

MA 520: Boundary Value Problems of Differential Equations
Spring 2024, Midterm One

Instructor: Yip

- This test booklet has FOUR QUESTIONS, totaling 100 points for the whole test. You have 75 minutes to do this test. **Plan your time well. Read the questions carefully.**
- This test is **closed book, closed note, with no electronic devices.**
- In order to get full credits, you need to give **correct** and **simplified** answers and explain in a **comprehensible way** how you arrive at them.
- **As a rule of thumb, you should give explicit and useful answers.** No points will be given for just writing down some generically true statements. In other words, your answers should try to make use of all the information given in the question.
- **As a rule of thumb, you should only use those methods that have been covered in class.** If you use some other methods “for the sake of convenience”, at our discretion, we might not give you any credit. You have the right to contest. In that event, **you will be asked to explain your answer using only what has been covered in class up to the point of time of this exam.**

Name: Answer Key (Major: _____)

Question	Score
1.(25 pts)	_____
2.(25 pts)	_____
3.(25 pts)	_____
4.(25 pts)	_____
Total (100 pts)	_____

1. Consider the 2π -periodic function given by $f(x) = x^2$ on $-\pi < x < \pi$.

(a) Find its Fourier series expansion.

(b) Using the above or otherwise, compute the following series:

$$(A) = \frac{1}{1^2} - \frac{1}{2^2} + \frac{1}{3^2} - \frac{1}{4^2} \dots$$

$$(B) = \frac{1}{1^2} + \frac{1}{2^2} + \frac{1}{3^2} + \frac{1}{4^2} \dots$$

$$(C) = \frac{1}{1^4} + \frac{1}{2^4} + \frac{1}{3^4} + \frac{1}{4^4} \dots$$

(a) x^2 - even function. Hence

$$x^2 = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos nx$$

$$a_0 = \frac{2}{\pi} \int_0^{\pi} x^2 dx = \frac{2}{3\pi} \pi^3 = \frac{2\pi^2}{3}$$

$$a_n = \frac{2}{\pi} \int_0^{\pi} x^2 \cos nx dx$$

$$= \frac{2}{\pi} \int_0^{\pi} x^2 d\left(\frac{\sin nx}{n}\right)$$

$$= \frac{2}{\pi} \left[\frac{x^2 \sin nx}{n} \Big|_0^{\pi} - \frac{2}{n} \int_0^{\pi} x \sin nx dx \right]$$

$$= \frac{2}{\pi} \frac{2}{n} \left[\int_0^{\pi} x d\left(\frac{\cos nx}{n}\right) \right]$$

$$= \frac{4}{\pi n} \left[\frac{x \cos nx}{n} \Big|_0^{\pi} - \frac{1}{n} \int_0^{\pi} \cos nx dx \right]$$

$$= \frac{4}{\pi n} \left[\frac{\pi \sin n\pi}{n} - \frac{1}{n^2} \sin n\pi \right]_0^{\pi}$$

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$$= \frac{4}{n^2} (-1)^n$$

Hence

$$\pi^2 = \frac{\pi^2}{3} + \sum_{n=1}^{\infty} \frac{4}{n^2} (-1)^n \sin n\pi,$$

$$\begin{aligned} (b) \quad x \rightarrow 0 &\Rightarrow \\ 0 &= \frac{\pi^2}{3} + \sum_{n=1}^{\infty} \frac{4}{n^2} (-1)^n \\ &= \frac{\pi^2}{3} + 4 \left[-\frac{1}{1^2} + \frac{1}{2^2} - \frac{1}{3^2} + \dots \right] \end{aligned}$$

$$(A) \quad \frac{1}{1^2} - \frac{1}{2^2} + \frac{1}{3^2} - \frac{1}{4^2} \dots = \frac{\pi^2}{12}$$

$$x \rightarrow 0 \Rightarrow \pi^2 = \frac{\pi^2}{3} + 4 \sum_{n=1}^{\infty} \frac{(-1)^n (-1)^n}{n^2} \quad (\sin n\pi = (-1)^n)$$

$$\frac{2\pi^2}{12} = \sum_{n=1}^{\infty} \frac{1}{n^2}$$

$$(B) \quad \text{i.e.} \quad \frac{1}{1^2} + \frac{1}{2^2} + \frac{1}{3^2} + \dots = \frac{\pi^2}{6}$$

(C) M1

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By Parseval Identity:

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} |f|^2 dx = \frac{a_0^2}{4} + \sum_{n=1}^{\infty} a_n^2$$

$$\frac{1}{\pi} \int_0^{\pi} x^4 dx = \frac{\pi^4}{9} + \frac{1}{2} \sum_{n=1}^{\infty} \frac{16}{n^4}$$

$$\frac{1}{\pi} \frac{\pi^5}{5} = \frac{\pi^4}{9} + 8 \sum_{n=1}^{\infty} \frac{1}{n^4}$$

$$\text{Hence } \sum_{n=1}^{\infty} \frac{1}{n^4} = \frac{1}{8} \left(\frac{1}{5} - \frac{1}{9} \right) \pi^4 = \frac{\pi^4}{90}$$

(C)

$$\frac{1}{1^4} + \frac{1}{2^4} + \frac{1}{3^4} + \dots = \frac{\pi^4}{90}$$

M2

From: $x^2 = \frac{\pi^2}{3} + \sum_{n=1}^{\infty} \frac{4}{n^2} (-1)^n \cos nx$

$$\int dx \frac{x^3}{3} = \frac{\pi^2 x}{3} + \sum_{n=1}^{\infty} \frac{4}{n^3} (-1)^n \sin nx + C$$

$$x=0 \Rightarrow C=0$$

$$\int dx \left(\frac{x^3}{3} - \frac{\pi^2 x}{3} \right) = \sum_{n=1}^{\infty} \frac{4}{n^3} (-1)^n \sin nx$$

$$\frac{x^4}{12} - \frac{\pi^2 x^2}{6} = \sum_{n=1}^{\infty} \frac{4}{n^4} (-1)^{n+1} \cos nx + C$$

$$\int_{-\pi}^{\pi} dx \left(\frac{1}{60} \pi^5 \times 2 - \frac{\pi^2}{18} \pi^3 \times 2 \right) = C \cdot 2\pi$$

$$\left(\frac{1}{30} - \frac{1}{9} \right) \frac{\pi^5}{2\pi} = C$$

$$C = \frac{-21 \pi^4}{540} = -\frac{7\pi^4}{180}$$

Have

$$\frac{x^4}{12} - \frac{\pi^2 x^2}{6} = -\frac{7\pi^4}{180} + \sum_{n=1}^{\infty} \frac{4}{n^4} (-1)^{n+1} \cos nx$$

$\cos n\pi = (-1)^n$

$$x=\pi \Rightarrow \left(\frac{1}{12} - \frac{1}{6} + \frac{7}{180} \right) \pi^4 = 4(-1) \sum_{n=1}^{\infty} \frac{1}{n^4}$$

$$\left(-\frac{15 - 30 + 7}{4(180)} \right) \pi^4 = \sum_{n=1}^{\infty} \frac{1}{n^4}$$

$$= \frac{\pi^4}{90}$$

2. Let D be the unit disk $\{x^2 + y^2 \leq 1\}$ in \mathbb{R}^2 . Let

$$L^2(D) = \left\{ f : \iint_D |f(x, y)|^2 dx dy < \infty \right\}, \quad \langle f, g \rangle = \iint_D f(x, y) \overline{g(x, y)} dx dy.$$

Introduce $\mathcal{L} = \{f_n(x, y) = (x + yi)^n\}_{n=0}^{\infty}$.

(a) Show that \mathcal{L} is an orthogonal list of functions. Find also $\|f_n\|$.

(Hint: use polar coordinates $x + iy = re^{i\theta}$ and the formula $dx dy = r dr d\theta$.)

(b) Find the projections of the functions $f(x, y) = x$ and $g(x, y) = y$ onto the space spanned by \mathcal{L} , i.e., find $\text{Proj}_{\mathcal{L}} x$ and $\text{Proj}_{\mathcal{L}} y$.

(Hint: write x and y using polar coordinates.)

(c) Is \mathcal{L} complete in $L^2(D)$?

$$\begin{aligned} \text{(a)} \quad \iint_D f_n \overline{f_m} dx dy &= \int_0^1 \int_0^{2\pi} (r e^{in\theta}) \overline{(r e^{im\theta})} r d\theta dr \\ &= \int_0^1 r^{n+m+1} \left(\underbrace{\int_0^{2\pi} e^{i(n-m)\theta} d\theta}_{n \neq m} \right) dr \\ &= \frac{e^{i(n-m)\theta}}{i(n-m)} \Big|_0^{2\pi} = 0 \end{aligned}$$

Hence $f_n \perp f_m$ in $L^2(D)$ for $n \neq m$

When $n=m$,

$$\langle f_n, f_n \rangle = \int_0^1 r^{2n+1} \int_0^{2\pi} d\theta dr = \frac{2\pi}{2n+2} = \frac{\pi}{n+1}$$

$$\text{i.e. } \|f_n\|^2 = \frac{\pi}{n+1}, \quad \text{or } \|f_n\| = \sqrt{\frac{\pi}{n+1}}$$

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$$(b) \text{ Proj}_D x = \sum_{n=0}^{\infty} \frac{\langle x, f_n \rangle}{\|f_n\|^2} f_n$$

$$\langle x, f_n \rangle = \int_D \underline{x} \overline{(x+iy)^n} dx dy$$

$$(x = r \cos \theta) = \int_0^1 \int_0^{2\pi} \underline{(r \cos \theta)} r^n e^{-in\theta} r d\theta dr$$

$$= \int_0^1 r^{n+2} \int_0^{2\pi} \cos \theta e^{-in\theta} d\theta dr$$

$$\left(\cos \theta = \frac{e^{i\theta} + e^{-i\theta}}{2} \right) = \left(\int_0^1 r^{n+2} dr \right) \left(\int_0^{2\pi} \frac{e^{i\theta} + e^{-i\theta}}{2} e^{-in\theta} d\theta \right)$$

$$= \left(\frac{1}{n+3} \right) \frac{1}{2} \int_0^{2\pi} \left(e^{(1-n)i\theta} + \cancel{e^{-(1+n)i\theta}} \right) d\theta$$

= 0 for $n=0, 1, 2, \dots$

= 0 for $n \neq 1$, ($n=0, 2, 3, \dots$)

$$\text{When } n=1, \quad \langle x, f_1 \rangle = \left(\frac{1}{1+3} \right) \left(\frac{1}{2} \right) \int_0^{2\pi} d\theta = \frac{\pi}{4}$$

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Hence

$$\begin{aligned}\widehat{\text{Proj}}_D X &= \frac{\langle X, f_1 \rangle}{\|f_1\|^2} f_1 = \frac{\frac{\pi}{4}}{\frac{\pi}{2}} f_1 \\ &= \frac{1}{2} f_1(x, y) = \frac{x+yi}{2}\end{aligned}$$

Similarly, $\widehat{\text{Proj}}_D Y = \sum_{n=0}^{\infty} \frac{\langle Y, f_n \rangle}{\|f_n\|^2} f_n$

$$\begin{aligned}\langle Y, f_n \rangle &= \iint_D y \overline{f_n} \, dx dy \\ &= \int_0^1 \int_0^{2\pi} (r \sin \theta) r^n \overline{e^{in\theta}} r \, d\theta dr \\ &= \left(\int_0^1 r^{n+2} \, dr \right) \int_0^{2\pi} (\sin \theta) e^{-in\theta} \, d\theta\end{aligned}$$

$$\left(\sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2i} \right)$$

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$$= \left(\frac{1}{n+3} \right) \frac{1}{2i} \int_0^{2\pi} (e^{i\theta} - \bar{e}^{i\theta}) e^{-in\theta} d\theta$$

$$= \frac{1}{(n+3)} \left(\frac{1}{2i} \right) \int_0^{2\pi} \left(e^{(1-n)i\theta} - e^{-\cancel{(1+n)i\theta}} \right) d\theta$$

= 0 for $n=0, 1, \dots$

= 0 for $n \neq 1$

$$\text{For } n=1, \quad \langle y, f_1 \rangle = \frac{1}{4} \left(\frac{1}{2i} \right) \int_0^{2\pi} d\theta = \frac{\pi}{4i}$$

Hence

$$\begin{aligned} \text{Proj}_{\mathcal{L}} y &= \frac{\langle y, f_1 \rangle}{\|f_1\|^2} f_1 && \frac{1}{2i} f_1(x, y) \\ &= \frac{\frac{\pi}{4i}}{\frac{\pi}{2}} (x+yi) = \frac{1}{2i} (x+yi) \end{aligned}$$

$$\begin{aligned} (\text{Note : } \text{Proj}_{\mathcal{L}} (x+yi)) &= \text{Proj}_{\mathcal{L}} x + i \text{Proj}_{\mathcal{L}} y \\ &= \frac{1}{2} (x+yi) + i \frac{1}{2i} (x+yi) = x+yi \end{aligned}$$

(c) \mathcal{L} is not complete on $L^2(D)$. For otherwise, we would have $\text{Proj}_{\mathcal{L}} x = x$ and $\text{Proj}_{\mathcal{L}} y = y$

3. Consider the space of (real valued) functions defined on $(0, 1)$ with the following inner product:

$$\langle f, g \rangle = \int_0^1 f(x)g(x) dx.$$

You are given $P_1(x) = 1$, $P_2(x) = x$, and $P_3(x) = x^2$. Let $Q_1 = P_1$. (For simplicity, I have omitted the x 's.)

(a) Find $Q_2 = P_2 - \text{Proj}_{\{Q_1\}} P_2$.

(b) Find $Q_3 = P_3 - \text{Proj}_{\{Q_1, Q_2\}} P_3$.

(c) Show that $\{Q_1, Q_2, Q_3\}$ forms an orthogonal set.

$$\begin{aligned} \text{(a)} \quad \underline{Q_2} &= P_2 - \text{Proj}_{Q_1} P_2 = x - \frac{\langle P_2, Q_1 \rangle}{\langle Q_1, Q_1 \rangle} Q_1 \\ &= x - \frac{\int_0^1 x \cdot 1 dx}{\int_0^1 1 \cdot 1 dx} \cdot 1 = x - \frac{\frac{1}{2}(1)}{1} = x - \frac{1}{2} \end{aligned}$$

$$\begin{aligned} \text{(b)} \quad Q_3 &= P_3 - \text{Proj}_{\{Q_1, Q_2\}} P_3 \\ &= x^2 - \frac{\langle x^2, 1 \rangle}{\langle 1, 1 \rangle} \cdot 1 - \frac{\langle x^2, x - \frac{1}{2} \rangle}{\langle x - \frac{1}{2}, x - \frac{1}{2} \rangle} (x - \frac{1}{2}) \\ &= x^2 - \frac{\int_0^1 x^2 dx}{\int_0^1 1 dx} \cdot 1 - \frac{\int_0^1 x^2 (x - \frac{1}{2}) dx}{\int_0^1 (x - \frac{1}{2})^2 dx} (x - \frac{1}{2}) \end{aligned}$$

$$= x^2 - \frac{1}{3} - \frac{\int_0^1 (x^3 - \frac{x^2}{2}) dx}{\int_0^1 (x^2 - x + \frac{1}{4}) dx} (x - \frac{1}{2})$$

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$$= x^2 - \frac{1}{3} - \left(\frac{\frac{1}{4} - \frac{1}{6}}{\frac{1}{3} - \frac{1}{2} + \frac{1}{4}} \right) (x - \frac{1}{2})$$

$$= x^2 - \frac{1}{3} - \frac{\frac{1}{12}}{\frac{4-6+3}{12}} (x - \frac{1}{2})$$

$$= x^2 - \frac{1}{3} - x + \frac{1}{2} = x^2 - x + \frac{1}{6}$$

(c)

M1

$$Q_2 = P_2 - \text{Proj}_{Q_1} P_2 \perp Q_1 \implies \underline{Q_1 \perp Q_2}$$

$$Q_3 = P_3 - \text{Proj}_{\{Q_1, Q_2\}} P_3 \perp \{Q_1, Q_2\}$$

$$\implies \underline{Q_3 \perp Q_1},$$

$$\underline{Q_3 \perp Q_2}$$

Hence $\{Q_1, Q_2, Q_3\}$ is orthogonal

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$$\textcircled{M2} \quad \langle Q_1, Q_2 \rangle = \int_0^1 1(x - \frac{1}{2}) dx = \frac{1}{2} - \frac{1}{2} = 0$$

$$\langle Q_1, Q_3 \rangle = \int_0^1 1(x^2 - x + \frac{1}{6}) dx = \frac{1}{3} - \frac{1}{2} + \frac{1}{6} = 0$$

$$\langle Q_2, Q_3 \rangle = \int_0^1 (x - \frac{1}{2})(x^2 - x + \frac{1}{6}) dx$$

$$= \int_0^1 (x^3 - x^2 + \frac{x}{6} - \frac{x^2}{2} + \frac{x}{2} - \frac{1}{12}) dx$$

$$= \frac{1}{4} - \frac{1}{3} + \frac{1}{12} - \frac{1}{6} + \frac{1}{4} - \frac{1}{12}$$

$$= \frac{1}{2} - \frac{1}{3} - \frac{1}{6} = 0$$

4. You are given the following information:

$$\begin{pmatrix} -5 & 2 \\ 2 & -8 \end{pmatrix} \begin{pmatrix} 2 \\ 1 \end{pmatrix} = -4 \begin{pmatrix} 2 \\ 1 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} -5 & 2 \\ 2 & -8 \end{pmatrix} \begin{pmatrix} -1 \\ 2 \end{pmatrix} = -9 \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

(a) Solve the following system

$$\frac{d^2 X}{dt^2}(t) = \begin{pmatrix} -5 & 2 \\ 2 & -8 \end{pmatrix} X(t), \quad X(0) = \begin{pmatrix} 1 \\ 4 \end{pmatrix}, \quad \frac{dX}{dt}(0) = \begin{pmatrix} 2 \\ -1 \end{pmatrix}.$$

What can you say about the solution as $t \rightarrow +\infty$?

(b) Consider the following system

$$\frac{d^2 X}{dt^2}(t) + \frac{dX}{dt}(t) = \begin{pmatrix} -5 & 2 \\ 2 & -8 \end{pmatrix} X(t),$$

(with some unknown/unspecified initial conditions).

Find the general solution. You should write down the solution as precise as possible. (Of course not all constants can be identified/found as the initial conditions are not given.)

What can you say about the solution as $t \rightarrow +\infty$?

$$(a) \quad X(t) = Q_1(t) V_1 + Q_2(t) V_2$$

$$\ddot{X} = AX$$

$$\ddot{Q}_1 V_1 + \ddot{Q}_2 V_2 = A(Q_1 V_1 + Q_2 V_2) = \underline{Q_1 \lambda_1 V_1} + \underline{Q_2 \lambda_2 V_2}$$

$$\ddot{Q}_1 = -4Q_1 \quad \text{and} \quad \ddot{Q}_2 = -9Q_2$$

$$\text{Hence} \quad Q_1(t) = (a \cos 2t + b \sin 2t)$$

$$Q_2(t) = (c \cos 3t + d \sin 3t)$$

$$X(t) = (a \cos 2t + b \sin 2t) V_1 + (c \cos 3t + d \sin 3t) V_2$$

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$$= (a \cos 2t + b \sin 2t) \begin{pmatrix} 2 \\ 1 \end{pmatrix} + (c \cos 3t + d \sin 3t) \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

$$X(0) = a \begin{pmatrix} 2 \\ 1 \end{pmatrix} + c \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$a = \frac{\langle \begin{pmatrix} 1 \\ 4 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix} \rangle}{\langle \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix} \rangle} = \frac{6}{5}, \quad c = \frac{\langle \begin{pmatrix} 1 \\ 4 \end{pmatrix}, \begin{pmatrix} -1 \\ 2 \end{pmatrix} \rangle}{\langle \begin{pmatrix} -1 \\ 2 \end{pmatrix}, \begin{pmatrix} -1 \\ 2 \end{pmatrix} \rangle} = \frac{7}{5}$$

$$\dot{X}(t) = (-2a \sin 2t + 2b \cos 2t) \begin{pmatrix} 2 \\ 1 \end{pmatrix} + (-3c \sin 3t + 3d \cos 3t) \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

$$\dot{X}(0) = (2b) \begin{pmatrix} 2 \\ 1 \end{pmatrix} + (3d) \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

$$2b = \frac{\langle \begin{pmatrix} 2 \\ -1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix} \rangle}{\langle \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \end{pmatrix} \rangle} = \frac{3}{5} \Rightarrow b = \frac{3}{10}$$

$$3d = \frac{\langle \begin{pmatrix} 2 \\ -1 \end{pmatrix}, \begin{pmatrix} -1 \\ 2 \end{pmatrix} \rangle}{\langle \begin{pmatrix} -1 \\ 2 \end{pmatrix}, \begin{pmatrix} -1 \\ 2 \end{pmatrix} \rangle} = -\frac{4}{5} \Rightarrow d = -\frac{4}{15}$$

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$$X(t) = \left(\frac{6}{5} \cos 2t + \frac{3}{10} \sin 2t \right) \begin{pmatrix} 2 \\ 1 \end{pmatrix} + \left(\frac{7}{5} \cos 3t - \frac{4}{15} \sin 3t \right) \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

as $t \rightarrow \infty$, $X(t)$ keeps oscillation.

$$(b) \quad \ddot{X} + \dot{X} = AX$$

$$\text{Let } X(t) = a_1(t) V_1 + a_2(t) V_2$$

$$\text{Then } (\ddot{a}_1 V_1 + \ddot{a}_2 V_2) + (\dot{a}_1 V_1 + \dot{a}_2 V_2) = a_1 \lambda_1 V_1 + a_2 \lambda_2 V_2$$

$$\ddot{a}_1 + \dot{a}_1 = -4a_1 \quad \text{and} \quad \ddot{a}_2 + \dot{a}_2 = -9a_2$$

$$\begin{aligned} & \downarrow \\ r^2 + r + 4 &= 0 \\ r &= \frac{-1 \pm \sqrt{1-16}}{2} \\ &= -\frac{1}{2} \pm \frac{\sqrt{15}}{2} i \end{aligned}$$

$$\begin{aligned} & \downarrow \\ r^2 + r + 9 &= 0 \\ r &= \frac{-1 \pm \sqrt{1-36}}{2} \\ &= -\frac{1}{2} \pm \frac{\sqrt{35}}{2} i \end{aligned}$$

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$$\text{Hence } q_1(t) = e^{-\frac{1}{2}t} \left(a \cos \frac{\sqrt{15}}{2}t + b \sin \frac{\sqrt{15}}{2}t \right)$$

$$q_2(t) = e^{-\frac{1}{2}t} \left(c \cos \frac{\sqrt{35}}{2}t + d \sin \frac{\sqrt{35}}{2}t \right)$$

$$X(t) = e^{-\frac{1}{2}t} \left(a \cos \frac{\sqrt{15}}{2}t + b \sin \frac{\sqrt{15}}{2}t \right) \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$e^{-\frac{1}{2}t} \left(c \cos \frac{\sqrt{35}}{2}t + d \sin \frac{\sqrt{35}}{2}t \right) \begin{pmatrix} -1 \\ 2 \end{pmatrix}$$

(a, b, c, d cannot be determined as initial conditions are not specified.)

Note that as $t \rightarrow +\infty$, $X(t) \rightarrow 0$
