

# Floquet, Monodromy and Poincaré

(Review of Lec 17, 18)

$$(*)_1 \begin{cases} \frac{dX}{dt} = A(t)X, & A(t+T) = A(t) \\ X(0) = X(T) \end{cases}$$

$$X(t) = \Phi(t)X(0)$$

$$X(T) = X(0) \iff \Phi(T)X(0) = X(0)$$

$$\iff (\Phi(T) - I)X(0) = 0$$

$(*)_1$  has a non-trivial solution ( $X(0) \neq 0$ )

$\iff (\Phi(T) - I)$  is not invertible

$(\Phi(T) - I)^{-1}$  does not exist

$\iff \mu = 1$  is an eigenvalue of  $\Phi(T)$

$\left( \begin{array}{l} X(0) \text{ is an eigenvector of } \Phi(T) \\ \text{(wrt. } \mu = 1) \end{array} \right)$

[H, Thm 1.1, p. 408]

$$(*)_2 \left\{ \begin{array}{l} \frac{dX}{dt} = A(t)X + g(t) \\ X(t+T) = X(t) \end{array} \right.$$

$$\begin{array}{l} A(t+T) = A(t) \\ g(t+T) = g(t) \end{array}$$

$$X(t) = \Phi(t)X(0) + \int_0^t \underbrace{\Phi(t,s)}_{=\Phi(t)\Phi(s)^{-1}} g(s) ds$$

$$X(T) = X(0)$$

$$\Leftrightarrow X(0) = \Phi(T)X(0) + \int_0^T \Phi(T,s)g(s) ds$$

$$\Leftrightarrow (\Phi(T) - I)X(0) = - \int_0^T \Phi(T,s)g(s) ds$$

IF  $(\Phi(T) - I)^{-1}$  exists, then  $(*)_2$  has a soln.  
for any  $g(t)$  and

$$X(0) = -(\Phi(T) - I)^{-1} \int_0^T \Phi(T,s)g(s) ds$$

and  $\|X(\cdot)\|_{C^0(0,T)} \leq \alpha \int_0^T \|g(s)\| ds$

Otherwise, for  $(*)_2$  to have a solution,  $g(\cdot)$  needs to satisfy some compatibility condition

[H, Thm 2.1, p. 413]

$$(*)_3 \left\{ \begin{array}{l} \frac{dX}{dt} = A(t)X + f(t, X) \\ X(t+T) = X(t) \end{array} \right. \quad \begin{array}{l} A(t+T) = A(t) \\ f(t+T, X) = f(t, X) \end{array}$$

$(*)_3$  has a unique solution if

(1)  $(\Phi(T) - I)^{-1}$  exists

(2)  $\|f(t, X) - f(t, Y)\| \leq \theta \|X - Y\|$

(3)  $\alpha \theta T < 1$

[H, p. 415, Thm 2.3]

$$(*)_4 \left\{ \begin{array}{l} \frac{dX}{dt} = F(t, X, \mu) \\ X(t+T) = X(t) \end{array} \right. \quad F(t+T, X, \mu) = F(t, X, \mu)$$

Suppose (1)  $(*)_4 |_{\mu=0}$  has a solution  $\gamma(t)$

(2) Let  $A(t) = D_X F(t, \gamma(t), 0) \Rightarrow \Phi(t)$

$(\Phi(T) - I)^{-1}$  exists

Then  $(*)_4$  has a solution for  $|\mu| \ll 1$

# Floquet Theory [M, Sec 2.8]

$$\frac{dx}{dt} = A(t)x \quad A(t+T) = A(t)$$

$$\Phi(t) = Q(t)e^{tB}, \quad Q(t+T) = Q(t)$$

$$\Phi(0) = I \Rightarrow Q(0) = I$$

$$\Rightarrow Q(nT) = I$$

$$\Phi(T) = e^{TB} := M \text{ (Monodromy matrix)}$$

$$\Phi(nT) = e^{nTB} = M^n$$

$$X(t) = Q(t)e^{tB} X(0)$$

$$X(nT) = Q(nT)e^{nTB} X(0)$$

$$= M^n X(0)$$

$$= \mu^n X(0)$$

choose  
 $M X(0) = \mu X(0)$

$$\|X(nT)\| = |\mu|^n \|X(0)\| \begin{cases} \rightarrow 0 & \text{if } |\mu| < 1 \\ \rightarrow +\infty & \text{if } |\mu| > 1 \end{cases}$$

Let  $X(t) = Q(t) Y(t)$ , or  $Y(t) = Q^{-1}(t) X(t)$

Then  $\dot{X}(t) = (\dot{Q}(t) Y(t) + Q(t) \dot{Y}(t))$

$$\frac{d}{dt} \Phi(t) = A(t) \Phi(t)$$

ie.  $(Q(t) e^{tB})' = A(t) Q(t) e^{tB}$

~~$$\dot{Q}(t) e^{tB} + Q(t) B e^{tB} = A(t) Q(t) e^{tB}$$~~

$$\underline{\dot{Q}(t) + Q(t) B = A(t) Q(t)}$$

$$\dot{X}(t) = (A(t) Q(t) - Q(t) B) Y(t) + Q(t) \dot{Y}(t)$$

$$= \underbrace{A(t) Q(t)}_X Y - Q(t) B Y + Q \dot{Y}$$

$$\Rightarrow \dot{X} - A(t) X = Q(t) (\dot{Y} - B Y)$$

Hence  $\dot{X} = A(t) X \iff \dot{Y} = B Y$

$\Phi(t)$   $e^{tB}$

$$\Phi(T) = M = e^{TB}$$

$$MX = \mu X$$

$$BY = \lambda Y$$

- Eigenvalues of  $B$  ( $\lambda_i$ ) are called characteristic exponents of  $B$
- Eigenvalues of  $M$  ( $\mu_i$ ) are called characteristic multipliers of  $M$
- $\mu_i = e^{T\lambda_i}$

$$\operatorname{Re}(\lambda_i) < 0 \iff |\mu_i| < 1$$

Autonomous System  $\frac{dX}{dt} = F(X)$  (\*)

Suppose (\*) has a  $T$ -periodic solution  $\gamma(t)$   
( $\gamma(t+T) = \gamma(t)$ )

Note:  $T$  is not known a priori.

Let  $A(t) = D_x F(\gamma(t))$ .

Then  $A(t+T) = A(t)$

Consider:  $\frac{d\gamma(t)}{dt} = F(\gamma(t))$

Then  $\frac{d}{dt} \left( \underbrace{\frac{d}{dt} \gamma(t)}_{X(t)} \right) = \frac{d}{dt} F(\gamma(t)) = \underbrace{D_x F(\gamma(t))}_{A(t)} \underbrace{\frac{d\gamma}{dt}}_{X(t)}$

Hence  $X(t) = \dot{\gamma}(t) \neq 0$  solves

$$\frac{dX}{dt} = A(t)X, \quad X(t+T) = X(t)$$

$\Rightarrow (\Phi(T) - I)^{-1}$  does not exist!

$$\text{and } X(0) = \Phi(T) X(0)$$

$$\text{i.e. } \dot{x}(0) = \Phi(T) \dot{x}(0)$$

i.e.  $\dot{x}(0)$  is an eigenvector of  $\Phi(T)$  w.r.t.  $\mu=1$

Physical Interpretation: time shift

$$\left\{ \begin{array}{l} \frac{d}{dt} x(t) = F(x(t)) \\ \frac{d}{dt} x(t+\delta) = F(x(t+\delta)) \end{array} \right.$$

$$\Rightarrow \frac{d}{dt} (x(t+\delta) - x(t)) = F(x(t+\delta)) - F(x(t))$$

$$\frac{d}{dt} \left( \frac{x(t+\delta) - x(t)}{\delta} \right) = \frac{F(x(t+\delta)) - F(x(t))}{\delta}$$

$\downarrow$   $\delta \rightarrow 0$

$$\frac{d}{dt} (\dot{x}(t)) = [D_x F(x(t))] \dot{x}(t)$$



[H, p. 416, Thm 2.4]

Consider  $\frac{dx}{dt} = F(x, \mu)$  (\*)

Suppose at  $\mu = 0$

(1) (\*) has a  $T$ -periodic solution  $\gamma_0(t)$

(2) Let  $A(t) = D_x F(\gamma_0(t)) \Rightarrow \Phi(t)$

$\mu = 1$  is a simple eigenvalue of  $\Phi(T)$

ie. multiplicity of  $\mu = 1$  is one

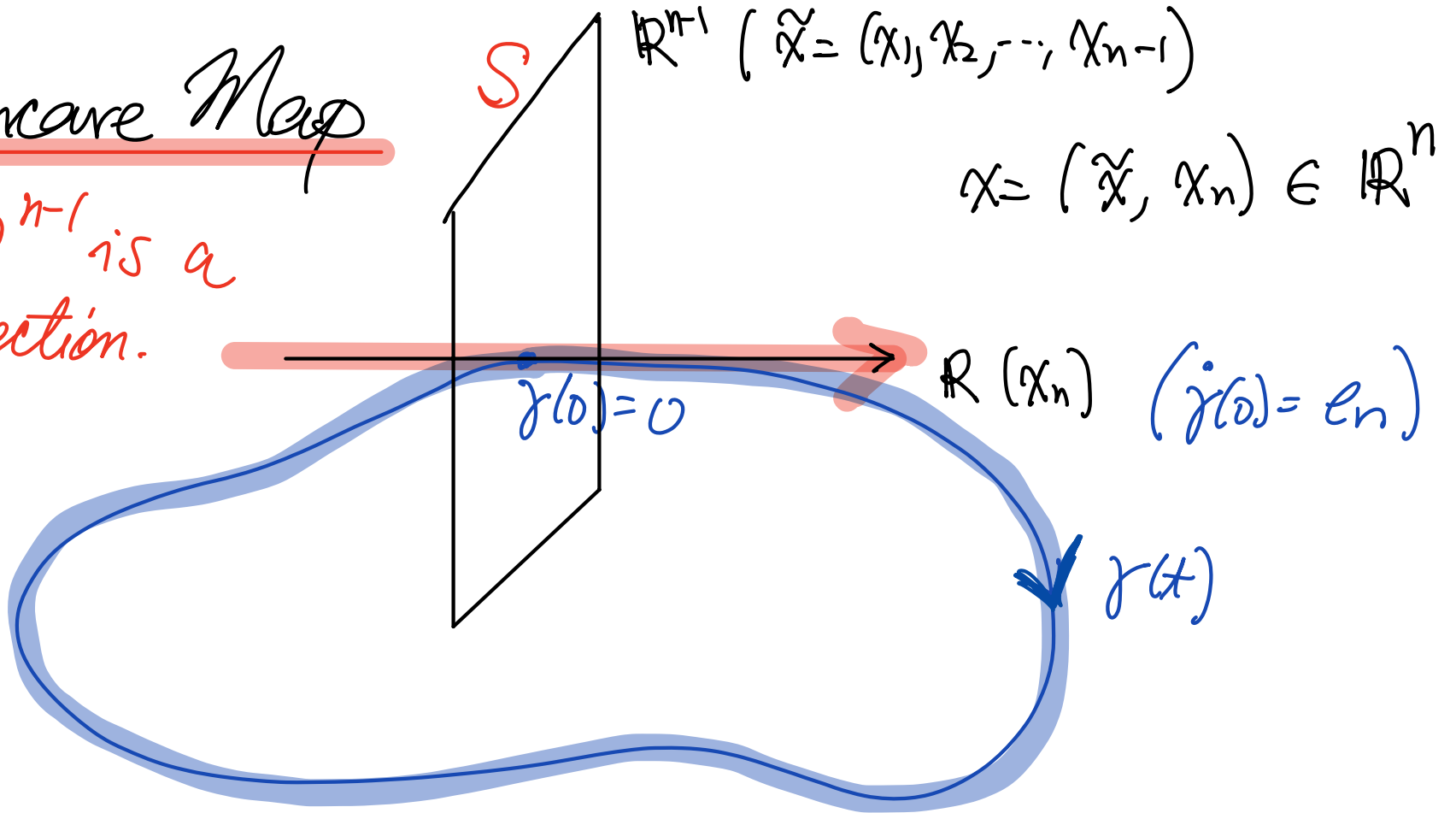
ie.  $\dim(\text{Null}(\Phi(T) - I)) = 1$

Then for  $|\mu| \ll 1$ , (\*) has a solution  $\gamma_\mu(\cdot)$  with period  $T(\mu)$

# Poincaré Map

$S \cong \mathbb{R}^{n-1}$  is a  
cross-section.

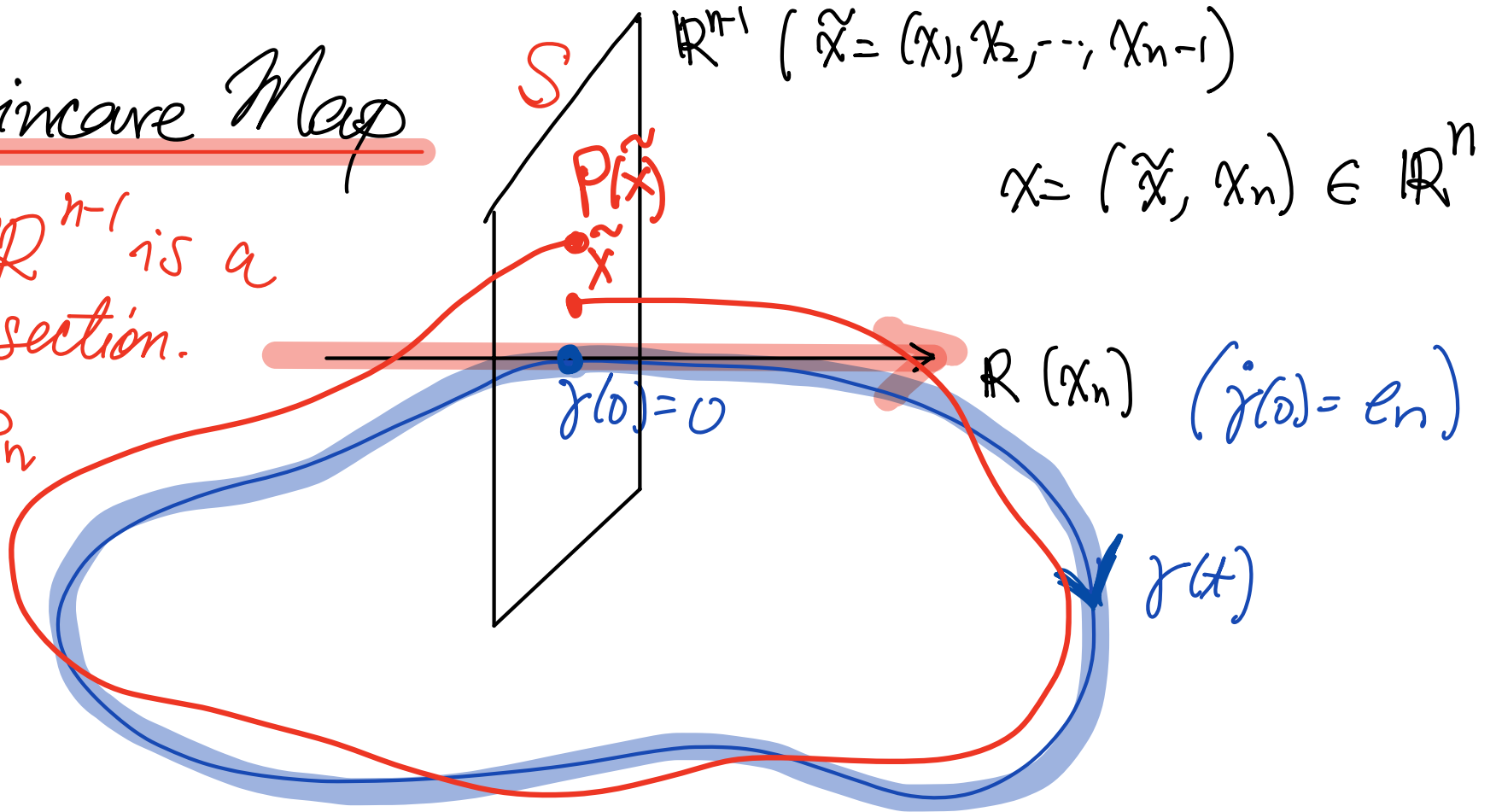
$\perp e_n$



# Poincaré Map

$S \cong \mathbb{R}^{n-1}$  is a cross-section.

$\perp e_n$



- For any  $x(0) = \tilde{x} \in S$ , close to  $\gamma(0)$ , there is a  $U(x)$  s.t.

$$\phi_{\tau(\tilde{x})}(\tilde{x}) \in S$$

- Poincaré Map:  $P(\tilde{x}) = \phi_{\tau(\tilde{x})}(\tilde{x})$

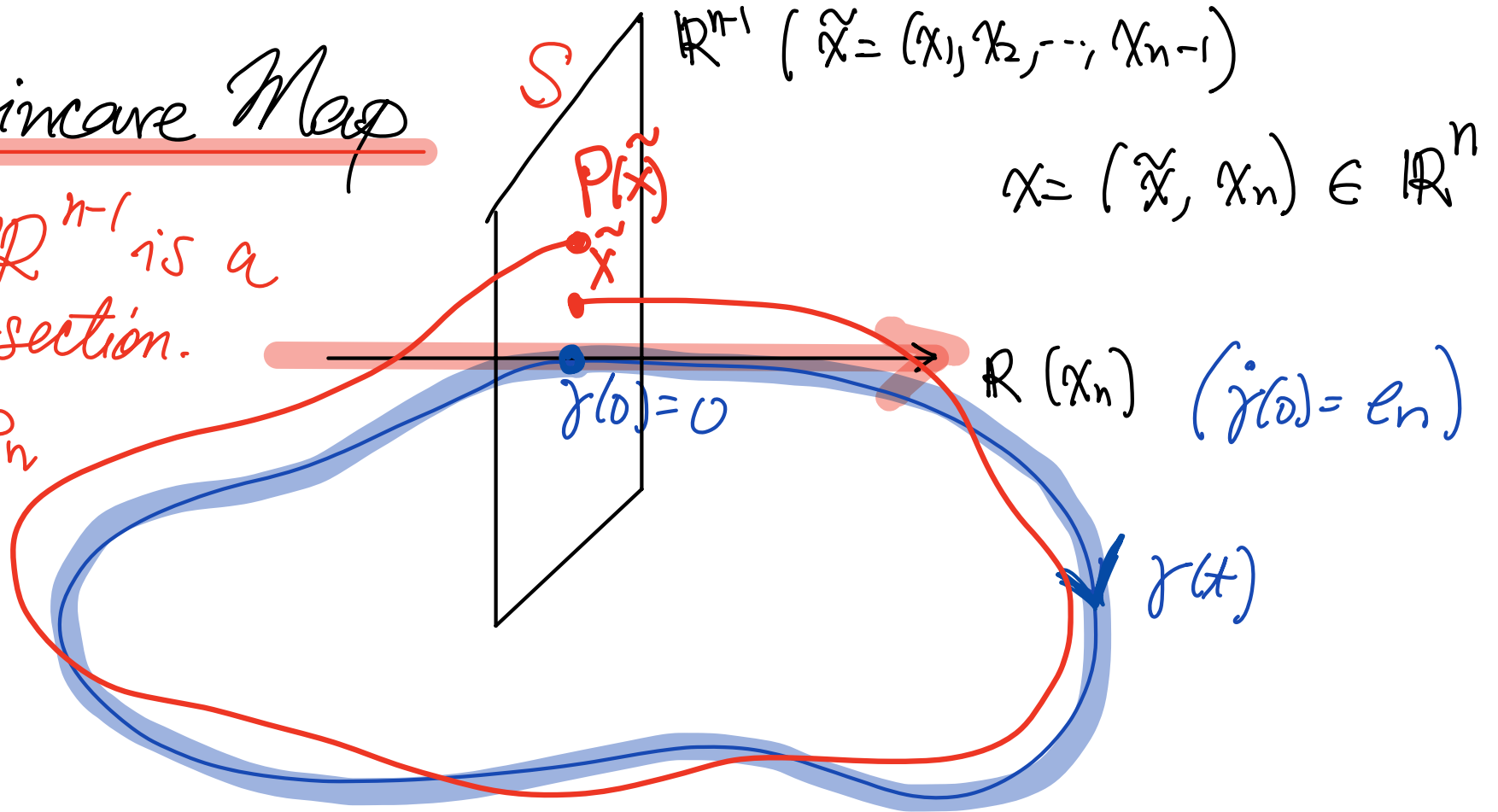
$$P: \mathbb{R}^{n-1} \rightarrow \mathbb{R}^{n-1}$$

$$(S \rightarrow S)$$

# Poincaré Map

$S \cong \mathbb{R}^{n-1}$  is a cross-section.

$\perp e_n$



- The solution  $x(t)$  starting at  $\tilde{x} \in S$  is a periodic orbit if and only if  $x$  is a fixed point of  $P$ , i.e.  $P(\tilde{x}) = \tilde{x}$  e.g.  $P(0) = 0$



# Pf (Outline)

$$\tilde{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_{n-1} \end{pmatrix} \in \mathbb{R}^{n-1} \quad x = \begin{pmatrix} x_1 \\ \vdots \\ x_{n-1} \\ x_n \end{pmatrix} = \begin{pmatrix} \tilde{x} \\ x_n \end{pmatrix} \in \mathbb{R}^n$$

$$e_n \parallel F(0) = \dot{\gamma}(0)$$

①

$$\frac{d}{dt} \varphi_t(x) = F(\varphi_t(x))$$

$$D_x \downarrow \frac{d}{dt} [D_x \varphi_t(x)] = [D_x F(\varphi_t(x))] [D_x \varphi_t(x)]$$

$$\frac{d}{dt} [D_x \varphi_t(0)] = [A(t)] [D_x \varphi_t(0)]$$

$$D_x \varphi_t(0) = \Phi(t) \quad [D_x \varphi_0(0) = I]$$

$$\Rightarrow \boxed{D_x \varphi_T(0) = \Phi(T) = M} \quad [M] = \begin{bmatrix} \tilde{M} & \vdots & 0 \\ \vdots & \ddots & \vdots \\ \vdots & \vdots & 0 \\ \text{xxxxxx} & & I \end{bmatrix}$$

Recall:  $M \dot{\gamma}(0) = \dot{\gamma}(0)$ , i.e.  $M e_n = e_n$

$$\textcircled{2} \text{ Let } Q: \mathbb{R}^n \rightarrow S \subseteq \mathbb{R}^n$$

$$x \rightarrow \varphi_{\tau(x)}(x) \in S$$

$$Q(x) = \varphi_{\tau(x)}(x)$$

$$D_x Q(x) = D_x \varphi_{\tau(x)}(x) + \frac{d\varphi_{\tau(x)}(x)}{dt} \nabla_x \tau(x)$$

$x=0 \downarrow$

$$D_x Q(0) = D_x \varphi_{\tau(0)}(0) + \frac{d\varphi_{\tau(0)}(0)}{dt} \nabla_x \tau(0)$$

$$(\tau(0) = T, \quad D_x \varphi_{\tau(0)} = M, \quad \frac{d\varphi_{\tau(0)}}{dt} = F(0) // e_n)$$

$$D_x Q(0) = M + F(0) \nabla_x \tau$$

$$= \begin{bmatrix} \tilde{M} & \vdots & 0 \\ \dots & \dots & \vdots \\ \dots & \dots & 0 \\ \dots & \dots & 1 \end{bmatrix} + \begin{bmatrix} 0 \\ \vdots \\ 0 \\ x \end{bmatrix} [\nabla_x \tau]$$

$$= \begin{bmatrix} \tilde{M} & \vdots & 0 \\ \dots & \dots & \vdots \\ \dots & \dots & 0 \\ \dots & \dots & x \end{bmatrix}$$

③

$$\mathcal{P}: S \longrightarrow S$$

$$\tilde{x} \longrightarrow \mathcal{P}(\tilde{x}) (\tilde{x})$$

$$\mathcal{P}(\tilde{x}) = \mathcal{Q}(\tilde{x})$$

$$\begin{bmatrix} \mathcal{P}(\tilde{x}) \\ 0 \end{bmatrix} = \mathcal{Q} \begin{pmatrix} \tilde{x} \\ 0 \end{pmatrix}$$

$$\begin{bmatrix} D_{\tilde{x}} \mathcal{P}(\tilde{x}) \\ 0 \end{bmatrix} = \begin{bmatrix} D_{\tilde{x}} \mathcal{Q}(\tilde{x}) \\ 0 \end{bmatrix} \begin{bmatrix} \tilde{x} \\ 0 \end{pmatrix}$$

$\tilde{x} = 0$

$$\begin{bmatrix} D_{\tilde{x}} \mathcal{P}(0) \\ 0 \end{bmatrix} = \begin{bmatrix} D_{\tilde{x}} \mathcal{Q}(0) \\ 0 \end{bmatrix} \begin{bmatrix} I \\ 0 \end{bmatrix}$$

$(n-1) \times (n-1)$  (pointing to  $D_{\tilde{x}} \mathcal{P}(0)$ )

$n \times n$  (pointing to  $D_{\tilde{x}} \mathcal{Q}(0)$ )

$(n-1) \times (n-1)$  (pointing to  $I$ )

$$\begin{bmatrix} \tilde{M} \\ \vdots \\ x \ x \ \dots \ x \end{bmatrix} = \underbrace{(M + F(0)) \nabla_{\tilde{x}} \mathcal{C}}_{\tilde{M}} \begin{bmatrix} I \\ 0 \end{bmatrix}$$

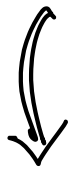
$$= \begin{bmatrix} \tilde{M} \\ \hline x \ x \ x \ \dots \ x \end{bmatrix}$$

$(n-1) \times (n-1)$  (pointing to  $\tilde{M}$ )

Hence  $D_{\tilde{x}} \mathcal{P}(0) = \tilde{M}$



$$\textcircled{4} \quad \begin{bmatrix} M \end{bmatrix}^{n \times n} = \begin{bmatrix} \tilde{M} & \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} \\ x \dots x & \boxed{1} \end{bmatrix} = \begin{bmatrix} D_x \tilde{P}(0) & \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} \\ x \dots x & \boxed{1} \end{bmatrix}$$



$$\text{spec}(M) = \text{spec}(D_x \tilde{P}(0)) \cup \{1\}$$

Proof of [H, p. 416, Thm 2.4] (Outline)

Need:  $\varphi_{\tilde{x}(\mu)}(\tilde{x}, \mu) - \tilde{x} = 0$

i.e.  $P(\tilde{x}, \mu) - \tilde{x} = 0$

At  $\mu = 0$ ,  $P(0, 0) - 0 = 0$

as  $\text{Spec } M = \underbrace{\text{Spec } D_x P(0)}_{1 \notin} \cup \{1\}$

Hence  $D_x \tilde{P}(0, 0) - I$  is invertible

By Implicit Function Thm,

$P(\tilde{x}, \mu) - \tilde{x} = 0$  has a solution  $\tilde{x}$  for  $|\mu| \ll 1$ .