

MATH 165 (SUMMER '22, SESH B2)

FINAL EXAM
SOLUTIONS

(EVENING SLOT)

2.

(a)

$$\frac{dy}{dx} + 3x^2y = 3x^5.$$

INTEGRATING FACTOR = $e^{\int p(x) dx}$, $p(x) = 3x^2$

$$= e^{x^3}$$

$$\therefore \frac{d}{dx} (e^{x^3} y) = e^{x^3} \frac{dy}{dx} + 3x^2 e^{x^3} y = 3 e^{x^3} x^5$$

$$\Rightarrow e^{x^3} y = \int 3x^5 e^{x^3} dx$$

$$u = x^3 \Rightarrow du = 3x^2 dx$$

$$\begin{aligned}\therefore e^{x^3} y &= \int x^3 e^{x^3} (3x^2 dx) = \int u e^u du \\&= ue^u - \int e^u du \\&= ue^u - e^u + C \\&= x^3 e^{x^3} - e^{x^3} + C\end{aligned}$$

$$\Rightarrow y = x^3 - 1 + C e^{-x^3}$$

(b)

$$\frac{dy}{dx} = x + x^2 + xy^2 + x^2y^2, \quad y(0) = 0.$$

$$x + x^2 + y^2 + x^2y^2 = (x+y^2)(1+y^2)$$

$$\Rightarrow \frac{dy}{1+y^2} = (x+x^2) dx$$

$$\Rightarrow \int_0^y \frac{dy}{1+y^2} = \int_0^x (x+x^2) dx \quad (\because y(0)=0)$$

$$\Rightarrow \operatorname{Arctan} y = \frac{x^2}{2} + \frac{x^3}{3} \Rightarrow y = \tan\left(\frac{x^2}{2} + \frac{x^3}{3}\right)$$

(c)

$$\frac{dy}{dx} + \frac{y}{x} = 4, \quad y(1) = 2.$$

$$\text{E.F.} = e^{\int \frac{dx}{x}} = e^{\ln x} = x$$

$$\therefore \frac{d}{dx}(xy) = x\frac{dy}{dx} + y = 4x$$

$$\Rightarrow \int_1^x \frac{d}{dx}(xy) dx = \int_1^x 4x dx = 2x^2 - 2$$

$$\Rightarrow xy - (1)(2) = 2x^2 - 2 \quad (\because y(1)=2)$$

$$\Rightarrow y = 2x.$$

(d)

$$\left(\frac{dy}{dx}\right)^7 - x^7 y = 0.$$

$$\Rightarrow \frac{dy}{dx} = (x^7 y)^{1/7} = x y^{1/7}$$

$$\Rightarrow y^{-1/7} dy = x dx$$

$$\Rightarrow \frac{y^{6/7}}{6/7} = \frac{x^2}{2} + C \Rightarrow y = \left(\frac{3x^3}{7} + C^1\right)^{7/6}$$

3. (25 points) Consider

$$A = \begin{bmatrix} 2 & 3 & -3 \\ -1 & -2 & 2 \\ 4 & 6 & -7 \end{bmatrix}$$

- (a) Compute $\det A$. Why is A invertible?
(b) Using elementary row operations, compute A^{-1} .
(c) Compute $\det A^{-1} + \det A$.

(a) $\det A = 2 \begin{vmatrix} -2 & 2 \\ 6 & -7 \end{vmatrix} - 3 \begin{vmatrix} -1 & 2 \\ 4 & -7 \end{vmatrix} + (-3) \begin{vmatrix} -1 & -2 \\ 4 & 6 \end{vmatrix}$

$$= 2(2) - 3(-1) + (-3)(2) = 1 \neq 0$$

(c) $\det A^{-1} + \det A$

$$= \frac{1}{\det A} + \det A$$

$$= \frac{1}{1} + 1 = 2$$

$\Rightarrow A$ is INVERSE.

(b)

$$\left[\begin{array}{ccc|ccc} 2 & 3 & -3 & 1 & 0 & 0 \\ -1 & -2 & 2 & 0 & 1 & 0 \\ 4 & 6 & -7 & 0 & 0 & 1 \end{array} \right]$$

↓ EROs

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & 2 & 3 & 0 \\ 0 & 1 & 0 & 1 & -2 & -1 \\ 0 & 0 & 1 & 2 & 0 & -1 \end{array} \right]$$

$$\therefore A^{-1} = \left[\begin{array}{ccc} 2 & 3 & 0 \\ 1 & -2 & -1 \\ 2 & 0 & -1 \end{array} \right]$$

4. (30 points) Consider the matrix

$$\begin{bmatrix} 4 & 3 & 2 & -1 \\ 5 & 4 & 3 & -1 \\ -2 & -2 & -1 & 2 \\ 11 & 6 & 4 & 1 \end{bmatrix}.$$

SEE

SOLNS

T9

SAMPLE

MID TERM 2.

5. (15 points)

Determine whether the set S is linearly independent in the vector space V for the following.

(a) $V = P_{10}(\mathbb{R})$, $S = \{1, 1-x, (1-x)^{10}\}$.

$$w = \begin{vmatrix} 1 & 1-x & (1-x)^{16} \\ 0 & -1 & -10(1-x)^9 \\ 0 & 0 & 90(1-x)^8 \end{vmatrix} = -99(1-x)^8 \neq 0$$

(e.g. if $x=0$).

$\therefore L.I.$

$$(b) V = V_2(0, 1), S = \left\{ \begin{bmatrix} t \\ t^4 \end{bmatrix}, \begin{bmatrix} t^4 \\ t \end{bmatrix} \right\}.$$

$$W = \begin{vmatrix} t & t^4 \\ t^4 & t \end{vmatrix} = t^2 - t^8 \neq 0 \quad (\text{e.g. if } t = \frac{1}{2})$$

∴ L.I.

$$(c) \ V = V_2(-\infty, \infty), S = \left\{ \begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} \cos^2 t \\ \sin^2 t \\ 1 \end{bmatrix}, \begin{bmatrix} \sin^2 t \\ \cos^2 t \\ 1 \end{bmatrix} \right\}$$

$$\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix} = \begin{bmatrix} \cos^2 t \\ \sin^2 t \\ 1 \end{bmatrix} + \begin{bmatrix} \sin^2 t \\ \cos^2 t \\ 1 \end{bmatrix}$$

$\therefore L.D.$

6. (30 points)

Compute the eigenvalues and eigenspaces of the following matrix.

$$\begin{bmatrix} 0 & 2 & -2 \\ -2 & 4 & -2 \\ -2 & 2 & 0 \end{bmatrix}$$

SEE

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SAMPLE

FINAL.

7. (25 points)

Let $P(D) = D^2 + 3D + 2$ and $Q(D) = D + 2$ be two polynomial differential operators.

(a) Show that $Q(D)$ annihilates e^{-2x} .

(b) Solve the differential equation $P(D)Q(D)y = 0$.

(c) Using your solution to the previous part, find the general solution to the differential equation $P(D)y = 2e^{-2x}$. - (3)

$$\begin{aligned} \text{(a)} \quad Q(D)e^{-2x} &= (D+2)e^{-2x} = D(e^{-2x}) + 2e^{-2x} \\ &= -2e^{-2x} + 2e^{-2x} = 0 \end{aligned}$$

$$(b) \quad (D^2 + 3D + 2)(D + 2) y = 0$$

AUXILIARY EQUATION

$$(D^2 + 3D + 2)(D + 2) = 0$$
$$\Rightarrow (D+2)^2(D+1)$$

$$\begin{aligned} \lambda &= -2 && (\text{w/ MULT. 2}) \\ \lambda &= -1 && (\text{w/ MULT. 1}) \end{aligned}$$

$$\therefore y = c_1 e^{-2x} + c_2 e^{-x} + c_3 x e^{-2x}$$


 $P(D), y_c$


 $Q(D), y_p$

(C) PLUGGING y_p INTO (A) :

$$P(D)y_p = 2e^{-2x}$$
$$(D^2 + 3D + 2)(c_3 x e^{-2x}) = 2e^{-2x}$$

$$\Rightarrow c_3 e^{-2x} = 2e^{-2x}$$

$$\Rightarrow c_3 = 2$$

$$\therefore y = y_c + y_p = c_1 e^{-2x} + c_2 e^{-x} + 2x e^{-2x}$$

8. (10 points)

- (a) Find a first order linear system of differential equations such that solving it is equivalent to solving the differential equation in 7(b).
- (b) Rewrite this as a vector differential equation.

$$(D^2 + 3D + 2)(D + 2)y = 0 \leadsto \frac{d^3y}{dt^3} + 5\frac{d^2y}{dt^2} + 8\frac{dy}{dt} + 4y = 0$$

$$x_1 = y, \quad x_2 = \frac{dy}{dt}, \quad x_3 = \frac{d^2y}{dt^2}$$

$$\Rightarrow \text{SYSTEM : } \frac{dx_1}{dt} = x_2, \quad \frac{dx_2}{dt} = x_3$$

$$\frac{dx_3}{dt} = -4x_1 - 8x_2 - 5x_3$$

$$\Rightarrow \frac{d\vec{x}}{dt} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -4 & -8 & -5 \end{bmatrix} \vec{x}$$

9. (25 points)

Consider

$$A = \begin{pmatrix} 5 & -6 \\ 6 & 5 \end{pmatrix}$$

- (a) Find the eigenvalues and eigenvectors of A .
- (b) Using this, solve the initial value problem

$$\frac{d\vec{x}}{dt} = A\vec{x}, \quad \vec{x}(0) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$P(\lambda) = \begin{vmatrix} 5-\lambda & -6 \\ 6 & 5-\lambda \end{vmatrix} = (5-\lambda)^2 + 36$$

$$\Rightarrow \text{E.V.} = \lambda = 5 \pm 6i$$

FOR $\lambda = 5 - 6i$

$$A - \lambda I = \begin{bmatrix} 6i & -6 \\ 6 & 6i \end{bmatrix}$$

\brace{ERO}

$$\begin{bmatrix} i & -1 \\ 0 & 0 \end{bmatrix}$$

$$\therefore iv_1 - v_2 = 0$$

$$\therefore v_1 = t, v_2 = it \Rightarrow \begin{bmatrix} 1 \\ i \end{bmatrix} \text{ u on e.v.}$$

$\therefore 5+6i$, $\begin{bmatrix} 1 \\ -i \end{bmatrix}$ IS THE OTHER EIGENPAIR.

$$(b) \quad \vec{x} = c_1 \vec{x}_1 + c_2 \vec{x}_2$$

WHERE

$$\vec{x}_1 = e^{(5+6i)t} \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

$$\vec{x}_2 = e^{(5-6i)t} \begin{bmatrix} 1 \\ i \end{bmatrix}$$

$$\therefore c_1 x_1(0) + c_2 x_2(0) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \Rightarrow c_1 \begin{bmatrix} 1 \\ -i \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ i \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\begin{aligned} \Rightarrow c_1 + c_2 &= 0 \\ -ic_1 + ic_2 &= 1 \end{aligned}$$

$$\Rightarrow c_1 = -\frac{1}{2i}, \quad c_2 = \frac{1}{2i}$$

$$\therefore \vec{x} = -\frac{1}{2i} x_1(t) + \frac{1}{2i} x_2(t)$$

$$= \begin{bmatrix} -e^{st} \sin t \\ e^{st} \cos t \end{bmatrix}$$