with explanation, whether  $A$  is a defective or non-defective matrix.

$A$  is non-defective because the sum of the dimensions of its eigenspaces equals 3.

$A$  is  $3 \times 3$  matrix.

7. (10 points) Solve the initial value problem

$$y''' - 4y'' + 5y' - 2y = 0, \quad y(0) = 2, \quad y'(0) = 3, \quad y''(0) = 5.$$

Auxiliary polynomial:  $p(r) = r^3 - 4r^2 + 5r - 2$   
 $r=1$  is a root.  $p(r) = (r-1) \overbrace{r^2 - 3r + 2}^{\text{by long division.}}$   $(r-1)(r-1)(r-2)$

Roots  $r=1$  multiplicity 2  
 $r=2$  ——— 1.

General solution is  $y = c_1 e^t + c_2 e^t t + c_3 e^{2t}$   
 $y'(t) = c_1 e^t + c_2 (t+1)e^t + 2c_3 e^{2t}$   
 $y''(t) = c_1 e^t + c_2 (t+2)e^t + 4c_3 e^{2t}$

Setting  $t=0$ :

$$2 = y(0) = c_1 + 0 + c_3$$

$$3 = y'(0) = c_1 + c_2 + 2c_3$$

$$5 = y''(0) = c_1 + 2c_2 + 4c_3$$

By inspection set  $c_1 = c_3 = 1, c_2 = 0$ .

So  $y(t) = e^t + e^{2t}$

⊛ The long division

$$\begin{array}{r|l} r^3 - 4r^2 + 5r - 2 & r-1 \\ \underline{r^3 - r^2} & \underline{r^2 - 3r + 2} \\ -3r^2 + 5r - 2 & \\ \underline{-3r^2 + 3r} & \\ 2r - 2 & \\ \underline{2r - 2} & \\ 0 & \end{array}$$



8. (10 points) Determine the general solution to

$$y'' + 4y' + 4y = x e^{-x}.$$

$$y = y_c + y_p.$$

$y_c$ : Auxiliary polynomial is  $p(r) = r^2 + 4r + 4 = (r+2)^2$ .

$$\text{So } y_c = c_1 e^{-2x} + c_2 x e^{-2x}$$

$y_p$ : For the particular solution we try

$$y_p = A_0 e^{-x} + A_1 x e^{-x}.$$

$$y_p' = -A_0 e^{-x} + A_1 (1-x) e^{-x}$$

$$y_p'' = A_0 e^{-x} + A_1 (x-2) e^{-x}$$

~~Then~~ Substituting in the equation:

$$A_0 e^{-x} + A_1 (x-2) e^{-x} = \cancel{4A_0 e^{-x}} + \cancel{4A_1 (1-x) e^{-x}} + \cancel{4A_0 e^{-x}} + \cancel{4A_1 x e^{-x}} \\ \times e^{-x}. \quad \text{So}$$

$$(A_0 - 2A_1 + 4A_1) e^{-x} + (A_1 - 4A_1 + 4A_1) x e^{-x} = x e^{-x}. \quad (=)$$

$$(A_0 + 2A_1) e^{-x} + A_1 x e^{-x} = x e^{-x}.$$

Equating coefficients of  $e^{-x}$ :  $A_0 + 2A_1 = 0$

$$x e^{-x}: A_1 = 1$$

$$\Rightarrow \begin{cases} A_0 = -2 \\ A_1 = 1 \end{cases}$$

$$\text{So } \boxed{y(x) = c_1 e^{-2x} + c_2 x e^{-2x} - 2 e^{-x} + x e^{-x}}$$

9. (10 points) Find the general solution to

$$y'' + 2y' = e^{-x} + x.$$

$$y = y_c + y_p$$

$y_c$ : Auxiliary polynomial  $p(r) = r^2 + 2r = r(r+2)$

$$\text{So } y_c = c_1 + c_2 e^{-2x}.$$

$y_p$ : Try  $y_p = A e^{-x} + Bx + Cx^2$  zero is a root of  $p(r)$ .

$$y_p' = -A e^{-x} + B + 2Cx$$

$$y_p'' = A e^{-x} + 2C.$$

Substituting

$$A e^{-x} + 2C = 2A e^{-x} + 2B + 4Cx = e^{-x} + x. \quad \text{So}$$

$$-A e^{-x} + 4Cx + 2C + 2B = e^{-x} + x.$$

Equating coefficients of  $e^{-x}$ :  $-A = 1 \Rightarrow A = -1$

$x$ :  $4C = 1 \Rightarrow C = 1/4$

$1$ :  $2C + 2B = 0 \Rightarrow B = -1/4$

$$\text{So } y(x) = c_1 + c_2 e^{-2x} - e^{-x} - \frac{x}{4} + \frac{x^2}{4}.$$

10. (10 points) Solve the initial value problem

$$\begin{cases} x_1' = -2x_1 + x_2, & x_2' = x_1 - 2x_2, \\ x_1(0) = 3, & x_2(0) = 1. \end{cases}$$

$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ ,  $A = \begin{bmatrix} -2 & 1 \\ 1 & -2 \end{bmatrix}$  so the system becomes

$$\vec{x}' = A\vec{x}, \quad \vec{x}(0) = \begin{bmatrix} 3 \\ 1 \end{bmatrix}.$$

We find the eigenvalues / eigenvectors of  $A$ :

~~Characteristic~~ Characteristic polynomial

$$\begin{aligned} p(t) &= \det(A - tI) = \begin{vmatrix} -2-t & 1 \\ 1 & -2-t \end{vmatrix} = (2+t)^2 - 1^2 \\ &= (2+t-1)(2+t+1) = (1+t)(3+t) \end{aligned}$$

$$\boxed{\lambda = -1, -3}$$

$$\lambda = -1: (A + I)\vec{v} = \vec{0} \Leftrightarrow \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow v_1 = v_2 \Rightarrow \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\lambda = -3: (A + 3I)\vec{v} = \vec{0} \Leftrightarrow \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow v_1 = -v_2 \Rightarrow \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

So

$$\vec{x} = c_1 e^{-t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 e^{-3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}.$$

$$\text{Setting } t=0 \text{ gives } \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} c_1 + c_2 \\ c_1 - c_2 \end{bmatrix} \Rightarrow \begin{cases} c_1 = 2 \\ c_2 = 1 \end{cases}$$

$$\Rightarrow \vec{x} = 2e^{-t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + e^{-3t} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\text{In terms of } x_1, x_2 \quad \begin{cases} x_1 = 2e^{-t} + e^{-3t} \\ x_2 = 2e^{-t} - e^{-3t} \end{cases}$$