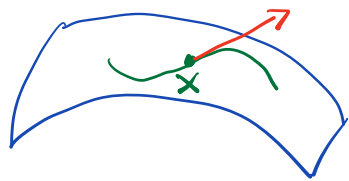


# Setup

- $E$  is a linear space with inner product  $\langle \cdot, \cdot \rangle$
- $M \subseteq E$  is a submanifold in  $E$
- The general definition of tangent space of a manifold  $M \subseteq E$

$$T_x M = \{ C'(0) \mid C: \underbrace{(-\epsilon, \epsilon)}_{\text{some interval in } \mathbb{R}} \rightarrow M \text{ is smooth \& } C(0) = x \}$$



$C(t)$  is a curve on  $M$

$C'(t)$  is tangent to the curve

Theorem If  $M \subseteq E$  is describable by  $h(x) = 0$ , then

$$\text{Ker}[Dh(x)] = T_x M$$

Any element in  $T_x M$  is a tangent vector at  $x$

- Tangent Bundle  $TM = \{ \underbrace{V_x}_{\downarrow} \in T_x M : \forall x \in M \} = \bigcup_{x \in M} T_x M$   
subscript  $x$  denotes it's a tangent vector at  $x$   
For convenience, we sometimes ignore the subscript.

- A vector field on  $M$  is a map

$$V: M \rightarrow TM$$

s.t.  $V(x) \in T_x M$  for any  $x \in M$

- A metric is a choice of inner product  $\langle \cdot, \cdot \rangle_x$

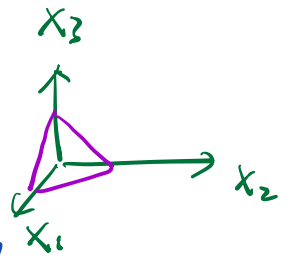
for  $T_x M$  at each  $x \in M$ .

- A metric is Riemannian if  $\langle \cdot, \cdot \rangle_x$  is smooth w.r.t.  $x$   
i.e.  $\langle V(x), W(x) \rangle_x$  is smooth for smooth vector fields  $V, W$ .
- Let  $g_x(\cdot, \cdot) = \langle \cdot, \cdot \rangle_x$  be a Riemannian metric  
 $(M, g)$  is a Riemannian manifold.

Example:

$$M = \Delta_+^{n-1} = \left\{ x \in \mathbb{R}^n : x_i > 0, \sum_{i=1}^n x_i = 1 \right\}$$

relative interior of the simplex or probability manifold



$M$  is an embedded manifold of  $\mathbb{R}^n$

$$T_x M = \left\{ v \in \mathbb{R}^n : \sum_{i=1}^n v_i = 0 \right\}$$

The Fisher-Rao metric  $(M, g)$

$$g_x(u, v) = \sum_{i=1}^n \frac{u_i v_i}{x_i}$$

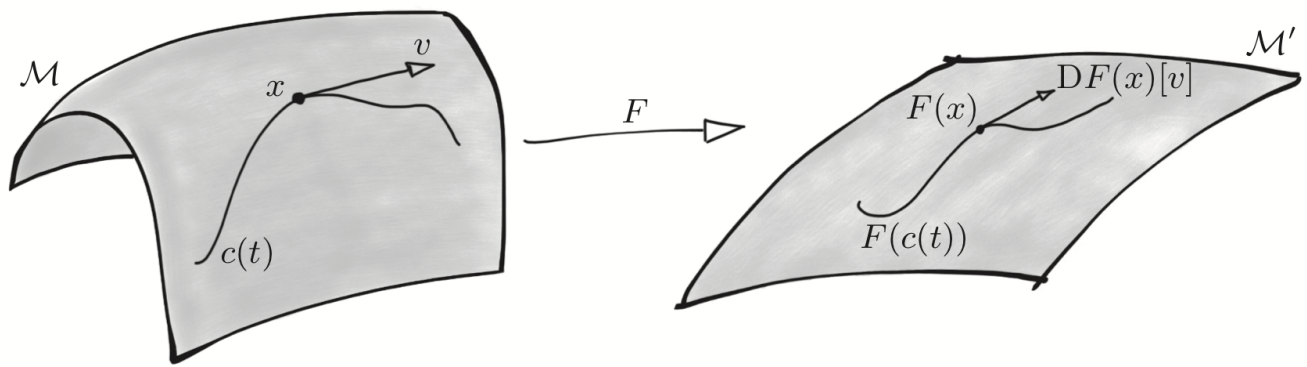
- $F: M \rightarrow M'$  is smooth map where  $M, M'$  are manifolds

The differential is the linear map

$$DF(x): T_x M \rightarrow T_{F(x)} M' \quad \text{defined by}$$

$$DF(x)[v] = \left. \frac{d}{dt} F(c(t)) \right|_{t=0} = (F \circ c)'(0)$$

where  $c(t)$  is a smooth curve on  $M$   $\begin{cases} c(0) = x \\ c'(0) = v \end{cases}$



Example  $f: M \rightarrow \mathbb{R}$

$$Df(x): T_x M \rightarrow \mathbb{R}$$

$$v \mapsto Df(x)[v]$$

$$= \left. \frac{d}{dt} f(c(t)) \right|_{t=0} \quad \leftarrow \text{not easy to compute}$$

- Let  $M \subset \mathcal{E}$  and  $M' \subset \mathcal{E}'$  be embedded submanifolds in  $\mathcal{E}$  and  $\mathcal{E}'$

Then a smooth map  $F: M \rightarrow M'$  has a smooth

$$\text{extension } \bar{F}: \mathcal{E} \rightarrow \mathcal{E}'$$

Notice that  $F(c(t)) = \bar{F}(c(t))$  because  $c(t) \in M$ .

$$\left. \frac{d}{dt} \bar{F}(c(t)) \right|_{t=0} = D\bar{F}(c(0))[c'(0)] = D\bar{F}(x)[v]$$

||

$$\left. \frac{d}{dt} F(c(t)) \right|_{t=0} = DF(x)[v]$$

$$\Rightarrow DF(x)[v] = D\bar{F}(x)[v]$$

Example  $S_t(n, p) = \{ X \in \mathbb{R}^{n \times p}, X^T X = I_p \} \quad p \leq n$

$$f: \text{St}(n, p) \longrightarrow \mathbb{R} \quad \langle U, V \rangle = \text{tr}(U^T V)$$

$$\boxed{A^T = A}$$

$$X \longmapsto \text{tr}(X^T A X) = \langle X, A X \rangle$$

can be extended to  $\langle X, Y \rangle = \sum_{i=1}^n \sum_{j=1}^p X_{ij} Y_{ij}$

$$\bar{f}: \mathbb{R}^{n \times p} \longrightarrow \mathbb{R}$$

$$X \longmapsto \text{tr}(X^T A X) = \langle X, A X \rangle$$

$$\begin{aligned} \forall V \in \mathbb{R}^{n \times p}, \quad D\bar{f}(X)[V] &= \lim_{t \rightarrow 0} \frac{\bar{f}(X+tV) - \bar{f}(X)}{t} \\ &= \lim_{t \rightarrow 0} \frac{\langle X+tV, A(X+tV) \rangle - \langle X, AX \rangle}{t} \\ &= \lim_{t \rightarrow 0} \frac{t \langle V, AX \rangle + t \langle X, AV \rangle + t^2 \langle V, AV \rangle}{t} \\ &= \langle 2AX, V \rangle \end{aligned}$$

$$\forall X \in \text{St}(n, p)$$

$$\forall V \in T_x \text{St}(n, p) = \{ V \in \mathbb{R}^{n \times p} : X^T V + V^T X = 0 \} \subseteq \mathbb{R}^{n \times p}$$

$$Df(X)[V] = D\bar{f}(X)[V] = \langle 2AX, V \rangle$$

### Riemannian Gradient

For a smooth  $f: M \rightarrow \mathbb{R}$  on a Riemannian manifold  $(M, g)$

the Riemannian gradient of  $f$  is the vector field  $\text{grad } f$

defined by  $g_x(\text{grad } f(x), v_x) = Df(x)[v_x], \quad \forall x \in M$   
 $\forall v_x \in T_x M$

Remark:  $\text{grad} f(x)$  is a tangent vector in  $T_x M$

Example:  $f: \text{St}(n, p) \rightarrow \mathbb{R}$

$$x \mapsto \text{tr}(x^T A x) = \langle x, Ax \rangle$$

$$\bar{f}: \mathbb{R}^{n \times p} \rightarrow \mathbb{R}$$

$$x \mapsto \text{tr}(x^T A x) = \langle x, Ax \rangle$$

$$Df(x)[V] = D\bar{f}(x)[V] = \langle 2Ax, V \rangle$$

① Euclidean Gradient of  $\bar{f}$  in  $\mathbb{R}^{n \times p}$  is defined by

$$\langle \nabla \bar{f}(x), v \rangle = D\bar{f}(x)[v], \quad \forall v \in \mathbb{R}^{n \times p}$$

$$\Rightarrow \nabla \bar{f}(x) = 2Ax$$

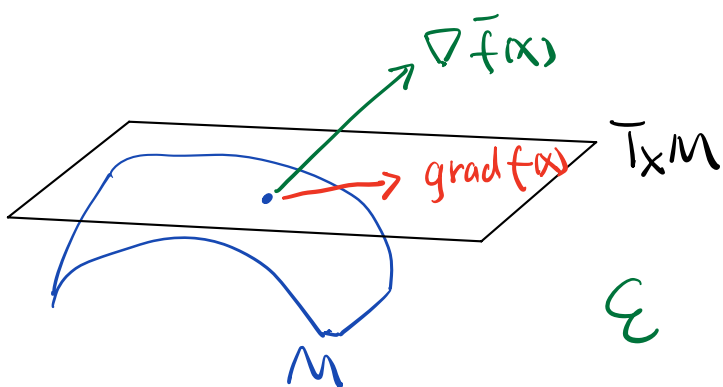
② Riemannian Gradient of  $f$  on  $(M, g)$  is defined by

$$g_x(\text{grad} f(x), v) = Df(x)[v], \quad \forall v \in T_x M \subseteq \mathbb{R}^{n \times p}$$

Suppose we choose  $g_x(u, v) = \langle u, v \rangle$ , then

$$\langle \text{grad} f(x), v \rangle = \langle \nabla \bar{f}(x), v \rangle, \quad \forall v \in T_x M$$

$$\Rightarrow \langle \text{grad} f(x) - \nabla \bar{f}(x), v \rangle = 0, \quad \forall v \in T_x M$$



$\Rightarrow \text{grad} f(x)$  is Euclidean Projection of  $\nabla \bar{f}(x)$  onto  $T_x M$

$$\textcircled{2} \quad T_x \text{St}(n, p) = \{ V \in \mathbb{R}^{n \times p} : X^T V + V^T X = 0 \} = S_1$$

$X_\perp \in \mathbb{R}^{n \times (n-p)}$  is a matrix s.t.

Col Space of  $X_\perp$  is orthogonal complement to

Col Space of  $X \in \mathbb{R}^{n \times p}$

$$T_x \text{St}(n, p) = \{ X \Omega + X_\perp K : \Omega^T = -\Omega \in \mathbb{R}^{p \times p}, K \in \mathbb{R}^{(n-p) \times p} \} = S_2$$

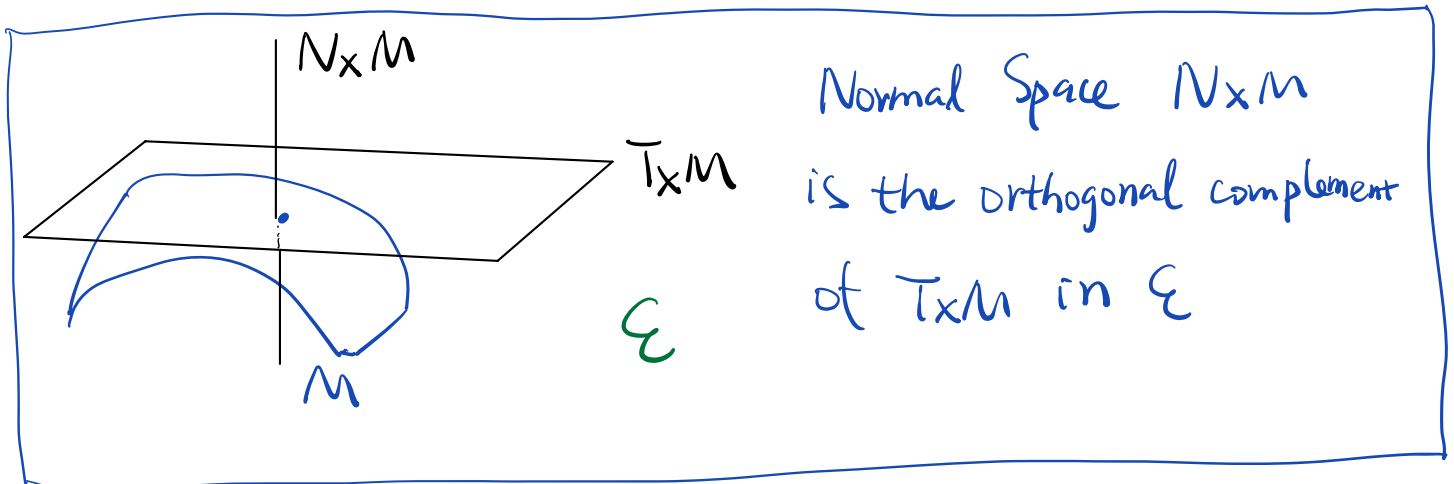
Pick  $X_\perp$  s.t.  $X_\perp$  has orthonormal columns

The matrix  $[X \ X_\perp] \in \mathbb{R}^{n \times n}$  has orthonormal columns

This can be proven by counting dimensions.

$$\begin{aligned} 1) \quad S_2 \subseteq S_1 \text{ because } & (X \Omega + X_\perp K)^T X + X^T (X \Omega + X_\perp K) \\ & = \Omega^T X^T X + K^T X_\perp^T X + X^T X \Omega + X^T X_\perp K = 0 \end{aligned}$$

$$2) \quad S_2 \text{ has the same dim as } S_1 \Rightarrow S_2 = S_1$$



$$\textcircled{3} \quad N_x \text{St}(n, p) = \{ X S : S^T = S, S \in \mathbb{R}^{p \times p} \}$$

$$\langle X S, X \Omega + X_\perp K \rangle = \text{tr}(S X^T (X \Omega + X_\perp K))$$

$$= \text{tr}(S \Omega)$$

$$= \langle S, \Omega \rangle = 0$$

$$\text{because } S^T = S, \Omega^T = -\Omega$$

④ Projection of onto  $N_x \text{St}(n, p)$  is  $P_x^\perp$

Projection of onto  $T_x \text{St}(n, p)$  is  $P_x$

$$\text{Then } P_x(Y) = Y - P_x^\perp(Y) = (I - P_x^\perp)Y$$

$$P_x^\perp(Y) = X \text{sym}(X^T Y) = X \frac{X^T Y + Y^T X}{2}$$

$$\text{sym}(B) = \frac{B^T + B}{2}$$

$$P_x(Y) = (I - X X^T)Y + \text{skew}(X^T Y)$$

$$\text{skew}(B) = \frac{1}{2}(B - B^T)$$

$$\Rightarrow \text{grad} f(x) = P_x[\nabla \bar{f}(x)]$$

$$= (I - X X^T) \nabla \bar{f}(x) + \text{skew}(X^T \nabla \bar{f}(x))$$

Special Example :

$$\textcircled{1} P=1, \text{St}(n, p) = S^{n-1}$$

$$P_x(Y) = (I - X X^T)Y + \text{skew}(X^T Y) = (I - X X^T)Y$$

$$\text{grad} f(x) = (I - X X^T) \nabla \bar{f}(x)$$

$$\textcircled{2} P=n, \text{St}(n, p) = O(n) = \{X \in \mathbb{R}^{n \times n} : X^T X = I\}$$

$$f(x) = \frac{1}{2} \text{tr}(X^T A X), \quad A^T = A$$

$$\nabla \bar{f}(x) = A X \Rightarrow \text{skew}(X^T \nabla \bar{f}(x)) = \text{skew}(X^T A X) = 0$$

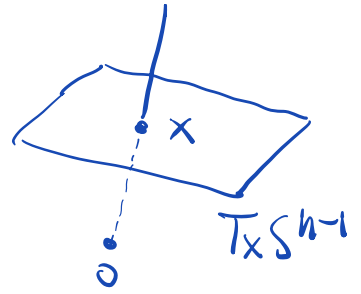
$$\Rightarrow \text{grad} f(x) = (I - X X^T) A X$$

Example ① Regard  $S^{n-1}$  as a Riemannian submanifold of  $\mathbb{R}^n$

$$\left. \begin{aligned} f(x) &= \frac{1}{2} x^T A x \text{ defined on } S^{n-1} \\ \bar{f}(x) &= \frac{1}{2} x^T A x \text{ defined on } \mathbb{R}^n \end{aligned} \right\} A^T = A$$

$$\nabla \bar{f}(x) = Ax$$

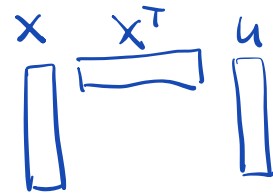
Projection of  $u$  onto  $T_x S^{n-1}$



$$P_{T_x S^{n-1}}(u) = x - \frac{\langle x, u \rangle}{\langle x, x \rangle} x, \quad x \in S^{n-1}$$

$$= u - \langle x, u \rangle x$$

$$= (I - x x^T) u$$



$$\text{grad } f(x) = P_{T_x S^{n-1}}(\nabla \bar{f}(x))$$

$$= (I - x x^T) Ax = Ax - (x^T A x) x$$

Remark:  $\text{grad } f(x) = 0 \Leftrightarrow Ax = \underbrace{(x^T A x)}_{\text{scalar}} x$

$$\nabla \bar{f}(x) = Ax$$

So critical point on  $S^{n-1} \Leftrightarrow$  eigenvectors

$$\textcircled{2} M = \Delta_+^{n-1} = \left\{ x \in \mathbb{R}^n : x_i > 0, \sum_{i=1}^n x_i = 1 \right\}$$

relative interior of the simplex or probability manifold

$M$  is an embedded manifold of  $\mathbb{R}^n$

$$T_x M = \left\{ v \in \mathbb{R}^n : \sum_{i=1}^n v_i = 0 \right\}$$



The Fisher-Rao metric

$$g_x(u, v) = \sum_{i=1}^n \frac{u_i v_i}{x_i}$$

$$f: M \rightarrow \mathbb{R}$$

$$\bar{f}: \mathbb{R}^n \rightarrow \mathbb{R} \quad \nabla \bar{f}(x)$$

$$\begin{aligned} g_x(\text{grad} f(x), v) &= Df(x)[v] = D\bar{f}(x)[v] \\ &= \langle \nabla \bar{f}(x), v \rangle \\ &= v^T \cdot \nabla \bar{f}(x) \end{aligned}$$

To find an expression

Let  $\text{grad} f(x) = u \in T_x M$

$\frac{u}{x}$  denotes the vector  $\left[ \frac{u_1}{x_1} \dots \frac{u_n}{x_n} \right]^T$

$$v^T \cdot \frac{\text{grad} f(x)}{x} = v^T \cdot \nabla \bar{f}(x) \quad \forall v \in T_x M$$

Given  $w \in \mathbb{R}^n$ , solve  $u \in T_x M$  satisfying

$$v^T u = v^T w, \quad \forall v \in T_x M$$

$$\Rightarrow v^T (u - w) = 0$$

$$\Rightarrow P_{T_x M}(u - w) = 0$$

$$\Rightarrow u - w \parallel \begin{bmatrix} | \\ | \\ | \end{bmatrix}$$

$$\Rightarrow u = w + \lambda \mathbf{1}, \quad \lambda \in \mathbb{R}$$

$$\Rightarrow \frac{\text{grad} f(x)}{x} = \nabla \bar{f}(x) + \lambda \mathbf{1}$$

$$\Rightarrow \text{grad } f(x) = \underline{x} \circ \nabla \bar{f}(x) + \lambda x$$

entry wise product

$$\text{grad } f(x) \in T_x M \Rightarrow \sum_{i=1}^n (x_i [\nabla \bar{f}(x)]_i + \lambda x_i) = 0$$

$$\Rightarrow \lambda = - \sum_{i=1}^n x_i [\nabla \bar{f}(x)]_i$$

$$\Rightarrow \text{grad } f(x) = x \circ \nabla \bar{f}(x) - \langle x, \nabla \bar{f}(x) \rangle x$$

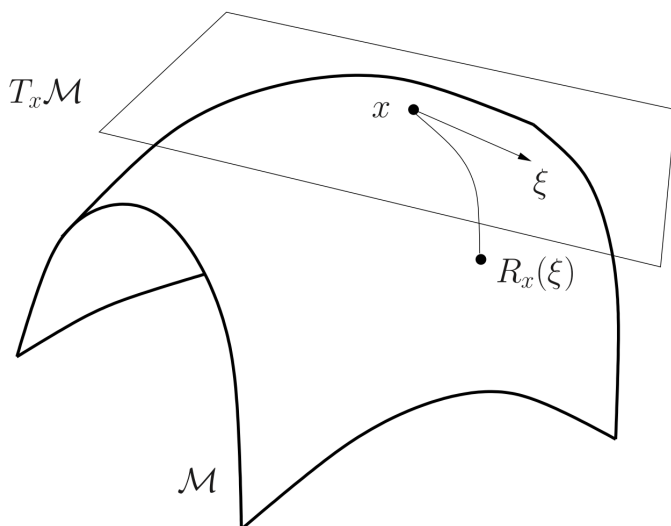
A Retraction on  $M$  is a smooth map

$$R: TM \rightarrow M$$

$$v_x \mapsto R_x(v)$$

Such that each curve  $c(t) = R_x(tv)$  satisfies

$$\begin{cases} c(0) = x \\ c'(0) = v \end{cases}$$



$$R: TM \rightarrow M$$

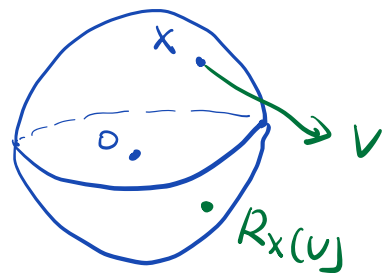
$$v_x \mapsto R_x(v_x)$$

$$c(t) = R_x(t\xi)$$

$$c(0) = x$$

$$c'(0) = \xi$$

## Examples of Retraction on $S^{n-1}$



$$\begin{aligned} \textcircled{1} \quad R_x(v) &= \frac{x+v}{\|x+v\|} = \frac{x+v}{\sqrt{\|x+v\|^2}} \\ &= \frac{x+v}{\sqrt{1+\|v\|^2}} \end{aligned}$$

$$\textcircled{2} \quad R_x(v) = \cos(\|v\|)x + \frac{\sin(\|v\|)}{\|v\|}v$$

$c(t) = R_x(tv)$  is the great circle passing  $x$  with  $c'(0) = v$ .

---

## Riemannian Gradient descent on $(M, g)$

$$\min_{x \in M} f(x)$$

$$x_{k+1} = R_{x_k}[-\eta \text{grad} f(x)]$$

Example:

$M = \text{sphere } S^{n-1}$ ,  $g$  is  $\langle, \rangle$ ,  $f(x) = \frac{1}{2}x^T A x$

$$R_x[v] = \frac{x+v}{\|x+v\|}$$

$$\begin{cases} \tilde{x}_{k+1} = x_k - \eta (I - x_k^T x_k) A x_k \\ x_{k+1} = \frac{\tilde{x}_{k+1}}{\|\tilde{x}_{k+1}\|} \end{cases}$$