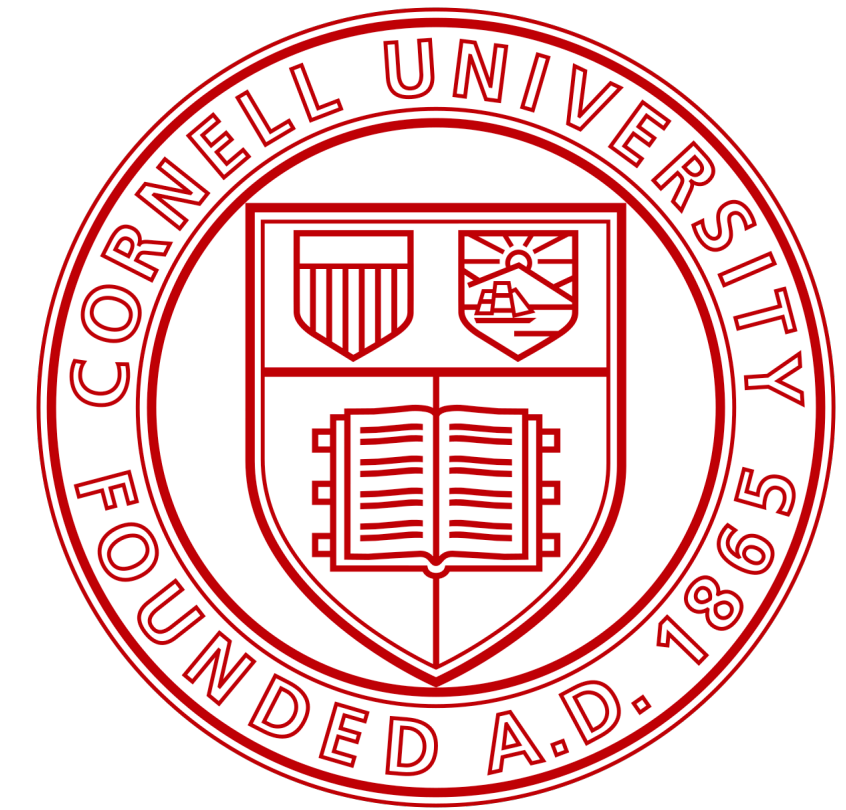


# Low Tensor-Train Rank Methods to Solve Sylvester Tensor Equations

**Tianyi Shi**  
**Cornell University**



Alex Townsend



Max Ruth

# Sylvester matrix equation

$$AX + XB^T = F$$

$$A \in \mathbb{C}^{n_1 \times n_1}, \quad B \in \mathbb{C}^{n_2 \times n_2}, \quad F \in \mathbb{C}^{n_1 \times n_2}$$

# 3D Sylvester tensor equation

$$\mathcal{X} \times_1 A + \mathcal{X} \times_2 B + \mathcal{X} \times_3 C = \mathcal{F}$$

$$A \in \mathbb{C}^{n_1 \times n_1}, \quad B \in \mathbb{C}^{n_2 \times n_2}, \quad C \in \mathbb{C}^{n_3 \times n_3}, \quad \mathcal{F} \in \mathbb{C}^{n_1 \times n_2 \times n_3}$$

Example: Poisson w/ FD

$$-(u_{xx} + u_{yy} + u_{zz}) = f \text{ on } \Omega = [-1, 1]^3$$

$$u|_{\partial\Omega} = 0$$

k-mode product for a tensor  $\mathcal{X} \in \mathbb{C}^{n_1 \times \dots \times n_d}$  and a matrix  $A \in \mathbb{C}^{n_k \times n_k}$

$$(\mathcal{X} \times_k A)_{i_1, \dots, i_{k-1}, j, i_{k+1}, \dots, i_d} = \sum_{i_k=1}^{n_k} \mathcal{X}_{i_1, \dots, i_d} A_{j, i_k}$$

$$\mathcal{X} \times_1 K + \mathcal{X} \times_2 K + \mathcal{X} \times_3 K = \mathcal{F}$$

$$K = -\frac{1}{h^2} \begin{bmatrix} 2 & -1 & & \\ -1 & \ddots & \ddots & \\ & \ddots & \ddots & -1 \\ & & -1 & 2 \end{bmatrix}$$

# Alternating Direction Implicit (ADI) method

[Wachspress, 2008]

“Iterative” method for Sylvester matrix equation  $AX - XB^T = F$

1. Select shift parameters  $p$  and  $q$  each of length  $\ell$  based on spectra of  $A$  and  $B$ .
2. For  $1 \leq j \leq \ell$ 
  - Solve  $(A - q_j I)X = F + X(B - q_j I)^T$ .
  - Solve  $X(B - p_j I)^T = (A - p_j I)X - F$ .

# Factored ADI (fADI) [Benner, Li & Truhar, 2009]

“Iterative” method for Sylvester matrix equation  $AX - XB^T = UV^T$   
 $X = ZDY^T$  rank  $r$

1. Select shift parameters  $p$  and  $q$  each of length  $\ell$  based on spectra of  $A$  and  $B$ .
2. Solve  $(A - q_1 I)Z_1 = U$  and  $(B - \bar{p}_1 I)Y_1 = V$ . Set  $Z = Z_1$  and  $Y = Y_1$ .
3. Let  $D = (q_1 - p_1)I$ .
4. For  $1 \leq j \leq \ell - 1$ 
  - Solve  $(A - q_{j+1} I)Z_{j+1} = (q_{j+1} - p_j)Z_j$ . Set  $Z_{j+1} = Z_{j+1} + Z_j$  and  $Z = [Z \ Z_{j+1}]$ .
  - Solve  $(B - \bar{p}_{j+1} I)Y_{j+1} = (\bar{p}_{j+1} - \bar{q}_j)Y_j$ . Set  $Y_{j+1} = Y_{j+1} + Y_j$  and  $Y = [Y \ Y_{j+1}]$ .
  - Set  $D = \begin{bmatrix} D \\ (q_{j+1} - p_{j+1})I \end{bmatrix}$

# fADI as a direct method

- Guaranteed to converge after all iterations
- Quasi-optimal shift parameters  $p$  and  $q$  are known in many situations  
[Fortunato & Townsend, 2020]  
[Townsend & Wilber, 2018]
- Zeros and poles of a rational function that can achieve a quasi-optimal Zolotarev number [Zolotarev, 1877]

$$Z_k(\Lambda(A), \Lambda(B)) := \inf_{r \in \mathcal{R}_{k,k}} \frac{\sup_{z \in \Lambda(A)} |r(z)|}{\inf_{z \in \Lambda(B)} |r(z)|}, \quad k \geq 0$$

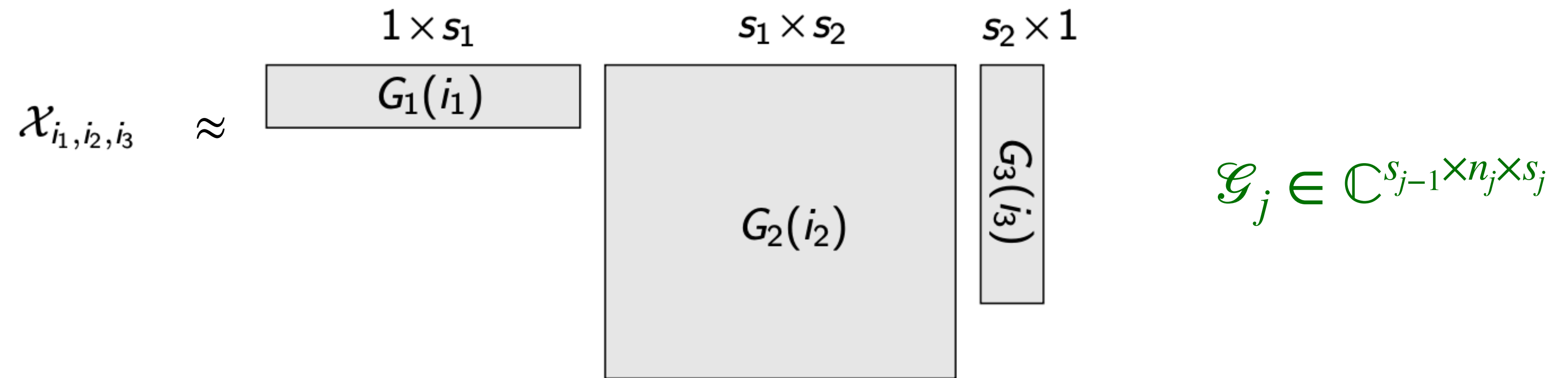
$$\|X - X_k\|_F \leq Z_k(\Lambda(A), \Lambda(B)) \|X\|_F \quad [\text{S. \& Townsend, 2021}]$$

- Complexity  $\mathcal{O}(r\ell T)$ ,  $\mathcal{O}(T)$  for solving shifted linear systems of  $A$  and  $B$

**Goal:** Solve Sylvester tensor equations with fADI

**Method:** Rewrite into several Sylvester matrix equations

# Tensor-train format [Oseledets, 11]



$$s_k \leq \text{rank}(X_k), \quad X_k = \text{reshape}(\mathcal{X}, \prod_{s=1}^k n_s, \prod_{s=k+1}^3 n_s)$$

Trains: “somewhat” mimic the bases for column/row spaces of a matrix

$$\mathcal{X} \times_1 A + \mathcal{X} \times_2 B + \mathcal{X} \times_3 C = \mathcal{F}$$

$$F_1 = M_1 N_1^T \text{ and } F_2 = M_2 N_2^T \quad \longleftrightarrow \quad \mathcal{F} \text{ with TT cores } \mathcal{G}_1, \mathcal{G}_2, \mathcal{G}_3 \text{ have low TT rank}$$

$$F_1 = G_1(G_2)_1(G_3 \otimes I) \quad F_2 = (I \otimes G_1)(G_2)_2 G_3$$

# 3D Sylvester solver in TT format

$$\mathcal{X} \times_1 A + \mathcal{X} \times_2 B + \mathcal{X} \times_3 C = \mathcal{F}$$

## Method 1: Combine TTSVD with fADI

TTSVD [Oseledets, 11]

Calculate SVD of  $X_1 \approx U_1 S_1 V_1^T$ ,  
and use  $U_1$  as first “train”

Let  $W = \text{reshape}(S_1 V_1^T, s_1 n_2, n_3)$ ,  
and calculate SVD of  $W \approx U_2 S_2 V_2^T$ .

Use  $\text{reshape}(U_2, s_1, n_2, s_2)$  as  
second “train”, and  $S_2 V_2^T$  as third  
“train”

fADI steps [S. & Townsend, 21]

$$AX_1 + X_1(I \otimes B + C \otimes I)^T = F_1 = M_1 N_1^T$$

Solve only for column space basis  $U_1$

$$(I \otimes (U_1^T A U_1) + B \otimes I)W + WC^T = (I \otimes U_1^T)F_2 = (I \otimes U_1^T)M_2 N_2^T$$

$$(I \otimes (U_1^T A U_1) + B \otimes I - \alpha I)Z = R$$



$$(U_1^T A U_1 - \frac{\alpha}{2} I)Z_j + Z_j(B - \frac{\alpha}{2} I)^T = R_j$$

$Z_j$  and  $R_j$  are reshape of  $j$ th column of  $Z$  and  $R$



# Example: Poisson equation

$$-(u_{xx} + u_{yy} + u_{zz}) = f \text{ on } \Omega = [-1,1]^3, \quad u|_{\partial\Omega} = 0$$

Ansatz  $\tilde{C}^{(3/2)}$ : normalized ultraspherical

$$u(x, y, z) = (1 - x^2)(1 - y^2)(1 - z^2) \sum_{p=0}^n \sum_{q=0}^n \sum_{r=0}^n \mathcal{X}_{pqr} \tilde{C}_p^{(3/2)}(x) \tilde{C}_q^{(3/2)}(y) \tilde{C}_r^{(3/2)}(z),$$

$$f(x, y, z) = \sum_{p=0}^n \sum_{q=0}^n \sum_{r=0}^n \mathcal{F}_{pqr} \tilde{C}_p^{(3/2)}(x) \tilde{C}_q^{(3/2)}(y) \tilde{C}_r^{(3/2)}(z)$$

Sylvester equation

$$\mathcal{X} \times_1 A^{-1} + \mathcal{X} \times_2 A^{-1} + \mathcal{X} \times_3 A^{-1} = \mathcal{G}$$

$$\mathcal{G} = \mathcal{F} \times_1 M^{-1} \times_2 M^{-1} \times_3 M^{-1}$$

$A = D^{-1}M$ ,  $D$  diagonal,  $M$  and  $A$  symmetric pentadiagonal

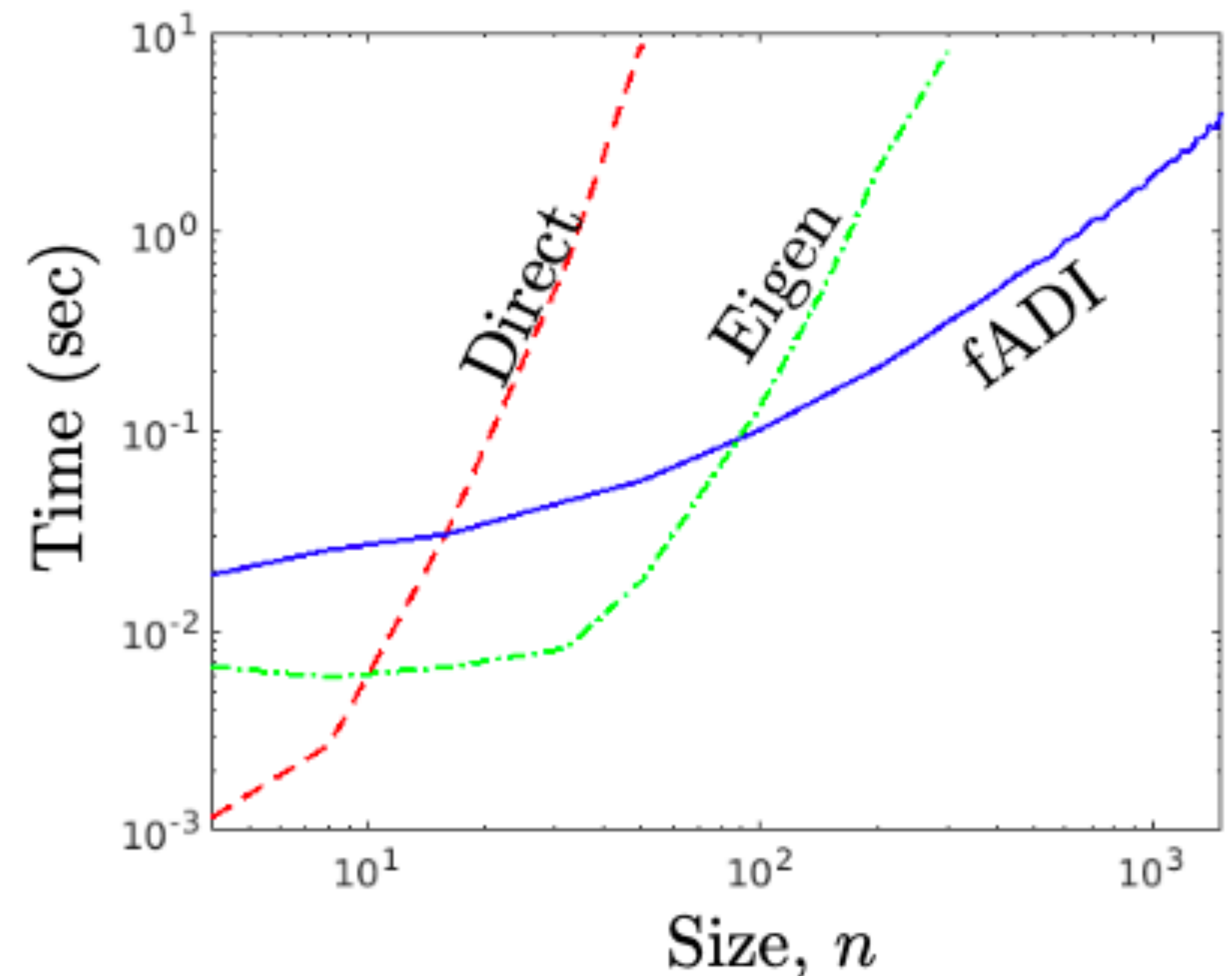
$$\Lambda(A) \in [-1, -1/(30n^4)]$$

[Fortunato & Townsend, 20]

$$f = -2(1 - y^2)(1 - z^2) - 2(1 - x^2)(1 - z^2) - 2(1 - x^2)(1 - y^2)$$

$$u = (x^2 - 1)(y^2 - 1)(z^2 - 1)$$

Complexity  $\mathcal{O}(n(\log n)^3(\log(1/\epsilon))^3)$



# 3D Sylvester solver in TT format

$$\mathcal{X} \times_1 A + \mathcal{X} \times_2 B + \mathcal{X} \times_3 C = \mathcal{F}$$

## Method 2: Combine parallel-TTSVD with fADI

parallel-TTSVD [S., Ruth & Townsend]

Calculate SVD of  $X_1 \approx U_1 S_1 V_1^T$ ,  
and use  $U_1$  as first “train”

Calculate SVD of  $X_2 \approx U_2 S_2 V_2^T$ . Use  
 $\text{reshape}(U_1^* \text{reshape}(U_2, n_1, n_2 s_2), s_1, n_2, s_2)$   
as second “train” and  $S_2 V_2^T$  as third “train”

fADI steps [S., Ruth & Townsend]

$$AX_1 + X_1(I \otimes B + C \otimes I)^T = F_1 = M_1 N_1^T$$

Solve only for column space basis  $U_1$

$$(I \otimes A + B \otimes I)X_2 + X_2 C^T = F_2 = M_2 N_2^T$$

Only solve shifted linear systems with  $A$ ,  $B$ , and  $C$

Use universal shift parameters for both above equations, then find “trains” almost simultaneously

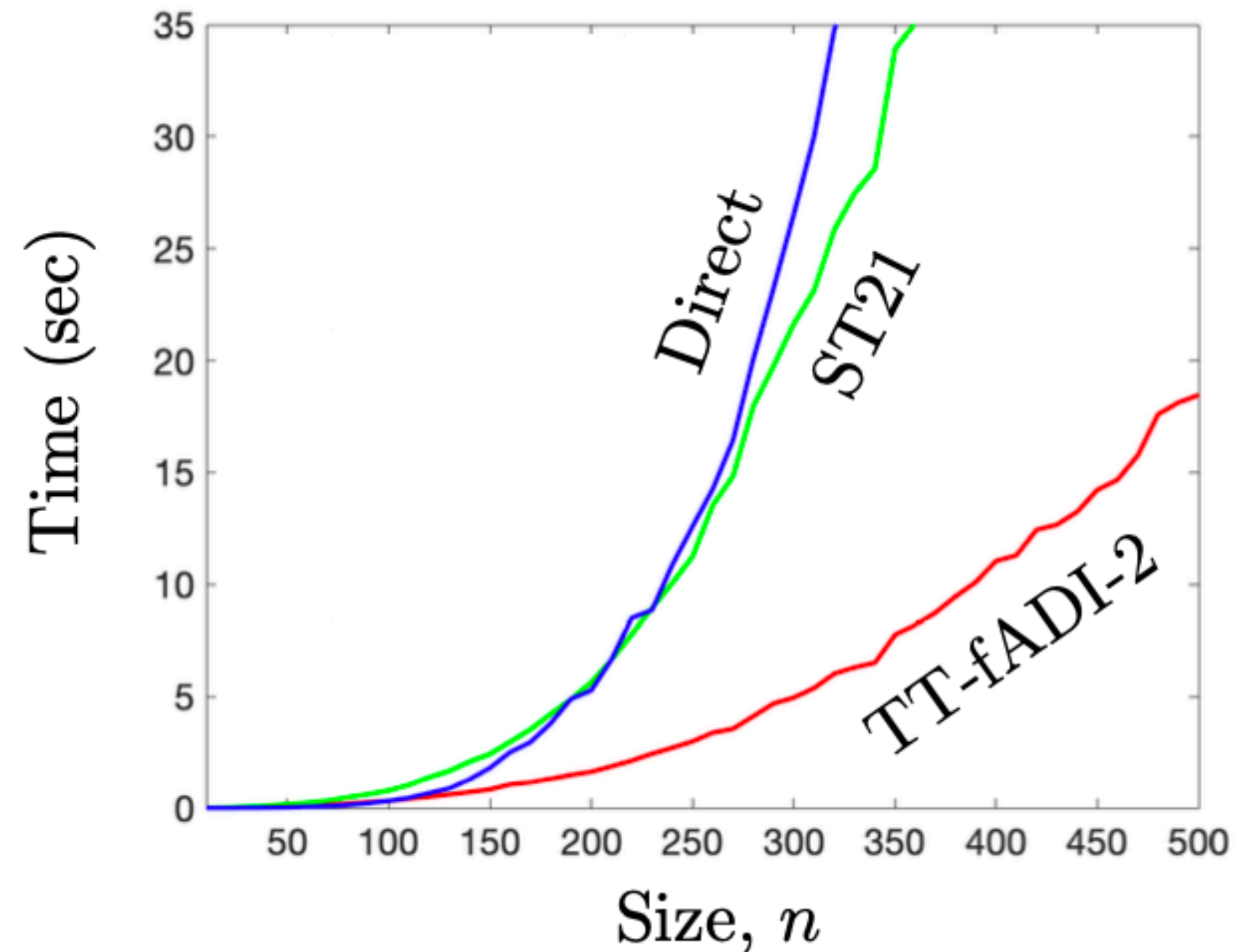
# Example

$$\mathcal{X} \times_1 D + \mathcal{X} \times_2 D + \mathcal{X} \times_3 D = \mathcal{F}$$

$D \in \mathbb{R}^{n \times n}$  diagonal with  $D_j \in [-1, -1/(30n)]$

$\mathcal{F}$  has TT rank  $(1, \lfloor n/4 \rfloor, 2, 1)$  with i.i.d. uniform random numbers in TT cores

Complexity  $\mathcal{O}(n(\log n)^3(\log(1/\epsilon))^3)$



**Thank you!**