

MATH 165 (SUMMER '22, SESS B2)

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OFF HRS:

T - 9:00 PM - 10:00 PM (ET)

F - 3:00 PM - 4:00 PM (ET)

LECTURES:

9:00 AM - 11:15 AM (ET)

M, T, W, R

Zoom ID:

979-4693-6650

COURSE

WEB PAGE

<https://people.math.rochester.edu/grads/asahay/summer2022/math165/index.html>

SHORT URL: bit.ly/sahay165

NOTE: ALL
IMAGES ARE
FROM THE
(GOOD & ANMIN
4TH EDITION)

ANNOUNCEMENTS / NOTES

1. MATERIALS FOR LECTURES 1-7 ARE UPLOADED.

2. WW 03 - WAS DUE SATURDAY (9th JULY) AT 11:00 PM ET

EXT? ← WW 04 - IS DUE TUESDAY (12th JULY) AT 11:00 PM ET

WW 05 - IS DUE SATURDAY (16th JULY) AT 11:00 PM ET

3. MIDTERM 1 TODAY !

4. REMINDER : PLEASE KEEP VIDEOS ON, IF POSSIBLE !

§ 2.6 INVERSE OF
A SQUARE MATRIX

$A \rightarrow n \times n$ MATRIX.

(Q: DOES THERE
EXIST B:)

$$AB = I_n$$

,

$$BA = I_n$$

MOTIVATION: $A\vec{x} = \vec{b}$

$$\begin{cases} a_{11}x_1 + \dots + a_{1n}x_n = b_1 \\ \vdots \\ a_{n1}x_1 + \dots + a_{nn}x_n = b_n \end{cases}$$

SUPPOSE , $\exists B$, s.t.

$$BA = I_n$$

$$A \vec{x} = \vec{b}$$

\Rightarrow

$$B(A \vec{x}) = B \vec{b}$$

(PREMULTIPLY
By B)

\parallel

$$(BA) \vec{x} = (I_n) \vec{x}$$

$$= I_n \vec{x} = \vec{x}$$

$$I_n = \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix}$$

$$\vec{x} = B \vec{b}$$

$B \vec{b} = A \vec{x}$
} FIXED

$$\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = I \begin{bmatrix} \vdots \\ \vdots \end{bmatrix}$$

$$\begin{matrix} \nearrow m \times n \\ A I_n = I_m A = A \end{matrix}$$

Theorem 2.6.1

Let A be an $n \times n$ matrix. Suppose B and C are both $n \times n$ matrices satisfying

$$AB = \underline{BA} = I_n \quad (2.6.4)$$

$$AC = CA = I_n \quad (2.6.5)$$

respectively. Then $B = C$.

Pf

$$B = B I_n = B (AC)$$

$$= (B A) C = I_n C = C$$

$$\Rightarrow B = C \quad \mathbf{!}$$

DEFINITION 2.6.2

Let A be an $n \times n$ matrix. If there exists an $n \times n$ matrix A^{-1} satisfying

$$AA^{-1} = A^{-1}A = I_n,$$

then we call A^{-1} *the* matrix **inverse** to A , or just *the* inverse of A . We say that A is **invertible** if A^{-1} exists.

Invertible matrices are sometimes called **nonsingular**, while matrices that are not invertible are sometimes called **singular**.

~
INVERTIBLE

Example 2.6.3

If $A = \begin{bmatrix} 1 & -1 & 2 \\ 2 & -3 & 3 \\ 1 & -1 & 1 \end{bmatrix}$, verify that $B = \begin{bmatrix} 0 & -1 & 3 \\ 1 & -1 & 1 \\ 1 & 0 & -1 \end{bmatrix}$ is the inverse of A .

$$AB = \begin{bmatrix} 1 & -1 & 2 \\ 2 & -3 & 3 \\ 1 & -1 & 1 \end{bmatrix} \begin{bmatrix} 0 & -1 & 3 \\ 1 & -1 & 1 \\ 1 & 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$BA = \begin{bmatrix} 0 & -1 & 3 \\ 1 & -1 & 1 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & -1 & 2 \\ 2 & -3 & 3 \\ 1 & -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\Rightarrow BA = AB = I \quad \}$$

$$B = A^{-1}.$$

Theorem 2.6.5

If A^{-1} exists, then the $n \times n$ system of linear equations

$$A\mathbf{x} = \mathbf{b}$$

has the *unique* solution

$$\mathbf{x} = A^{-1}\mathbf{b}$$

for every \mathbf{b} in \mathbb{R}^n .

Pf

$$\Rightarrow A^{-1}(A\mathbf{x}) = A^{-1}\mathbf{b}$$

$$\Rightarrow \mathbf{x} = \mathbb{I}\mathbf{x} = (A^{-1}A)\mathbf{x} = A^{-1}(A\mathbf{x}) = A^{-1}\mathbf{b}$$

$$\Rightarrow \text{Rank } A = \text{Rank } A^{\#} = n$$

$$A^{\#} \downarrow = [A \mid \mathbf{b}]$$

Theorem 2.6.6

An $n \times n$ matrix A is invertible if and only if $\text{rank}(A) = n$.

Pf (\Rightarrow) A IS INVERTIBLE

$\Rightarrow A \vec{x} = \vec{b}$ HAS A UNIQUE SOLN.

$\Rightarrow \text{rank } A = \text{rank } [A | \vec{b}] = n$

(\Leftarrow) $\text{rank } A = n$

$$AX = I$$

$$I = \begin{bmatrix} \vec{e}_1 & \vec{e}_2 & \dots & \vec{e}_n \\ 1 & & & \\ & 1 & & \\ & & \dots & \\ & & & 1 \\ 0 & & & \\ & & & \vdots \\ & & & 0 \end{bmatrix}$$

$$I = [\vec{e}_1 \quad \dots \quad \vec{e}_n]$$

$$\vec{e}_j = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \textcircled{1} \\ 0 \\ \vdots \\ 0 \end{bmatrix} \rightarrow j^{\text{th}} \text{ entry}$$

$$X = [\vec{x}_1 \quad \dots \quad \vec{x}_n]$$

$$AX = A [\vec{x}_1 \quad \dots \quad \vec{x}_n] = [A\vec{x}_1 \quad A\vec{x}_2 \quad \dots \quad A\vec{x}_n] = [\vec{e}_1 \quad \dots \quad \vec{e}_n]$$

$$A \vec{x}_j = \vec{e}_j \rightarrow \vec{x}_j \text{ EXISTS \& IS UNIQUE}$$

$$\text{rank } A = \text{rank } [A | \vec{e}_j] = n$$

$$A^{-1} = [\vec{x}_1 \quad \dots \quad \vec{x}_n]$$

\Rightarrow A IS INVERTIBLE

GAUSS - JORDAN METHOD FOR INVERSES

$$A X = I_n$$

$$X = \begin{bmatrix} \vec{x}_1 & \dots & \vec{x}_n \end{bmatrix}$$

$$I_n = \begin{bmatrix} \vec{e}_1 & \dots & \vec{e}_n \end{bmatrix}$$

$$\boxed{A \vec{x}_j = \vec{e}_j}$$

$$\vec{e}_j = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix}$$

*j*th entry

$$A \vec{x} = \vec{b}$$

$$\left[\begin{array}{c|c} A & b \end{array} \right]$$

ERO
→

ROW ECHELON
FORM
(GAUSSIAN)

ERO
→

REDUCED
FORM
ROW ECHELON

(GAUSS-JORDAN)

$$[A | b]$$

ERO
→
GAUSS-JORDAN

$$\left[\begin{array}{ccc|c} 1 & & 0 & c_1 \\ & \ddots & & \vdots \\ 0 & & 1 & c_n \end{array} \right]$$

$A \rightarrow n \times n$ MATRIX
INVERTIBLE

$A \vec{x} = \vec{b}$, $A \rightarrow$ INVERTIBLE ($n \times n$)

$$[A | \vec{b}]$$

EROS
→

$$\left[I_n | \vec{x} \right]$$

$$[A | \vec{b}']$$

SAME
EROS
→

$$\left[I_n | \vec{x}' \right]$$

$$(A \vec{x}' = \vec{b}')$$

$$A \vec{x}_j = \vec{e}_j$$

$$\left[A \mid \vec{e}_j \right] \xrightarrow[\text{ERO}_s]{\text{SAME}} \left[I_n \mid \vec{x}_j \right]$$

$$\left[A \mid \underbrace{\vec{e}_1 \mid \vec{e}_2 \mid \dots \mid \vec{e}_n}_{I_n} \right] \xrightarrow[\text{ERO}_s]{\text{SAME}} \left[I_n \mid \underbrace{\vec{x}_1 \mid \vec{x}_2 \mid \dots \mid \vec{x}_n}_X \right]$$

$$\left[A \mid I_n \right] \xrightarrow{\text{ERO}_s} \left[I_n \mid X \right]$$

ALGO : A^{-1} ,

$$\left[A \mid I_n \right]$$

} EROs FOR REDUCED ROW
ECHELOM FORM

$$\left[I_n \mid A^{-1} \right]$$

Example 2.6.8Find A^{-1} if $A = \begin{bmatrix} 1 & 1 & 3 \\ 0 & 1 & 2 \\ 3 & 5 & -1 \end{bmatrix}$.

$$[A \mid I]$$

$$\left[\begin{array}{ccc|ccc} \boxed{1} & 1 & 3 & 1 & 0 & 0 \\ 0 & 1 & 2 & 0 & 1 & 0 \\ 3 & 5 & -1 & 0 & 0 & 1 \end{array} \right]$$

 $A_{13}(-3)$

$$\left[\begin{array}{ccc|ccc} 1 & 1 & 3 & 1 & 0 & 0 \\ 0 & \boxed{1} & 2 & 0 & 1 & 0 \\ 0 & 2 & -10 & -3 & 0 & 1 \end{array} \right]$$

 $A_{21}(-1)$ $A_{23}(-2)$

$A_{11}(-1)$
 $A_{22}(-2)$

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 1 & -1 & 0 \\ 0 & 1 & 2 & 0 & 1 & 0 \\ 0 & 0 & -14 & -3 & -2 & 1 \end{array} \right]$$

$\downarrow M_3(-1/14)$

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 1 & -1 & 0 \\ 0 & 1 & 2 & 0 & 1 & 0 \\ 0 & 0 & 1 & 3/14 & 1/7 & -1/14 \end{array} \right]$$

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 1 & -1 & 0 \\ 0 & 1 & 2 & 0 & 1 & 0 \\ 0 & 0 & 1 & \frac{3}{14} & \frac{1}{7} & -\frac{1}{14} \end{array} \right]$$

$\downarrow A_{32}(-2)$
 $\downarrow A_{31}(-1)$

$$\left[\begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{11}{14} & -\frac{8}{7} & \frac{1}{14} \\ 0 & 1 & 0 & -\frac{3}{7} & \frac{5}{7} & \frac{1}{7} \\ 0 & 0 & 1 & \frac{3}{14} & \frac{1}{7} & -\frac{1}{14} \end{array} \right] \xrightarrow{A^{-1}}$$

Example 2.6.9Continuing the previous example, use A^{-1} to solve the system

$$x_1 + x_2 + 3x_3 = 2,$$

$$x_2 + 2x_3 = 1,$$

$$3x_1 + 5x_2 - x_3 = 4.$$

$$A\vec{x} = \begin{bmatrix} 2 \\ 1 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \vec{x} = A^{-1} \begin{bmatrix} 2 \\ 1 \\ 4 \end{bmatrix} = \begin{bmatrix} 11/14 & -8/7 & 1/14 \\ -3/7 & 5/7 & 1/7 \\ 3/14 & 1/7 & -1/14 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ 4 \end{bmatrix}$$

Theorem 2.6.10

Let A and B be invertible $n \times n$ matrices. Then

1. A^{-1} is invertible and $(A^{-1})^{-1} = A$.

2. AB is invertible and $(AB)^{-1} = B^{-1}A^{-1}$.

3. A^T is invertible and $(A^T)^{-1} = (A^{-1})^T$.