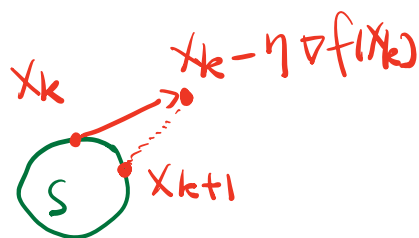


Constrained Minimization

$$\begin{cases} \min_x f(x) \\ \text{s.t. } x \in S \end{cases}$$



$$\Leftrightarrow \min_x [f(x) + g(x)] \quad g(x) = i_S(x)$$

Projected Gradient Method

$$\begin{aligned} x_{k+1} &= \underbrace{P_S}(x_k - \eta \nabla f(x_k)) \\ &= \underbrace{(I + \eta \partial g)^{-1}}(x_k - \eta \nabla f(x_k)) \end{aligned}$$

Forward-Backward Splitting:

Example

$$0 \in \partial f(x_*) + \partial g(x_*)$$

for solving $0 \in A(x) + B(x)$

where A & B are operators

$$x_{k+1} = x_k - \eta [A(x_k) + B(x_{k+1})]$$

$$(I + \eta B)(x_{k+1}) = x_k - \eta A(x_k)$$

$$x_{k+1} = (I + \eta B)^{-1}(I - \eta A)(x_k)$$

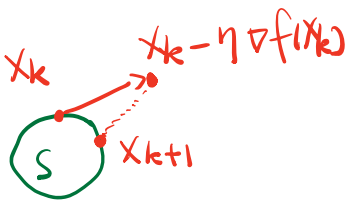
Example: ① Projected Gradient Method

$$\begin{cases} \min_x f(x) \\ \text{s.t. } x \in S \end{cases} \Leftrightarrow \min_x f(x) + g(x) \quad g(x) = i_S(x)$$

$$0 \in \nabla f(x) + \partial g(x)$$

$$A(x) = \nabla f(x), \quad B(x) = \partial g(x)$$

$$x_{k+1} = (I + \eta B)^{-1}(I - \eta A)(x_k)$$



$$= P_S (x_k - \eta \nabla f(x_k))$$

② Proximal Gradient for Composite Optimization

$$\min_x [f(x) + g(x)] \quad \begin{array}{l} f(x) \text{ is smooth} \\ g(x) \text{ is nonsmooth} \end{array}$$

$$A(x) = \nabla f(x), \quad B(x) = \partial g(x)$$

$$\begin{aligned} x_{k+1} &= (I + \eta B)^{-1} (I - \eta A)(x_k) \\ &= (I + \eta \partial g)^{-1} (x_k - \eta \nabla f(x_k)) \end{aligned}$$

③ Implicit - Explicit (IMEX) for ODE

$$\frac{d}{dt} u(t) = A(u) + B(u)$$

$$\frac{u^{n+1} - u^n}{\Delta t} = \underbrace{A(u^n)}_{\text{explicit}} + \underbrace{B(u^{n+1})}_{\text{implicit}}$$

Example: $u_t = u_x + u_{xx}$

④ LASSO: $\min_x \left(\frac{\lambda}{2} \|Ax - b\|^2 + \|x\|_1 \right)$

ISTA (Iterative Shrinkage - Thresholding Alg)

$$x_{k+1} = T_\gamma [x_k - \gamma \lambda A^T (Ax_k - b)]$$

$$T_{\gamma}(x)_i = \begin{cases} x_i - \gamma & , \text{ if } x_i > \gamma \\ x_i + \gamma & , \text{ if } x_i < -\gamma \\ 0 & , \text{ if } x_i \in [-\gamma, \gamma] \end{cases}$$

Shrinkage

$$f(x) = \frac{\lambda}{2} \|Ax - b\|^2 \quad \Bigg| \quad g(x) = \|x\|_1$$

$$\nabla f(x) = \lambda A^T(Ax - b)$$

$$A(x) = \nabla f(x), \quad B(x) = \partial g(x)$$

$$x_{k+1} = (I + \gamma B)^{-1} (I - \gamma A)(x_k)$$

$$= T_{\gamma} [x_k - \gamma \lambda A^T(Ax_k - b)]$$

Forward-Backward splitting

{ Projected Gradient
 Proximal Gradient
 IMEX
 ISTA

- Plan {
- More on convexity
 - Convergence of subgradient method

Example: $\min_{Ax=b} \|x\|_1 + \frac{\mu}{2} \|x\|^2$

$\Leftrightarrow \min_{x \in \mathbb{R}^n} \|x\|_1 + \frac{\mu}{2} \|x\|^2 + \mathbb{I}_{\{x: Ax=b\}}$

This function is a proper closed μ -strongly convex function

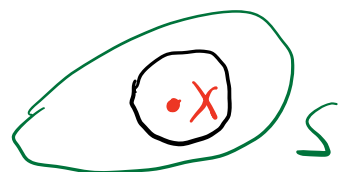
Read Section 3.3 in typed notes for details

3.3	Extended real-valued functions
3.3.1	Proper, convex, and closed functions
3.3.2	Existence and boundness of subderivatives
3.3.3	Strong convexity

A function f is

- extended if $f: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\pm\infty\}$
- proper if $\begin{cases} f: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\} \\ f(x) \in \mathbb{R} \text{ for at least one } x \end{cases}$
- closed if $\text{dom}(f) = \{x \in \mathbb{R}^n : f(x) \in \mathbb{R}\}$ is a closed set

an open set S means $\forall x \in S$, a ball centered at x is also in S



A closed set S means its complement is open

Ex: $\{x: Ax=b\}$ is closed.

Theorem 3.6. For an extended real-valued function $f: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\pm\infty\}$, the following are equivalent:

1. f is a closed function.
2. The level set $\{x: f(x) \leq a\}$ is a closed set for any $a \in \mathbb{R}$.
3. f is **lower semicontinuous**: for any x , for any sequence $x_n \rightarrow x$,

$$f(x) \leq \liminf_{n \rightarrow \infty} f(x_n).$$

• Convex

Theorem 3.7. A proper (extended) function $f: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is convex if and only if $\text{dom}(f)$ is convex and

$$f(\lambda x + (1-\lambda)y) \leq \lambda f(x) + (1-\lambda)f(y), \quad \forall x, y \in \text{dom}(f), \lambda \in (0, 1).$$

• Strongly convex

Definition 3.10. An extended function $f: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is μ -strongly convex if $\text{dom}(f)$ is convex and the following holds for any $\lambda \in (0, 1)$:

$$f(\lambda x + (1-\lambda)y) \leq \lambda f(x) + (1-\lambda)f(y) - \frac{\mu}{2} \lambda(1-\lambda) \|x-y\|^2, \quad \forall x, y \in \text{dom}(f).$$

Theorem 3.10. An extended function $f: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is μ -strongly convex if and only if $f(x) - \frac{\mu}{2} \|x\|^2$ is convex.

Example: $i_S(x) = \begin{cases} 0 & , x \in S \\ +\infty & , x \notin S \end{cases}$

1) ι_S is convex if S is convex

2) ι_S is closed $\Leftrightarrow S$ is closed

\Downarrow
 ι_S is l.s.c. (Lower Semicontinuous)

3) $\iota_S(x) + \frac{\mu}{2} \|x\|^2$ is strongly convex
if S is a convex set

4) $\|x\|_1 + \frac{\mu}{2} \|x\|^2 + \iota_{\{x: Ax=b\}}$ is strongly convex

Even though $\partial f(x)$ denotes a set, for simplicity, we often abuse the notation by using it to denote any element in this set. Lemma 1.1 can be extended as (see [3], Theorem 5.24] for the proof):

Lemma 3.1. For a proper function $f(x) : \mathbb{R}^n \rightarrow (-\infty, +\infty]$, assume $\text{dom}(f)$ is convex, then the following are equivalent:

1. $f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y), \quad \forall x, y \in \text{dom}(f), \lambda \in (0, 1).$
2. $f(x) \geq f(y) + \langle \partial f(y), x - y \rangle, \quad \forall x, y \in \text{dom}(f).$
3. $\langle \partial f(y) - \partial f(x), y - x \rangle \geq 0, \quad \forall x, y \in \text{dom}(f).$

For a proper closed and convex function, the following are equivalent:

1. f is μ -strongly convexity
2. $f(x) \geq f(y) + \langle \partial f(y), x - y \rangle + \frac{\mu}{2} \|x - y\|^2, \quad \forall x, y \in \text{dom}(f).$
3. $\langle \partial f(y) - \partial f(x), y - x \rangle \geq \mu \|x - y\|^2, \quad \forall x, y \in \text{dom}(f).$

An example is that $\iota_S + \frac{\mu}{2} \|x\|^2$ is μ -strongly convex for a convex set S .

Subdifferentials

Theorem 3.9. Consider a proper extended function $f : \mathbb{R}^n \rightarrow (-\infty, +\infty]$. Assume its domain $\text{dom}(f)$ is a convex set, then

1. Existence of subderivatives at any $\mathbf{x} \in \text{dom}(f)$ implies convexity of $f(\mathbf{x})$.
2. Convexity of f implies that subderivative exists at any \mathbf{x} in the interior of $\text{dom}(f)$, denoted as $\text{int}(\text{dom}(f))$ and $\partial f(\mathbf{x})$ is bounded:

$$\forall \mathbf{v} \in \partial f(\mathbf{x}), \|\mathbf{v}\| \leq C \quad \text{for some } C.$$

3. If $U \subset \text{int}(\text{dom}(f))$ is a nonempty compact set (bounded and closed set in \mathbb{R}^n), then convexity of f implies $\bigcup_{\mathbf{x} \in U} \partial f(\mathbf{x})$ is bounded (all subderivatives in U have a uniform bound).
4. For boundary points of $\text{dom}(f)$ of a convex function, subderivatives exist at the relative interior of $\text{dom}(f)$ but they can be unbounded.

Optimality

Theorem 3.12. For a proper convex function $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$, \mathbf{x}_* minimizes $f(\mathbf{x})$ if and only if $\mathbf{0} \in \partial f(\mathbf{x}_*)$.

Proof. $f(\mathbf{x}) \geq f(\mathbf{x}_*) = f(\mathbf{x}_*) + \langle \mathbf{0}, \mathbf{x} - \mathbf{x}_* \rangle \Leftrightarrow \mathbf{0} \in \partial(\mathbf{x}_*), \quad \forall \mathbf{x} \in \text{dom}(f). \quad \square$

Theorem 3.13. For a proper closed function $f : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$, if it is μ -strongly convex, then it has a unique minimizer \mathbf{x}_* .

Example: $f(x) = \iota_S(x) + \frac{\mu}{2} \|x\|^2$ is strongly convex

If S is a closed set, then $f(x)$ has a unique x^* .

Example: $f(x) = \iota_S(x) + \frac{1}{2} x^2$ is strongly convex

but not closed for $S = (0, 1)$, thus **no minimizer**

$\|x\|_1 + \frac{\mu}{2} \|x\|^2 + \iota_{\{x: Ax=b\}}$ is strongly convex **and closed**

For the indicator function ι_S , its subdifferential is given as

$$\partial \iota_S(\mathbf{x}) = N_S(\mathbf{x}), \quad \mathbf{x} \in S,$$

\Downarrow
C.S.C.

where N_S is the normal cone of S :

Definition 3.11. For a set $S \subset \mathbb{R}^n$ and $\mathbf{x} \in S$, the normal cone of S at \mathbf{x} is

$$N_S(\mathbf{x}) = \{\mathbf{y} : \langle \mathbf{y}, \mathbf{z} - \mathbf{x} \rangle \leq 0, \forall \mathbf{z} \in S\},$$

and $N_S(\mathbf{x})$ is an empty set for $\mathbf{x} \notin S$.

$$S = \{x \in \mathbb{R}^n : Ax = b\} \quad A \in \mathbb{R}^{m \times n}$$

$$N_S = \{A^T y : y \in \mathbb{R}^m\} \quad \text{because}$$

$$\begin{aligned} \text{given } x \in S, \forall z \in S \quad & \langle A^T y, z - x \rangle \\ &= \langle y, A(z - x) \rangle \\ &= \langle y, b - b \rangle = 0 \end{aligned}$$

3.5.3 Convergence of subgradient method

Theorem 3.14. *For the subgradient method*

$$\mathbf{x}_{k+1} = \mathbf{x}_k - \eta_k \frac{\mathbf{v}_k}{\|\mathbf{v}_k\|}, \quad \text{some } \mathbf{v}_k \in \partial f(\mathbf{x}_k,)$$

assume $\|\mathbf{v}_k\| \leq M, \forall k$. Define

$$\bar{\mathbf{x}}_k = \operatorname{argmin}_{1 \leq i \leq k} f(\mathbf{x}_i).$$

For a proper convex function $f(\mathbf{x})$ with a global minimizer \mathbf{x}_* , the following holds:

1. If $\sum_{k=0}^{\infty} \eta_k = +\infty$ and $\sum_{k=0}^{\infty} \eta_k^2 < +\infty$, then $f(\bar{\mathbf{x}}_k) - f(\mathbf{x}_*) \rightarrow 0$ as $k \rightarrow \infty$.
2. If using a step size $\eta_k \equiv \frac{C}{\sqrt{n+1}}$ for $k = 0, 1, \dots, n$, then

$$f(\bar{\mathbf{x}}_k) - f(\mathbf{x}_*) = \mathcal{O}\left(\frac{1}{\sqrt{k}}\right).$$

3. With the Polyak's step size $\eta_k = \frac{f(\mathbf{x}_k) - f(\mathbf{x}_*)}{\|\mathbf{v}_k\|}$: $f(\bar{\mathbf{x}}_k) - f(\mathbf{x}_*) = \mathcal{O}\left(\frac{1}{\sqrt{k}}\right)$.

If further assuming $f(\mathbf{x})$ is strongly convex with $\mu > 0$, then with $\eta_k = \frac{2}{\mu(k+1)} \|\mathbf{v}_k\|$,

4. $f(\bar{\mathbf{x}}_k) - f(\mathbf{x}_*) = \mathcal{O}\left(\frac{1}{k}\right)$ and $\|\mathbf{x}_k - \mathbf{x}_*\| = \mathcal{O}\left(\frac{1}{\sqrt{k}}\right)$.

Now assume strong convexity with $\mu > 0$

$$\|X_{k+1} - X_*\|^2 = \left\| X_k - X_* - \eta_k \frac{g_k}{\|g_k\|} \right\|^2$$

$$= \|X_k - X_*\|^2 - 2\eta_k \frac{1}{\|g_k\|} \langle X_k - X_*, g_k \rangle + \eta_k^2$$

$$f(X) \geq f(X_k) + \langle g_k, X - X_k \rangle + \frac{\mu}{2} \|X - X_k\|^2$$

$$f(X_*) \geq f(X_k) + \langle g_k, X_* - X_k \rangle + \frac{\mu}{2} \|X_* - X_k\|^2$$

$$\Rightarrow -\langle g_k, X_k - X_* \rangle \leq f(X_*) - f(X_k) - \frac{\mu}{2} \|X_* - X_k\|^2$$

$$\leq \left(1 - 2\eta_k \frac{1}{\|g_k\|} \frac{\mu}{2}\right) \|X_k - X_*\|^2$$

$$- 2\eta_k \frac{1}{\|g_k\|} [f(X_k) - f(X_*)] + \eta_k^2$$

$$\Rightarrow f(X_k) - f(X_*) \leq \left(\frac{\|g_k\|}{2\eta_k} - \frac{\mu}{2}\right) \|X_k - X_*\|^2 - \frac{\|g_k\|}{2\eta_k} \|X_{k+1} - X_*\|^2 + \frac{\|g_k\|}{2} \eta_k$$

$$\eta_k = \frac{2}{\mu(k+1)} \cdot \|g_k\|$$

$$= \frac{\mu(k-1)}{4} \|X_k - X_*\|^2 - \frac{\mu(k+1)}{4} \|X_{k+1} - X_*\|^2$$

$$+ \frac{1}{\mu(k+1)} \|g_k\|^2$$

$$k[f(X_k) - f(X_*)] \leq k \frac{\mu(k-1)}{4} \|X_k - X_*\|^2 - \frac{k\mu(k+1)}{4} \|X_{k+1} - X_*\|^2 + k \frac{1}{\mu(k+1)} \|g_k\|^2$$

Sum it for $k=0, 1, \dots, n$

$$\sum_{k=0}^n k [f(x_k) - f(x_*)] \leq -\frac{\mu}{L} n(n+1) \|x_{n+1} - x_*\|^2 + \frac{M^2}{\mu} \sum_{k=0}^n \frac{k}{k+1}$$

$$\leq \frac{M^2 n}{\mu}$$

$$\Rightarrow \left(\underbrace{\sum_{k=0}^n k}_{\frac{n(n+1)}{2}} \right) [f(\bar{x}_n) - f(x_*)] \leq \frac{M^2 n}{\mu}$$

$$\Rightarrow f(\bar{x}_n) - f(x_*) \leq \frac{2M^2}{\mu(n+1)}$$

$$\frac{\mu}{2} \|\bar{x}_k - x_*\|^2 \leq \underbrace{f(\bar{x}_k) - f(x_*)}_{\rightarrow \text{why?}}$$

$$\Rightarrow \|\bar{x}_k - x_*\| \leq \frac{2M}{\mu \sqrt{k+1}}$$