Linear System Lee 3 $\frac{d\vec{X}}{dt} = A\vec{X} + \vec{h}t, \quad X(0) = X_0$ $A \equiv \alpha \text{ constant matrix (autonomous)}$ dX = Alt) X + htt) A depende on time (non-autonomous) $(X, h \in \mathbb{R}^n, A \in \mathbb{R}^{n \times n})$

Constant coefficient matrix A $\mathcal{C}^{At} := I + \frac{tA}{l'} + \frac{tA^2}{2l} + \frac{t^3A^3}{2l} + \cdots$ $\left(= \frac{0}{2} \frac{(tA)^{7}}{(tA)^{7}} \right)$

Properties of et (Matrix Exponential) (1) $e^{At}/_{t=n} = I$ (2) $\frac{d}{dt}(e^{At}) = Ae^{tt} = e^{At}A$ $(3) e^{At} e^{As} = e^{A(t+s)}$ (4) $\left(e^{At}\right)^{-1} = \overline{e}^{At}$, i.e. $\left(e^{At}\right)\left(e^{-At}\right) = I$ io. ett is invertible. (5) If AB = BA, then (Infart, ett Bt (AFB)t for all t ifond only if AB=BA [M, p. 64 #6])

(Use IH)= e as integrating factor.) $\frac{\partial X}{\partial U} = AX + h\theta$ $\frac{dX}{dA} - AX = h(t)$ $e^{At} \frac{d}{dt} X - A \overline{e}^{At} X = \overline{e}^{At} h H$ d e At $\overline{e}^{\text{AH}} \frac{d}{dt} \chi + \left(\frac{d}{dt} \overline{e}^{\text{AH}} \right) \chi = \overline{e}^{\text{AH}} h(t)$ $\frac{d}{dt}\left(\overline{e}^{HT}X\right) = \overline{e}^{HT}h(t)$ $\int_{0}^{x} \frac{d}{ds} \left(e^{-As} \chi(s) \right) ds = \int_{0}^{t} e^{-As} h(s) ds$ $e^{At}X(t) - X(0) = \int e^{-As}h(s)ds$

 e^{HT} (4) = X(0) + $\int e^{-As} h(s) ds$ $X(t) = e^{At} X(0) + e^{At} \int_{0}^{t} e^{As} h(s) ds$ $= e^{At} X(0) + \int_{0}^{t} e^{A(t-s)} h(s) ds$ (In particular, if $h(s) \equiv 0$, i.e. X = AX,

then, $\chi(t) = e^{At}\chi(0)$.

Non-autonomous Case $\frac{dX}{dt} = A (t) X + h(t), \quad \chi(0) = \chi_0$ Variation of Parameters D Let {\\overline{\Delta}} \overline{\Delta} be a matrix function that sobre: $\frac{d\Phi(F)}{dF} = A(F)\overline{\Phi}(F), \quad \overline{\Phi}(G) = \overline{L}$ $\begin{bmatrix} \overline{\pm}(t) \end{bmatrix}^{N \times N} = \begin{bmatrix} \varphi_i(t) & \varphi_i(t) & \varphi_i(t) \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \varphi_i(t) & \varphi_i(t) \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \varphi_i(t) & \varphi_i(t) \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \varphi_i(t) & \varphi_i(t) \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \varphi_i(t) & \varphi_i(t) \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \varphi_i(t) & \varphi_i(t) \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \varphi_i(t) & \varphi_i(t) \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \varphi_i(t) & \varphi_i(t) \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \varphi_i(t) & \varphi_i(t) \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \varphi_i(t) & \varphi_i(t) \\ 1 & 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\begin{bmatrix} \varphi_i(t) & \varphi_i(t) \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \varphi_i(t) & \varphi_i(t) \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \varphi_i(t) & \varphi_i(t) \\ 1 & 1$ Then (1) solves $\frac{d}{dt}\varphi_{i}(t) = A(t) \varphi_{i}(t), \varphi_{i}(0) = e_{i}$ $\begin{array}{l} \text{lot} \underbrace{\chi(H)}_{(H)} = \underbrace{\Phi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \\ \underbrace{\chi(H)}_{(H)} = \underbrace{\Phi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \\ \underbrace{\chi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \\ \underbrace{\chi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \\ \underbrace{\chi(H)}_{(H)} \underbrace{\psi(H)}_{(H)} \underbrace{\psi$

Try to find u &) (=?) $\frac{dX}{dt} = A(t)X + h(t), \quad X(0) = X_0$ $\frac{d}{dt}(\underline{\Phi}_{H})(\mathcal{H}) = A(\mathcal{H})(\underline{\Phi}_{H})(\mathcal{H}) + h(\mathcal{H})$ $\left(\frac{d}{dt} \overline{\Phi}(t) + \overline{\Phi}(t) + \overline{\Phi}(t) + \frac{d}{dt} \overline{\Phi}(t) = A(t) \overline{\Phi}(t) + h(t) + h(t)$ $\overline{\Phi}_{\text{H}} \frac{du_{\text{H}}}{d4} = h_{\text{H}}$ $\overline{\Phi}_{\text{H}} \frac{du_{\text{H}}}{d4} = h_{\text{H}}$ $\overline{\Phi}_{\text{H}} \frac{du_{\text{H}}}{d4} = h_{\text{H}}$ $\int \left(\begin{array}{c} \frac{\partial \mathcal{U}(H)}{\partial H} = \overline{\Phi}(H) h(H) \right) \right)$) dt $\mathcal{U}(f) - \mathcal{U}(0) = \int_{-\infty}^{\infty} \overline{\mathcal{I}}(s) h(s) ds$ $u(t) = u(0) + \int_{-\infty}^{\infty} \frac{t - 1}{2} (s) h(s) ds$

 $\chi(H) = \overline{\Phi}(H) \eta(H)$ $= \overline{\Phi}(t) \mathcal{U}_0 + \overline{\Phi}(t) \int_{-\infty}^{\infty} \overline{\Phi}(c) \widehat{h}(c) ds$ $\chi_o = \overline{\pm}_{0} \mathcal{U}_0 + \overline{\pm}_{0} \mathcal{J}_0^{0} \cdots \mathcal{J}_n^{0}$ $u_0 = ?$ = IUn $\Rightarrow \mathcal{U}_0 = \chi_0$ Hence $X(t) = \overline{\Phi}(t) X_0 + \overline{\Phi}(t) \int_0^t \overline{\Phi}(s) h(s) ds$ $= \overline{\Phi}(H)X_{0} + \int \overline{\Phi}(H)\overline{\Phi}(S) + \int h(L)dS$ $Let \quad \overline{\Phi}(t,s) = \overline{\Phi}(t)\overline{\Phi}(s) \quad (0 \le s \le t)$ $\overline{\underline{\mathfrak{F}}}(\mathfrak{t},\mathfrak{o}) = \overline{\underline{\mathfrak{F}}}(\mathfrak{t},\mathfrak{o})$

Then $X(t) = \overline{\Phi}(t, \delta) X_0 + \int_0^t \overline{\Phi}(t, s) h(t) ds$

(In particular, if h(s)=2, then X(+) = = E(+,0)Xo)

(It) is called the fundamental matrix: $\frac{d\overline{\Phi}H}{dT} = AH (\overline{\Phi}H), \quad \overline{\Phi}(0) = I$ Ettis) is called the propagation operator: $\frac{d \Phi(t,s)}{M} = A(t) \Phi(t,s), \quad \Phi(s,s) = I$ Existence of \$(#) (Mothod 1) Let Ift) be the solution of 亚(+)= -亚(+)AH), 亚向)-正 Consider $\frac{d}{h}(\underline{\Psi}(H) \oplus (H)) = ?$ (Method 2) Use Abel's Thm [M, Thm 2.34] $\underline{d \Phi}(t) = A(t) \overline{\Phi}(t), \quad \underline{F}(0) = I$ Then $\frac{d}{dt} \left(\det \overline{\Phi} H \right) = \left(fr A H \right) \left(\det \overline{\Phi} H \right)$ $\rightarrow det \overline{\Phi}(t) = e^{\int_{0}^{t} (tr f(s)) ds}$