

# Examples and Summary of Riemannian Optimization

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Example:  $M = \mathbb{R}^n$  is a manifold

$$\forall x \in M, T_x M = \mathbb{R}^n$$

$$M \subseteq E = \mathbb{R}^n$$

Given  $f: M \rightarrow \mathbb{R}$ , we still use  $\bar{f}: \mathbb{R}^n \rightarrow \mathbb{R}$

Let  $g$  be a metric and  $g_x(\cdot, \cdot)$  may not be  $\langle \cdot, \cdot \rangle$

- Then the Riemannian Gradient of  $f$  on  $(M, g)$  is

$$\forall v \in T_x M = \mathbb{R}^n, g_x(\text{grad } f(x), v) = Df(x)[v] = D\bar{f}(x)[v] = \langle \nabla \bar{f}(x), v \rangle$$

- Retraction  $R_x$  can be taken as

$$R_x(v) = x + v$$

① If  $g_x(\cdot, \cdot)$  is  $\langle \cdot, \cdot \rangle$ , then  $\text{grad } f(x) \in T_x M = \mathbb{R}^n$

satisfies  $\langle \text{grad } f(x), v \rangle = \langle \nabla \bar{f}(x), v \rangle, \forall v \in T_x M = \mathbb{R}^n$

$\Rightarrow \text{grad } f(x) = \nabla \bar{f}(x)$  which is  $\nabla f(x)$

Riemannian Gradient Descent is

$$x_{k+1} = R_{x_k}(-\eta \text{grad } f(x_k))$$

$$= x_k - \eta \nabla f(x_k)$$

② If  $g_x(u, v) = v^T G u = \langle G u, v \rangle$

$$G \in \mathbb{R}^{n \times n}, \quad G^T = G, \quad G > 0$$

$$\text{then } g_x(\text{grad } f(x), v) = \langle \nabla \bar{f}(x), v \rangle$$

$$\Rightarrow \langle G \text{grad } f(x), v \rangle = \langle \nabla \bar{f}(x), v \rangle \quad \forall v \in \mathbb{R}^n$$

$$\Rightarrow \langle G \text{grad } f(x) - \nabla \bar{f}(x), v \rangle = 0$$

$$\Rightarrow \text{grad } f(x) = G^{-1} \nabla \bar{f}(x) = G^{-1} \nabla f(x)$$

Riemannian Gradient Descent is

$$x_{k+1} = R_{x_k}(-\eta \text{grad } f(x_k))$$

$$= x_k - \eta \underbrace{G^{-1} \nabla f(x_k)}_{\text{preconditioned gradient}}$$

$-G^{-1} \nabla f(x)$  is a descent direction because

$$G > 0 \Rightarrow G^{-1} > 0 \Rightarrow \langle \nabla f(x), G^{-1} \nabla f(x) \rangle = \nabla f(x)^T G^{-1} \nabla f(x) > 0$$

$$\textcircled{3} \text{ If } g_x(u, v) = v^T G(x)u = \langle G(x)u, v \rangle$$

with  $G(x) = \nabla^2 f(x)$ , then

Riemannian Gradient Descent is **Newton's Method**

$$x_{k+1} = R_{x_k}(-\eta \text{grad } f(x_k))$$

$$= x_k - \eta [\nabla^2 f(x_k)]^{-1} \nabla f(x_k)$$

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Previously, we considered an embedded submanifold  $M$  in  $E$

- $M \subset \mathcal{E}$
- $f: M \rightarrow \mathbb{R}$  is extended to  $\bar{f}: \mathcal{E} \rightarrow \mathbb{R}$
- $T_x M$  is a subspace in  $\mathcal{E}$
- $g_x(\text{grad } f(x), v) = \langle \nabla \bar{f}(x), v \rangle$

We extend it to an embedded submanifold  $M$  in  $(\bar{M}, \bar{g})$

where  $\bar{M}$  is a manifold with a metric  $\bar{g}$ ,

•  $M \subset \bar{M}$  example:  $\bar{M}$  is sphere,  $M$  is a circle on  $\bar{M}$

•  $f: M \rightarrow \mathbb{R}$  is extended to  $\bar{f}: \bar{M} \rightarrow \mathbb{R}$

•  $T_x M$  is a subspace of  $T_x \bar{M}$ ,  $\forall x \in M \subset \bar{M}$

• We can define the metric of  $M$  as the one induced by  $\bar{g}$ : if  $v \in T_x M$ , then  $v \in T_x \bar{M}$

$$g_x(v, w) = \bar{g}_x(v, w), \quad \forall v, w \in T_x M$$

$(M, g)$  is called an embedded Riemannian submanifold of  $(\bar{M}, \bar{g})$

•  $\bar{f}: \bar{M} \rightarrow \mathbb{R}$  has a Riemannian Gradient  $\text{grad } \bar{f}$

•  $f: M \rightarrow \mathbb{R}$ , its Riemannian Gradient can be computed

by

$$g_x(\underbrace{\text{grad } f(x)}_{\in T_x M}, v) = \bar{g}_x(\underbrace{\text{grad } \bar{f}(x)}_{T_x \bar{M}}, v), \quad \forall v \in T_x M$$

Example:  $x \in \mathbb{R}^n$ ,  $A \in \mathbb{R}^{n \times n}$ ,  $A^T = A$ ,  $A > 0$

$$f(x) = \frac{1}{2} x^T A x + \frac{\beta}{4} \sum_{i=1}^n x_i^4 \quad , \quad \beta \geq 0 \text{ is a constant}$$

Want to solve  $\min_{x \in S^{n-1}} f(x)$

$$\frac{\partial}{\partial x} f(x) = Ax + \beta x^3 \quad \begin{pmatrix} x_1^3 \\ \vdots \\ x_n^3 \end{pmatrix} \quad \frac{\partial^2}{\partial x^2} f(x) = A + 3\beta \begin{pmatrix} x_1^2 & & \\ & \ddots & \\ & & x_n^2 \end{pmatrix}$$

- $\bar{M} = \mathbb{R}^n$ ,  $\bar{f}: \bar{M} \rightarrow \mathbb{R}$   
 $x \mapsto \frac{1}{2} x^T A x + \frac{\beta}{4} \sum_{i=1}^n x_i^4$

$T_x \bar{M} = \mathbb{R}^n$ , pick a metric

$$\bar{g}_x(u, v) = v^T G(x) u$$

$$g_x(\text{grad } \bar{f}(x), v) = \left\langle \frac{\partial}{\partial x} f(x), v \right\rangle, \quad \forall v \in T_x \bar{M} = \mathbb{R}^n$$

$$\Rightarrow G(x) \text{grad } \bar{f}(x) = \frac{\partial}{\partial x} f(x)$$

$$\Rightarrow \text{grad } \bar{f}(x) = G(x)^{-1} [Ax + \beta x^3]$$

- $M = S^{n-1}$ , consider the embedded Riemannian submanifold  $(M, g)$  in  $(\bar{M}, \bar{g})$

$$f: M \rightarrow \mathbb{R}$$

$$x \mapsto \frac{1}{2} x^T A x + \frac{\beta}{4} \sum_{i=1}^n x_i^4$$

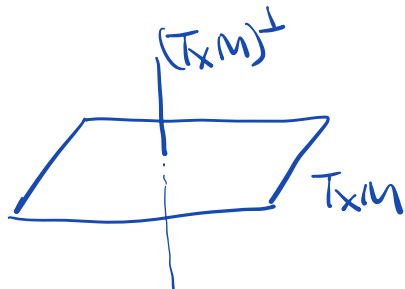
$$g_x(\text{grad } f(x), v) = \bar{g}_x(\text{grad } \bar{f}(x), v), \quad \forall v \in T_x M$$

To find  $\text{grad } f(x) \in T_x M \subseteq T_x \bar{M} = \mathbb{R}^n$ ,

we regard  $\text{grad } f(x), v$  as elements in  $T_x \bar{M}$

$$\Rightarrow \bar{g}_x(\text{grad } f(x), v) = \bar{g}_x(\text{grad } \bar{f}(x), v), \quad \forall v \in T_x M$$

$$\Rightarrow \bar{g}_x(\text{grad } f(x) - \text{grad } \bar{f}(x), v) = 0, \quad \forall v \in T_x M$$



$$T_x \bar{M} = T_x M \oplus (T_x M)^\perp$$

$$\Rightarrow \text{grad } f(x) - \text{grad } \bar{f}(x) \perp T_x M \text{ in } T_x \bar{M}$$

$$\Rightarrow \text{grad } f(x) \text{ is "Proj" of } \text{grad } \bar{f}(x) \text{ on } T_x M$$

$\rightarrow$  in the sense of  $\perp$  using  $\bar{g}_x$

$$M = S^{n-1}$$

$$\textcircled{1} T_x M = \{ v \in \mathbb{R}^n : x^T v = 0 \} \rightarrow \text{independent of } g$$

$$w \in (T_x M)^\perp, \quad \forall v \in T_x M, \quad \bar{g}_x(w, v) = 0$$

$\downarrow$   
depends on  $\bar{g}$

$$v^T G(x) w = 0$$

$$\Rightarrow G(x) w \parallel x$$

$$\Rightarrow (T_x M)^\perp = \{ a G(x)^{-1} x, a \in \mathbb{R} \}$$

$\textcircled{2}$  "Proj" of  $\text{grad } \bar{f}(x)$  onto  $(T_x M)^\perp$  is

$$\frac{g_x(\text{grad } \bar{f}(x), G(x)^{-1} x)}{g_x(G(x)^{-1} x, G(x)^{-1} x)} G(x)^{-1} x$$



③ "Proj" of  $\text{grad } \bar{f}(x)$  onto  $T_x M$  is

$$\begin{aligned} \Rightarrow \text{grad } f(x) &= \text{grad } \bar{f}(x) - \frac{g_x(\text{grad } \bar{f}(x), G(x)^{-1}x)}{g_x(G(x)^{-1}x, G(x)^{-1}x)} G(x)^{-1}x \\ &= G(x)^{-1} [Ax + \beta x^3] - \frac{\langle \text{grad } \bar{f}(x), G(x) G(x)^{-1}x \rangle}{\langle G(x)^{-1}x, G(x) G(x)^{-1}x \rangle} G(x)^{-1}x \\ &= G(x)^{-1} [Ax + \beta x^3] - \frac{\langle \text{grad } \bar{f}(x), x \rangle}{\langle G(x)^{-1}x, x \rangle} G(x)^{-1}x \end{aligned}$$

Choices of  $G(x)$ :

①  $G(x) = I$  meaning  $S^{n-1}$  with  $g = \langle \cdot, \cdot \rangle$

②  $G(x) = A$

$$\text{grad } \bar{f}(x) = x + \beta A^{-1}x^3$$

③  $G(x) = A + \beta \begin{pmatrix} x_1^2 & & \\ & x_2^2 & \\ & & \ddots \\ & & & x_n^2 \end{pmatrix}$

$$\text{grad } \bar{f}(x) = x \Rightarrow \text{grad } f(x) = x - \frac{\langle x, x \rangle}{\langle G(x)^{-1}x, x \rangle} G(x)^{-1}x$$

A numerical example:  $A = -\Delta + V$

Remark: an alternative way to compute  $\text{grad } f$

$$g_x(\text{grad } f(x) - \text{grad } \bar{f}(x), v) = 0, \forall v \in T_x M$$

$$v^T G(x) \text{grad } f(x) = v^T G(x) \text{grad } \bar{f}(x), \forall v \in T_x M$$

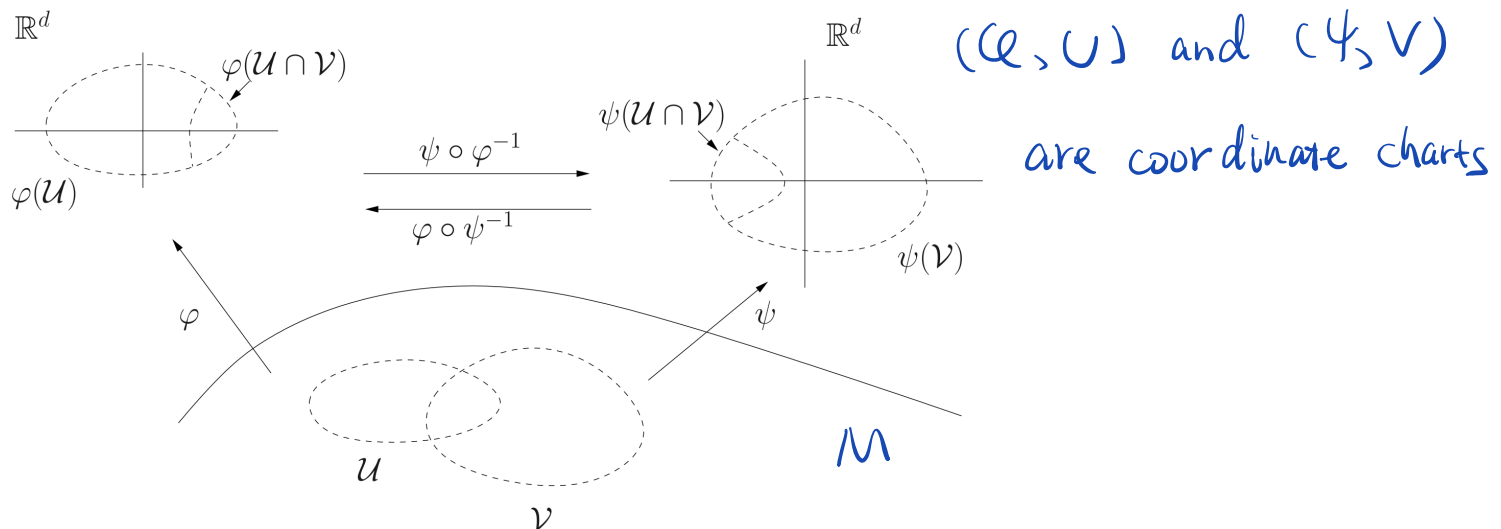
$$\Rightarrow v^T [G(x) \text{grad } f(x) - G(x) \text{grad } \bar{f}(x)] = 0$$

$\Rightarrow G(x) \text{grad } f(x)$  is Proj of  $G(x) \text{grad } \bar{f}(x)$  onto  $T_x M$

$$\Rightarrow G(x) \text{ grad } f(x) = P_{T_x M} [ G(x) \text{ grad } \bar{f}(x) ]$$

## Summary of some concepts for Riemannian Opt

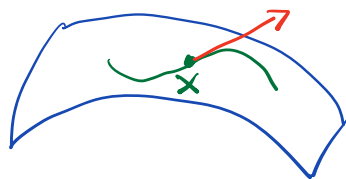
- Manifold > charts > smooth manifold



- Tangent Space  $T_x M$

The general definition of tangent space of a manifold  $M \subseteq \mathbb{E}$

$$T_x M = \{ c'(0) \mid c: (-\epsilon, \epsilon) \rightarrow M \text{ is smooth \& } c(0) = x \}$$



$c(t)$  is a curve on  $M$

$c'(t)$  is tangent to the curve

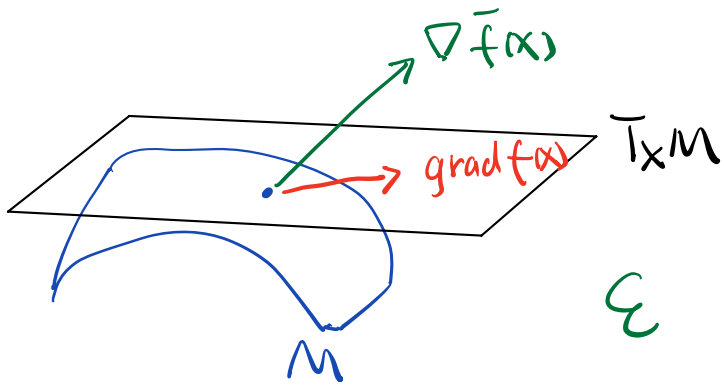
If  $M \subseteq \mathbb{E}$ ,  $T_x M$  is a subspace in  $\mathbb{E}$ .

- Riemannian Metric  $g$

at  $x \in M$ ,  $g_x(u, v)$  is an inner product for  $T_x M$

$T_x M$  stays the same for different choices of  $g$

- Riemannian Gradient  $\text{grad} f(x) \in T_x M$



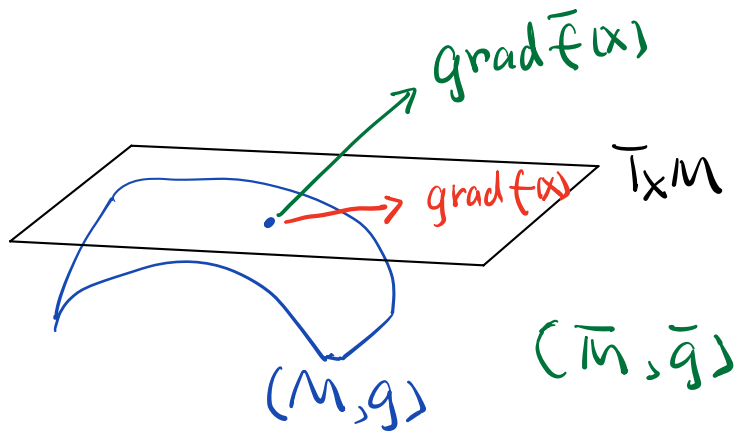
$$M \subset \mathcal{E}$$

$$f: M \rightarrow \mathbb{R} \text{ is extended to}$$

$$\bar{f}: \mathcal{E} \rightarrow \mathbb{R}$$

$$g_x(\text{grad} f(x), v) = \langle \nabla \bar{f}, v \rangle$$

$$\forall v \in T_x M$$



$$M \subset \mathcal{E}$$

$$f: M \rightarrow \mathbb{R} \text{ is extended to}$$

$$\bar{f}: \bar{M} \rightarrow \mathbb{R}$$

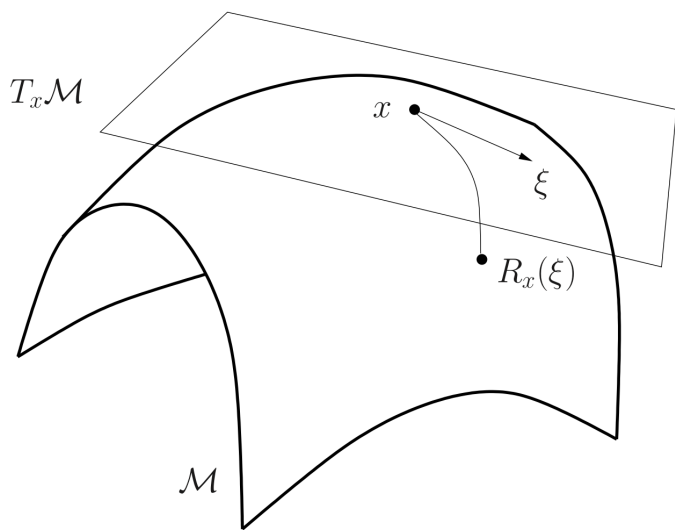
$$g_x(\text{grad} f(x), v) = \bar{g}_x(\text{grad} \bar{f}(x), v)$$

$$\forall v \in T_x M$$

	Manifold ( $S^{n-1}$ )	Embedding space ( $\mathbb{R}^n$ )
cost	$f(x) = x^T A x, x \in S^{n-1}$	$\bar{f}(x) = x^T A x, x \in \mathbb{R}^n$
metric	induced metric	$\bar{g}(\xi, \zeta) = \xi^T \zeta$
tangent space	$\xi \in \mathbb{R}^n : x^T \xi = 0$	$\mathbb{R}^n$
normal space	$\xi \in \mathbb{R}^n : \xi = \alpha x$	$\emptyset$
projection onto tangent space	$P_x \xi = (I - x x^T) \xi$	identity
gradient	$\text{grad} f(x) = P_x \text{grad} \bar{f}(x)$	$\text{grad} \bar{f}(x) = 2Ax$
retraction	$R_x(\xi) = \text{qf}(x + \xi)$	$R_x(\xi) = x + \xi$

- Retraction at  $x$  is a map  $R_x: T_x M \rightarrow M$



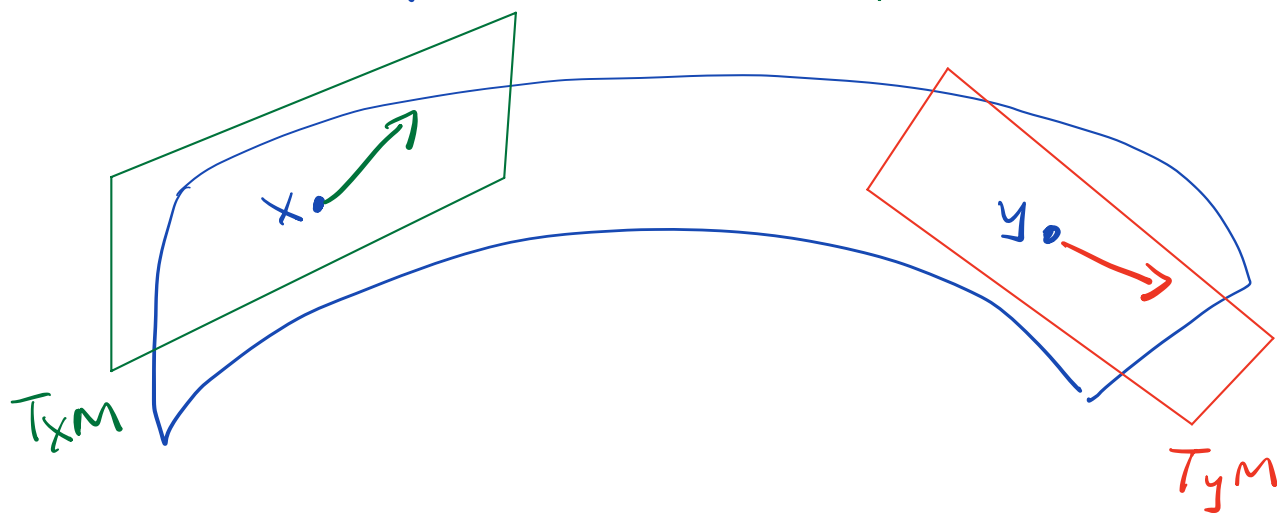


- Riemannian Gradient Descent on  $(M, g)$

$$x_{k+1} = R_{x_k}(-\eta \operatorname{grad} f(x_k))$$

Concepts that we do not cover but are important:

- Vector transports (how to define  $\nabla f(x_k) + \nabla f(x_{k-1})$ )



- Riemannian Hessian

$$\operatorname{Hess} f(x) : T_x M \rightarrow T_x M$$

$$v \mapsto \nabla_v \operatorname{grad} f(x)$$

$\nabla_v$  is called connection  
↳ covariant derivative.

- Quotient Manifold

Grassmann Manifold

$\text{Grass}(p, n) = \{ \text{subspaces of dim } p \text{ in } \mathbb{R}^n \}$