

Introduction to rough paths

① Intro

Basic problem in stock analysis Give meaning to

$$\dot{y}_t = b(y_t) dt + \sigma(y_t) \dot{B}_t$$

where

b, σ regular enough coeff

\dot{B} random forcing

Important variant Stochastic PDEs like

$$\partial_t u_t(x) = \Delta u_t(x) + \sigma(u) \dot{w}_t(x)$$

Brownian motion Gaussian process s.t.

$$B_0 = 0, \quad B_t \sim \mathcal{N}(0, t),$$

$\{\delta B_{t_j t_{j+1}}; j = 1, \dots, n\}$ independent

↳ Easy generalization to (B^1, \dots, B^d)

Problem with B Not differentiable

$$B \in C^{\frac{1}{2}-\varepsilon}(\Omega, \mathbb{T}), \quad \forall \mathbb{T}$$

Integral equation Recast sde as

$$y_t = a + \int_0^t b(y_r) dr + \int_0^t \sigma(y_r) dB_r$$

$$dy_t = \int_0^t b(y_r) dr + \int_0^t \sigma(y_r) dB_r$$

Main step Define

$$\int_0^t y_r dB_r,$$

for a reasonable class of processes y .

Aim Talk about 3 settings

- (i) Young (1936)
- (ii) Itô (1943)
- (iii) Rough paths (1998)

② Young integration

Aim consider α -Hölder on $(0, T]$

$x, y \in C^\alpha$, with $\alpha > \frac{1}{2}$

We wish to define

$$\int_s^t y_r dx_r = \lim_{n \rightarrow \infty} \sum y_{t_i} \delta x_{t_i, t_{i+1}}, \quad \equiv I_{st}^n$$

where $t_i = t_i^n = \frac{(t-s)}{2^n} i + s$

strategy Define

$$\int_s^t y_r dx_r = I_{st}^0 + \sum_{n=0}^{\infty} (I_{st}^{n+1} - I_{st}^n)$$

Decomposition Write

$$I_{st}^n = \sum_{i=0}^{2^n-1} y_{t_i^n} \delta x_{t_i^n, t_{i+1}^n}$$

$$= \sum_{i=0}^{2^n-1} y_{t_{2i}^{n+1}} \left(\delta x_{t_{2i}^{n+1}, t_{2i+1}^{n+1}} + \delta x_{t_{2i+1}^{n+1}, t_{2i+2}^{n+1}} \right)$$

$$I_{st}^{n+1} = \sum_{i=0}^{2^{n+1}-1} y_{t_{2i}^{n+1}} \delta x_{t_{2i}^{n+1}, t_{2i+1}^{n+1}} + y_{t_{2i+1}^{n+1}} \delta x_{t_{2i+1}^{n+1}, t_{2i+2}^{n+1}}$$

$$\Rightarrow I_{st}^{n+1} - I_{st}^n$$

$$= \sum_{i=0}^{2^n-1} \delta y_{t_{2i}^{n+1}, t_{2i+1}^{n+1}} \delta x_{t_{2i+1}^{n+1}, t_{2i+2}^{n+1}}$$

Bounds Recall: $x, y \in C^\alpha$

$$|I_{st}^{nm} - I_{st}^n|$$

$$\leq \sum_{i=0}^{n-1} |\delta y_{t_{2i} t_{2i+1}}| |\delta x_{t_{2i} t_{2i+2}}|$$

$$\lesssim \frac{1}{2^{n(2\alpha-1)}} \Rightarrow \sum |I_{st}^{nm} - I_{st}^n| < \infty$$

if $\alpha > \frac{1}{2}$

Conclusion For $\alpha > \frac{1}{2}$,

$\int_s^t y_r dx_r$ defined if $x, y \in C^\alpha$

③ Itô integration

Hyp • y_s depends "on the past"

• $x \equiv$ Brownian motion

$\Rightarrow y_s \perp \delta x_{st}$ if $s < t$

Bound

$$\mathbb{E} \left\{ |I_{st}^{n+1} - I_{st}^n|^2 \right\}$$

$$= \sum_{i,j=0}^{2^n-1} \mathbb{E} \left\{ \delta y_{t_{2^i}, t_{2^{i+1}}} \delta x_{t_{2^j}, t_{2^{j+2}}} \right. \\ \left. \delta y_{t_{2^j}, t_{2^{j+1}}} \delta x_{t_{2^{j+1}}, t_{2^{j+2}}} \right\}$$

$$\stackrel{II}{=} \sum_{i=0}^{2^n-1} \mathbb{E} \left\{ (\delta y_{t_{2^i}, t_{2^{i+1}}})^2 (\delta x_{t_{2^{i+1}}, t_{2^{i+2}}})^2 \right\}$$

$$\stackrel{III}{=} \sum_{i=0}^{2^n-1} \mathbb{E} \left[(\delta y_{t_{2^i}, t_{2^{i+1}}})^2 \right] \mathbb{E} \left[(\delta x_{t_{2^{i+1}}, t_{2^{i+2}}})^2 \right]$$

Rmk If

• x BM

• $y = f(x)$ or $dy = \sigma(y) dx$

Then

$$\mathbb{E} \left[(\delta y_{t_{2^i}, t_{2^{i+1}}})^2 \right] \asymp \frac{1}{2^n} \quad \mathbb{E} \left[(\delta x_{t_{2^{i+1}}, t_{2^{i+2}}})^2 \right] \asymp \frac{1}{2^n}$$

Conclusion we have

$$\mathbb{E}\{|I_{st}^{nm} - I_{st}^n|^2\} \lesssim \frac{1}{2^n}$$

$\Rightarrow I_{st}^n$ converges as in Young case

Remark

- This convergence is in $L^2(\mathcal{R})$
- It relies on a probabilistic structure

④ Rough paths

Setting for x we assume

(i) $x \in C^\alpha$ with $\frac{1}{2} \leq \alpha < \frac{1}{3}$

(ii) There exists

$$\mathbb{X}_{st}^{z, ij} = \int_{s < r_1 < r_2 < t} dx_{r_1}^i dx_{r_2}^j$$

and $x \in C^{2\alpha}$

Called rough path
above x

Rmk

- Existence of \mathbb{Z}^2 not automatic
- Has to be proved by probabilistic arg
- Otherwise theory is deterministic

setting for y

$$\overbrace{dy_{st}}^{C^\alpha} = \overbrace{y_s^x}_{=} \overbrace{dx_{st}}^{C^\alpha} + \overbrace{R_{st}}^{C^{2\alpha}}$$

\Downarrow
Remainder, more regular

Heuristics we have

$$\begin{aligned} \int_s^t y_r dx_r &= y_s dx_{st} + \int_s^t dy_{sr} dx_r \\ &= y_s dx_{st} + \int_s^t (y_s dx_{sr} + R_{sr}) dx_r \\ &= y_s dx_{st} + y_s \mathbb{Z}_{st}^2 + \underbrace{\int_s^t R_{sr} dx_r}_{\simeq \text{Young integral}} \end{aligned}$$

What can we do with RP

- Solve very general noisy systems
- Regularity structures: SPDEs
- Signatures & links to algebra, data analysis